

# Advanced Technology Needs for a Global Change Science Program

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## **Foreword**

Many scientists, engineers, and concerned citizens, both within the United States and abroad, are increasing our awareness of the real and potential damage that mankind is inflicting on Earth. Governments are responding with plans and resources, first, to understand the mechanisms at play and, then, to develop policies to protect the delicate balance of forces that shape our environment. The National Aeronautics and Space Administration (NASA) is one of the United States agencies involved in this effort, and one role NASA must perform well is the identification and development of advanced sensing methods, components, and operational spacecraft to support the scientific investigators. Therefore, NASA's Office of Aeronautics and Space Technology (OAST),<sup>1</sup> working with the field centers, initiated a concentrated effort to identify and prioritize the elements that should make up a technology program focused on global change science requirements.

Langley Research Center (LaRC) senior management selected a team of representatives from its science and technology development areas to assist in identifying and describing those LaRC technologies that would be beneficial to a global change science program. This team, known as the Global Change Technology Initiative (GCTI) Task Force, was responsible for generating the technology material listed in section 3. The Task Force members (listed below) and other LaRC personnel participated in a series of three workshops sponsored by NASA Headquarters (HQ) for synthesizing inputs from all the NASA centers. Having completed this initial effort in support of NASA OAST, the Task Force will continue, as appropriate, to provide HQ and LaRC senior management with information about those technologies listed in this report or others that are newly identified as being critical to the GCTI.

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<sup>1</sup> Reorganized in 1990 to be OAET (Office of Aeronautics and Exploration Technologies).



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## 1. Introduction

Since the launch of the first Television and Infrared Observation Satellite (TIROS) in April 1960, the United States has made tremendous strides in the application of satellite remote sensing to the study of Earth's land, oceans, and atmosphere. The growth in remote sensing technology and operations has benefited not only the science community, but also the business sector and society as a whole by providing both an increased understanding of the Earth system and an associated improvement in predictive capability (ref. 1). The two principal federal agencies involved in the development and use of remote sensing are the National Oceanic and Atmospheric Administration (NOAA) and the National Aeronautics and Space Administration (NASA), though many other agencies such as the National Science Foundation, Department of the Interior, Department of Agriculture, Department of Defense, Department of Transportation, and Environmental Protection Agency have developed diverse uses for the data that are produced.

Although we now view predictions of weather and severe storms as commonplace, this was not possible before observational technologies, analysis techniques, and operational spacecraft were available. For the larger task of developing even simple predictive models of the total Earth system, many additional measurement variables must be collected at greatly increased temporal and spatial frequencies so that the complex interactions among the hydrological cycle, the biogeochemical cycle, and the climate can be understood. A growing international concern regarding trends such as ozone depletion, global warming, and acid rain is generating an intense renewed emphasis on Earth science and on the associated support technologies that are needed to enable a comprehensive global change program such as Mission to Planet Earth (ref. 2). Many NASA responsibilities will bear upon the success of a global change science program; foremost among these activities will be research and development of advanced space technologies and systems. Adequate measurement techniques and operational systems have not been developed to collect the vast amounts of data needed to understand the complex interactions among the surface, oceanic, atmospheric, and biological elements of the planet. Major advances in observation techniques and sensors, data and information handling, and spacecraft and operations technologies must be achieved before the multidisciplinary science measurements (discussed in section 2) can be made and analyzed over sufficiently long time periods.

To this end, NASA is defining a technology program intended specifically *to enable and enhance a global change science program*. This Global Change Technology Initiative (GCTI), proposed for a funding start in the 1991 fiscal year, will develop, to the extent that the budget allows, the top-priority technology candidates in three major areas: observation technologies, data and information technologies, and spacecraft and operations technologies. NASA Headquarters (HQ) has involved the field centers in an intensive study to identify and prioritize the technology candidates. This paper presents the elements of the Langley Research Center (LaRC) technology development work (discussed in section 3) that are believed to be very important to the global change science program. Not all these elements are likely to be funded by the GCTI. Technical evaluations by NASA HQ and budget issues will determine which of the LaRC elements will be selected along with elements proposed by other centers for inclusion in the eventual GCTI proposal. The final content of the GCTI program will be documented by NASA HQ.

This paper will present briefly the science requirements for a global change program. These global change science issues and related measurements must, of course, be addressed by some sensing strategy, and the candidate sensors proposed for each measurement will be summarized. Technologies that are now or will be proposed as part of the LaRC technology development program which enable or enhance these measurements will be described. Detailed descriptions will be given for each proposed technology, including the scope, objective, and approach for that candidate; a technology readiness timeline; a list of deliverables; and an estimate of funding required to meet the deliverable milestones. This report, documenting the products of the LaRC GCTI Task Force, will be provided to NASA HQ to support their efforts to develop a GCTI proposal for presentation to the NASA Administrator.

## 2. Global Change Science Requirements

Global-scale changes now occurring in the chemical composition of the atmosphere threaten serious alterations of the Earth's climate. Some of the more significant environmental issues recently identified include

The greenhouse effect and possible global warming: Such changes in the Earth's atmospheric composition may result from factors such as increased fossil fuel burning.

Ozone depletion: Dramatic seasonal ozone losses have been detected in both the Arctic

and the Antarctic polar regions. There exists a strong potential link between man-made pollutants and these ozone losses.

Tropical deforestation: The destruction of the tropical rain forests is a significant contributor to the atmospheric carbon dioxide increases.

To understand these changes, identify their sources, and predict their consequences requires extensive global-scale observations and associated advanced new instrumentation and spacecraft. Numerous studies completed in recent years by U.S. and international agencies have listed the primary measurements that must be made if global change processes are to be understood, modeled, and predicted. One of the most comprehensive studies was conducted by the Earth System Sciences Committee of the NASA Advisory Council between 1983 and 1987. Its report, known as the Bretherton report (ref. 3), has provided an informative and often-quoted source of the issues and the possible courses of action to understand global change. The report has served as the basis for the global change science requirements described in this section, and the summary tables from the report have been augmented by additional measurement needs proposed by scientists interviewed at several NASA field centers.

### Measurement Requirements

The NASA field centers including the Jet Propulsion Laboratory (JPL), the Goddard Space Flight Center (GSFC), and the Langley Research Center (LaRC) surveyed their Earth scientists to identify any measurements beyond those listed in the Bretherton report that were deemed important. The study at JPL was conducted by Bob Gershman, at GSFC by Scott Shipley of ST Systems Corp. (STX) (GSFC internal report entitled "Science Traceability for the Global Change Technology Initiative"), and at LaRC by Tom Swissler. The scientists surveyed at LaRC are primarily atmospheric scientists, and consequently their additions to table I relate primarily to trace gases that play a major role in global change through the climate and biogeochemical areas.

Table I is a list of the measurement requirements combined from these sources and an internal report produced by the Geostationary Platform Earth Sciences Steering Committee (GPESSC) at Marshall Space Flight Center. (Internal report entitled "Geostationary Science Steering Group Committee Report: Understanding Dynamic Earth System Processes—The Need for Geostationary Observations.") The table describes the measurement objective, the target of the observation, the temporal

and spatial resolutions, the percentage accuracy required, clarification comments, the potential measurement methods, and the various sources that identified the measurement as being important. The LaRC, JPL, and GSFC items included are additions to the Bretherton list. The GPESSC items include all measurements mentioned in their report whether or not identified already by the Bretherton report. A total of 108 measurements are identified in this list, and they are divided into the following categories: solar irradiance; tropospheric constituents (trace gases, ozone, aerosols, clouds); stratospheric constituents (trace gases, ozone, aerosols); atmospheric response variables (temperature, pressure, wind, precipitation, radiation components); surface characteristics (soil moisture, vegetation index, biomass burning, volcanoes, albedo); ocean variables (temperature, sea ice extent, sea level, CO<sub>2</sub> content); and plate motions. No doubt others could be added by scientists in disciplines not well represented within this table. The fact that several instruments (and resolutions) may be proposed for many of these measurements indicates that different applications can be made of a single science measurement.

### Measurement History

Table II presents the history and current status of these measurements. The first two columns of table II are repeated from table I, but additional information has been presented. As is shown in this table, of 108 observables listed, 86 are currently being measured (at some resolution). Of these, only 50 have been measured by space-based systems, implying that the remainder have unacceptable temporal or spatial coverage. In fact, most of these measurements require enhanced spatial and temporal resolution in order to achieve the global coverage needed to infer knowledge of climate and global change. Thus, the need for greatly increased operational systems is obvious. Whether these unaccomplished measurements should be taken from in situ, aircraft, or spacecraft platforms will be determined by the coverage and repeat frequency requirements. For example, global climatology studies require long-term, accurate measurements on a global scale, while regional process studies require short-term measurements with high temporal resolution.

For 22 of these measurements, no routine operational sensor exists. Twelve of these measurement requirements are considered to be equivalent to the Bretherton report category of essential priority (No. 3), nine are in the category of highly important (No. 2), and one is in the category of substantially important (No. 1).

The importance of these measurement requirements can be better understood by citing some of their roles in global change characterization:

Ozone depletion: requirements for global daily measurements of stratospheric ozone and related photochemically important stratospheric trace gases

Greenhouse warming: requirements for global daily measurements of atmospheric temperatures, radiation budget components, trace gases and particulates, ocean parameters, and wind fields

Air pollution: requirements for measurements of tropospheric gases, particulates, precipitation, and pH of rain and clouds

Land surface characteristics: requirements for measurements of soil moisture, precipitation, cloud cover, radiation budget components, land surface temperatures, vegetation coverage, surface roughness, and river runoff

Transient events: requirements for measurement information on volcanoes, earthquakes, and floods

The particular intent of a given measurement requirement will affect the sensor selection and the resolution desired. For example, techniques and resolutions needed to measure cloud-top altitudes may be different from those needed to estimate location and extent of cloud cover. Thus, the extensive array of measurements in table I indicates those sensors needed aboard orbiting spacecraft for conducting space-based remote sensing, and table II indicates the deficiencies in the sensor maturity or operational status. The technologies needed to enable those sensors, to handle the resultant data, and to support their operation in the space environment are the technologies of interest to GCTI.

### 3. Advanced Technology Needs

A series of three workshops was sponsored by NASA HQ to gather the total NASA input to the GCTI program. The format used to present each technology proposed at these workshops was a four-quadrant chart ("quad" chart) which summarized the highlights of the proposal. These charts (LaRC's proposals are presented in the appendices) provide a detailed description of each technology as follows: the upper left quadrant gives the scope, objective, and rationale for the proposed technology; the upper right quadrant discusses the proposed approach as well as a list of deliverable items; the bottom left

quadrant presents the writer's estimate of the schedule for achieving the technology readiness levels (defined in table III), and the bottom right quadrant presents the writer's estimate for the funding and manpower required to accomplish each identified deliverable. The name of the quad chart writer is indicated in the upper right corner. Since this material was developed by many individuals, there is some variation in adherence to the formats, but in general, similar information appears throughout.

The work breakdown structure (WBS) developed for the GCTI in the three workshops is given in table IV and consists of three major thrusts: (1) observation technologies (WBS 1.0), (2) spacecraft and operations technologies (WBS 2.0), and (3) data and information systems technologies (WBS 3.0). NASA HQ has published a report (ref. 4) describing the needs in these areas. The GCTI technologies proposed by LaRC at these workshops are presented in appendices A, B, and C for each thrust area. Table V summarizes the number of proposals (quad charts) submitted by LaRC in each area and shows the requested funding totals in each fiscal year (FY 90 to 95) as extracted from the quad charts. A summary table listing the proposal titles is given in the appendices before each section of the WBS. LaRC had proposals in all but one WBS element (1.3 Submillimeter). LaRC proposals that were included in the HQ GCTI package (as of July 1989) are indicated in the summary tables within each appendix by a WBS number in the column denoted "NASA GCTI WBS." The technologies eventually chosen for GCTI funding will be selected from those listed in the appendices and from similar proposals made by other NASA centers.

#### Observation Technologies (WBS 1.0)

LaRC contributed 40 technology proposals in 7 of the 8 observation technology subelements (appendix A). These included entries in the areas of coolers, detectors, microwave sensing, optics, pointing and control, lasers, and calibration. The emphases of the observation technology proposals are primarily to advance maturity of the instruments and to improve overall measurement performance by development of better pointing, control, and calibration techniques. In order to better understand the importance of the LaRC proposals, the following discussion will address the development maturity of the sensing techniques.

Table I presents the broad list of measurements desirable for a global change science program, and the "measurement method" column often lists more than one possible observation approach. To assist in identifying the areas having the greatest technology needs, table II highlights the measurement

maturity for each observable. Some sensors have flown operationally; others have flown as experimental systems; and still others are only proposed experiments or, as yet, are unscheduled for development. Thus, it is possible to relate the science needs to technology needs via the measurement technique. Table VI presents in a matrix format the list of the top-level measurement categories cross-referenced to the techniques that have been proposed for each observable. For example, six potential sensing techniques have been identified for measuring the tropospheric ozone concentration. In addition to linking the observable to potential sensing techniques, this table links each technique to the advanced technologies required to enable or enhance it. As can be seen in the lower portion of the table, both the spacecraft and the data and information technologies can be so generally applicable as to enhance all the sensing techniques.

Table VI also shows the resolution and accuracy deemed adequate for each of the variables as proposed by the respondents to LaRC's survey. These numbers are different in some cases from the resolutions offered in table I; this reflects the different applications that various scientists may make of the same observable.

The sensing needs, in general, for a global Earth observation measurement program include the following:

- Laser systems for measuring cloud heights, aerosols, temperature, moisture, chemical composition, and winds
- Instruments for measurements in atmospheric chemistry
- High-resolution atmospheric sounders incorporating visible, infrared, and microwave channels
- Improved active/passive microwave sensors for surface hydrologic studies and precipitation measurements
- Earth radiation flux detectors

The extent of the technology development needed to bring any specific technique to maturity varies, of course, with the technique and its application. The technology readiness of the sensing techniques listed in table VI will now be described using a scale of 1 to 8 as defined in table III.

The authors wish to acknowledge Charles Husson of ST Systems Corp. (STX) for his contributions to the following descriptions of technology readiness of the science sensors.

***Light detection and ranging (lidar).*** Atmospheric physical and chemical properties as measured by laser interactions are well supported by theory and experiment. The design specifications for the components of a lidar system can be readily defined in order to achieve the required instrument performance. However, for the global change era, across-the-board improvements in component technology are required to extend the instrument performance; reduce weight, volume, and power; and comply with spacecraft integration requirements. As a generic instrumentation technology, lidar for global change is at level 3 and has passed through analytical conceptual design tests and in many cases has been demonstrated experimentally. Measurement requirements are being modified to meet the needs of future global change observations, and these inputs will challenge the component development and availability. The Lidar Atmospheric Sensing Experiment (LASE) and the Lidar In-Space Technology Experiment (LITE) provide a basis for the extrapolation to other lidar applications and a framework within which to design future instruments. Improvements under the GCTI in fixed and tunable lasers with optimized wavelengths; in laser wavemeters, filters, and receivers; and in telescopes are the prime requisites for reaching level 4 (critical functions/characteristics demonstrated).

***Gas correlation.*** Gas filter correlation radiometry (GFCR) is based on a well-established laboratory technology to detect gas species by the matched-filtering spectral-absorption properties of a gas in a test cell. While dual-beam spectroscopy has antecedents in sophisticated laboratory apparatus and is used to make passive remote measurements from the ground, aircraft, and spacecraft, the long optical paths and broadband source radiation inherent in remote passive sensing are limiting factors in the global change era. While for global change GFCR can be considered at level 3, current applications such as the Measurement of Air Pollution from Satellite (MAPS) instrument and the Halogen Occultation Experiment (HALOE) instrument will serve as precursors to advance the technology maturity. To meet the requirements for global change observations, further component development is required in detectors and test cell life, stability, and sensitivity; in telescope design; in beam path optics; and in solid-state modulators. With the availability of these improved components, GFCR instrument level 4 can be achieved.

***Ultraviolet radiometry—0.01 to 0.450  $\mu\text{m}$ .*** Using ultraviolet (UV) radiometry to measure solar radiance and the Earth's upper atmosphere has a well-developed basis in science. GCTI program activities will be focused on the development

of efficient optical throughput, stable and sensitive detectors, and optical beam devices to enhance information processing. UV radiometry for global change applications has passed the level 2 (conceptual design formulated) readiness state and, for some applications, has been tested in space. For future field-of-view, spatial resolution, and sensitivity requirements, level 3 or 4 can be reached only when components required by the level 2 designs are available and tested. These components include spectrometers, interferometers, lenses, detectors, and information processing components.

**Visible radiometry—0.450 to 0.750  $\mu\text{m}$ .** Visible radiometry is probably the most widely understood technology in the remote sensing inventory. For the global change era, users will be extending component capabilities to obtain better calibration, spectral resolution, and spatial resolution with their concomitant pointing, motion, and optical implications. Of these, calibration is the most critical. For example, measurement requirements of 10 nm spectral resolution with a system accuracy of 1 percent and 100 m spatial resolution challenge the current technology. While many of the global change science instrument concepts have moved into level 5 readiness (component/breadboard tested in a relevant environment), cost penalties and trade-offs associated with flight such as weight, power, volume, spectral and spatial resolution, motion compensation, sensor calibration, and information data density govern the overall level of technical readiness. In this broad sense, the global change visible radiometer instrument has entered level 4.

**Infrared radiometry—0.750 to 2.0  $\mu\text{m}$ .** For the pre-global change mission environment, infrared (IR) radiometry from 0.750 to 2.0  $\mu\text{m}$  is a well-developed remote measurement technology. However, for the global change era, there are requirements for increased spatial and spectral resolution, narrower fields of view, and long-term stability of optical and detection components. Also, major efforts are required to reduce weight, volume, and power. Analytical models are required to determine optical cleaning processes, telescope contamination, and heat flow in the field of view. This development work is a precursor for level 4 activity. In fact, there are still some efforts required to complete level 3, but the infrared radiometry instrument technology initiatives in the 0.750 to 2.0  $\mu\text{m}$  regime will primarily be directed to the completion of level 4.

**Far infrared radiometry—2.0 to 100  $\mu\text{m}$ .** Far infrared (FIR) radiometry instruments have precursors in the Earth Radiation Budget Experiment

(ERBE) and the Clouds and Earth's Radiant Energy System (CERES) upon which to build global change broadband instruments. Spectroscopy of the Atmosphere using Far Infrared Emissions (SAFIRE) is a precursor for molecular species measurements in FIR. The GCTI development should provide improvements in broadband detectors, calibration, and narrow-field-of-view telescopes. Also, better models for heat transfer, contamination, and stability are required for testing and analysis. Technology improvements to FIR radiometry are focused on instrument performance, weight, volume, and power for the global change era. Since the GCTI effort will be directed to get the best performance out of the individual component technologies, the instrument performance requirements will depend on the achievable component technology. Completion of level 3 is possible with preliminary results from the GCTI program and from CERES. When component performance is demonstrated, level 4 activities may begin.

**Submillimeter wave.** Submillimeter heterodyne receiver technology is the only technique capable of providing the required sensitivity and spectral resolution to simultaneously monitor both primary and trace species involved in the destruction of stratospheric ozone. The current state of the art in submillimeter technology covers frequencies up to 200 GHz. The existing gallium arsenide mixers do not have sufficient sensitivity to detect all the species on a global scale. New quantum well or varactor solid-state local oscillators and submillimeter receivers at 1200 and 2000 GHz must be developed for critical observations of OH and HF. Heterodyne receiver technology does not exist for these frequencies. Both photoconductive and superconducting mixers will be pursued, and lower temperature coolers must be available. Overall, the instrument performance, now at level 2, depends on component development matched to global change requirements.

**Microwave radiometry.** Passive microwave technology has the following factors affecting its future development: instrument development, performance characterization, spacecraft integration requirements, and the analyses of data decomposition algorithms. Requirements in the global change era include more stringent specifications on the lobe effects, surface finishes, and receiver technology. Analysis of complex, asymmetrical, large receiving antennas has not been completed, and resulting antenna designs may create challenging spacecraft integration problems. Further, the receiver technology and information processing concepts are closely linked to the antenna design and performance. For these reasons,

much of the microwave radiometry instrument activity is limited primarily to level 2 and partially to level 3. The technical initiatives to bring microwave radiometry into the global change era will address the level 2 and level 3 issues within the context of spacecraft weight, volume, power, and integration limits. Prior to reaching level 4, full-scale tests will be required.

**Active microwaves.** Active microwave technology has three facets to its readiness level: (1) the complexity of the reflection system, (2) the pointing and control management and implementation system, and (3) the detectors. Because of platform limitations, microwave antenna reflection systems are typically asymmetrical and difficult to analyze or design to obtain the desired improvements in the scanning and ranging requirements. Further, the narrow-field-of-view requirements for global change applications require significant reduction of lobe patterns. This difficulty is further increased by the asymmetry of the antenna system. Detector improvement is less demanding than that required for passive systems. The technology initiatives for global change will be directed at level 2 and level 3 activities. Some full-scale testing will be required to reach level 4.

**Active cavity radiometry.** Active cavity radiometers require cryogenic coolers in order to achieve the needed improvements in time constants, sensitivity, and field of view. As yet, the detectors, cooling, and calibration components have not been integrated as an instrument package. While the components are mature, the instrument itself must next be brought to level 5 (component/breadboard tested in relevant environment).

**In situ.** This category implies no particular sensing technique, but will require application of many of the techniques discussed above. Although the stringent requirements placed on an instrument for remote sensing do not generally apply to in situ measurements, the technology advances made in components will surely find applications here as well.

The quad charts in appendix A represent LaRC proposals in the observations thrust.

### Spacecraft and Operations Technologies (WBS 2.0)

Although the discussion in the previous section has highlighted the critical issue of sensor maturity and the technology needs of the instruments, many additional supporting technologies must be developed relative to the spacecraft that carries the instruments and to the data-handling systems that store

and process the huge volume of information the instruments produce. This section presents the work breakdown structure (WBS) developed to categorize the spacecraft technologies, and the next section addresses the information systems. LaRC contributed 18 quad charts in the 6 spacecraft WBS subelements (appendix B). These included entries in the areas of materials, structures and control, systems analysis, power, propulsion, and thermal control. In three of these areas (WBS 2.4, 2.5, 2.6), the proposals submitted by LaRC were related to nondestructive evaluation (NDE) techniques for monitoring system and component health. In WBS 2.3, the three proposals for systems analyses assume cooperation with other centers, but LaRC proposes to lead these activities and provide funds to others as suballotments from the total funding.

The emphases of technology proposals in this WBS thrust are very broad and address improvements needed in all the spacecraft subsystems as well as in their integration into operational spacecraft that can achieve the performance required by the global change science mission. While the various disciplines (e.g., power, propulsion, and attitude control) continue to advance subsystem and component capabilities, their utilization in flight systems is limited because of a lack of flight qualification history and heritage. It is proposed that a flight qualification program be initiated under the GCTI to carry those particularly promising technologies to flight hardware status. These subsystems and components could then be incorporated into the future system-level designs with reasonable expectations of obtaining acceptance and approval.

**Materials.** Global change missions require highly efficient platform and experiment support structures with stable geometry, long (5 to 30 years) life, and reliable performance in both geostationary and low Earth orbits. The materials element addresses the need to develop structural and tribological materials and coatings and nondestructive evaluation/inspection technology for reliable long-term performance of high-precision observation systems, reflectors, antennas, and stable platforms.

**Structures and controls.** The employment of multi-instrument platforms with their stringent pointing accuracy and stability specifications required by global change science dictates the development of new structures and control technologies. The structures and control element addresses the issues associated with potentially large and flexible platform structures and reflectors (erectable and deployable) and pointing, dynamics, and control.

**Systems.** The proposed Mission to Planet Earth (MPE) presents unprecedented challenges in all spacecraft and sensor system areas as well as in integration and on-orbit verification of all these systems to effect an operational spacecraft. The systems element provides the methodologies, tools (software, graphics, workstations), and studies needed to conduct spacecraft/platform/sensor system- and subsystem-level design and evaluations. Such studies assess the relative merits that various space infrastructures, competing technologies, or operational strategies might have. An MPE architectural system study now underway will compare the performance and complexity of placing subsets of the global change sensors in low Earth orbit, geostationary orbit, or other intermediate orbits. A second system study is examining the performance of geostationary platform concepts to achieve the pointing and stability requirements for a complement of 18 typical instruments proposed for global change science. This study will quantify the sources of performance limitations and the benefits that can be derived from application of various advanced technology options.

Other studies include requirements for autonomous and adaptive on-orbit integration, certification, and verification; requirements for automated assembly and checkout of large platforms; and assessment of space environmental effects on systems.

**Power, propulsion, thermal control.** The LaRC proposals in these areas represent various applications of nondestructive evaluation techniques to improve the monitoring and diagnosis of system and component health.

The elements in the spacecraft/operations technology program include analysis, design, development, integration, test, and verification of components and systems and the use of ground and flight tests and operations. These activities should result in better prediction of system performance, lower risk, and greater confidence in meeting mission objectives.

The quad charts in appendix B represent LaRC proposals in the spacecraft and operations thrust.

## Data and Information Systems Technologies (WBS 3.0)

The data volume and data rates that will be produced by the instruments proposed for a global change science program will greatly exceed all previous science programs. The supporting information system must provide end-to-end services including data acquisition, storage and communication, and delivery to the user community. LaRC contributed 24 quad charts in the 4 WBS subelements (appendix C). These included entries in the areas of systems,

flight element, information transfer, and ground element technologies. The emphases of the technologies in this thrust are very broad and address such diverse issues as flight and ground element hardware, software, and architectures, as well as software development environments, networks, and user interfaces.

**Systems technology.** A review of the information system maturity reveals the need for improvement in several key areas: application of standards at command, data, and interface development; use of software engineering approaches for creation of software at all levels, including flight, ground, and user applications; development of integrated tool sets that cover the entire development life cycle for both hardware and software (design, rapid prototyping, performance evaluation, integration, test, and calibration); use of test beds for determining reliability of hardware and software designs; creation of reusable software packages; and the application of automation for reducing the burden of continuous mission operations.

**Flight element technologies.** The performance of the orbiting sensors, in terms of system reliability, adaptability, and data quality, can be improved by using processing elements specifically matched to individual sensors. Such sensor preprocessing takes advantage of intimate knowledge of the sensor characteristics and optimizes use of the spacecraft resources while still delivering data in a generic format suitable for shared processing. The technologies holding the most promise include advanced neural networks, optical preprocessors, hybrid digital processors, and chip-level integration. Very Large Scale Integration (VLSI) technologies will be required to deliver components that meet the constraints of weight, power, and size. In addition, the onboard data system used to gather, store, and deliver science data can be improved to reduce data flow bottlenecks. The significant technologies in this area include high data rate, large volume storage systems; data compression and autonomous target-of-opportunity techniques; and interconnect systems with low electromagnetic interference susceptibility.

**Information transfer.** The highest priority technologies needed for development of the high-performance, space-based communications systems will be those that enable use of the wideband optical frequencies and high accuracy beam pointing. These include improvements in laser power output and receiver sensitivity and will result in smaller antennas, improved packaging, and reductions in spacecraft disturbance torques, size, weight, and power. The ground segment requires improvement

in those technologies that enable broad distribution and data access to principal investigators and end users. Specifically, high-performance networks and microwave ground terminals are needed for access to data archives and supercomputing resources so that communications network performance will be commensurate with recent advances in optical storage and scientific workstation performance.

**Ground element technologies.** Maximizing the scientific return from the collected data is the broad emphasis of this area. The multidisciplinary nature of Earth system science will require scientists to study data sets outside their normal areas of expertise and to process and understand the implications of the data. Obvious technology needs will include the advancement of mass storage devices, high-performance parallel processors, and information extraction techniques that can accommodate the huge volume of science data. In addition, smart user interfaces will be needed to support data query, filtering, and visualization, and to enable scientists to collaborate with others to fuse data for comprehension. Special purpose processors will also be needed for efficient processing of sensor- or problem-specific algorithms, and improvement in modeling techniques will be required to reconstruct and simulate the Earth processes identified under this science program.

The quad charts in appendix C represent LaRC proposals in the data and information systems thrust.

#### 4. Programmatic Assessment

The 82 LaRC proposals summarized in table V were submitted during the course of 3 workshops held to develop the GCTI WBS and to prioritize technologies. Fifty-nine of these were still included, in some form, within the full GCTI quad package distributed in late June 1989 by NASA, OAST. The GCTI has been envisioned as having three emphases for its technology developments (table VII). In phase 1, those technologies that support or provide needed alternatives for the near-term Earth Observing System (EOS) will be included under EOS technology. In phase 2, those technologies applicable to other low Earth (LEO) or geostationary-orbiting (GEO) sensors and spacecraft will be included under LEO/GEO technologies. These two phases are the only ones currently proposed for the FY 91 funding start. Phase 3 technologies are those specifically dictated by a future Mission to Planet Earth infrastructure and will be identified at a future time.

Budget realities will likely dictate that all of LaRC's proposals cannot be accommodated within GCTI. However, some of these proposals may be

addressed under existing OAST base funding or focused research and technology programs. In any event, the role that LaRC plays in the future global change program must be shaped by a conscientious effort by LaRC management to acquire the resources and to prioritize the programs that it feels will serve the nation and NASA best.

#### 5. Concluding Remarks

Global change is a documented reality and a focus of international scientific and policy concern. The greenhouse effect, ozone depletion, and acid rain have heightened worldwide awareness of the need for a better understanding of the Earth's atmosphere and its dynamic interactions with the land and oceans. A brief overview has been given of the global change science issues and their related measurements. The science requirements and candidate sensors for each measurement have been summarized. Technologies that enable or enhance these measurements have been proposed as part of the Langley Research Center (LaRC) technology development program. Detailed descriptions have also been given for each proposed technology, including the scope, objective, and approach for that candidate; a technology readiness timeline; a list of deliverables; and an estimate of the resources needed to meet the deliverables milestones. This report, documenting the products of the LaRC Global Change Technology Initiative (GCTI) Task Force, will be provided to NASA Headquarters to support their efforts to develop a GCTI program. In addition, it is hoped that the areas of technology advancement highlighted by this report will motivate research and development by industry and universities so that the gap between the desire for and the reality of global change understanding will be narrowed.

NASA Langley Research Center  
Hampton, VA 23665-5225  
August 22, 1990

#### References

1. NOAA; and NASA: *Space-Based Remote Sensing of the Earth: A Report to the Congress*. U.S. Government Printing Off., Sept. 1987.
2. Ride, Sally K.: *Leadership and America's Future in Space*. A Report to the Administrator of NASA, Aug. 1987.
3. Earth System Sciences Committee, NASA Advisory Council: *Earth System Science—A Closer View*. NASA, Jan. 1988.
4. Butner, C. L., ed.: *Global Change Technology Initiative—Technical Overview*. Contract NASW-4470, General Research Corp., May 1990.

## Appendix A

### Observation Technology Proposals (WBS 1.0)

#### LaRC GCTI Observation Technologies

##### 1.1 Coolers

Technology	NASA GCTI WBS	Proposal funding requirements, millions of dollars					
		FY90	FY91	FY92	FY93	FY94	FY95
Leak monitor for refrigerants			0.1	0.1	0.1	0.2	0.2
Totals			—	—	—	—	—

## Leak Monitor for Refrigerants

E. MADARAS

<p><b>SCOPE</b> DEVELOP FIBER OPTIC SENSORS THAT CAN BE USED TO LOCATE LEAKS IN AMMONIA-BASED REFRIGERANT SYSTEMS.</p> <p><b>OBJECTIVE</b></p> <ul style="list-style-type: none"> <li>• PROVIDE REAL-TIME INFORMATION ABOUT THE LOCATION OF AMMONIA-BASED REFRIGERANTS.</li> </ul>	<p><b>APPROACH</b></p> <ul style="list-style-type: none"> <li>• DEVELOP FIBER OPTIC COATINGS THAT ARE SPECIFICALLY SENSITIVE TO THE AMMONIA-BASED REFRIGERANT MATERIAL.</li> <li>• DEVELOP THE MEASUREMENT SYSTEM THAT CAN BE USED TO MEASURE THE SPECIAL FIBER FOR LEAKS.</li> </ul>	<p><b>DELIVERABLES</b></p> <ol style="list-style-type: none"> <li>1. A SPECIFICALLY DESIGNED FIBER WITH COATING THAT IS SENSITIVE TO THE PRESENCE OF THE REFRIGERANT THAT IS TO BE USED.</li> <li>2. DEVELOP A PROTOTYPE SYSTEM TO MONITOR THE FIBER SYSTEM FOR THE PRESENCE OF THE REFRIGERANTS.</li> </ol>	<p><b>TECHNOLOGY ASSESSMENT</b></p> <p>READYNESS LEVEL</p> <p>YEAR</p> <p>WORKING AT READINESS LEVELS OF 2 THROUGH 5</p>	<p><b>DEVELOPMENT PLAN</b></p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="text-align: left; padding: 2px;">YR 1991</th><th style="text-align: left; padding: 2px;">1992</th><th style="text-align: left; padding: 2px;">1993</th><th style="text-align: left; padding: 2px;">1994</th><th style="text-align: left; padding: 2px;">1995</th><th style="text-align: left; padding: 2px;">1996</th></tr> </thead> <tbody> <tr> <td style="text-align: left; padding: 2px;">\$/MY</td><td style="text-align: left; padding: 2px;">\$0.1 M 1</td><td style="text-align: left; padding: 2px;">\$0.1 M / 1</td><td style="text-align: left; padding: 2px;">\$0.1 M / 1</td><td style="text-align: left; padding: 2px;">\$0.1 M / 1</td><td style="text-align: left; padding: 2px;">\$0.1 M / 1</td></tr> <tr> <td></td><td></td><td></td><td></td><td style="text-align: left; padding: 2px;">\$0.1 M / 2</td><td style="text-align: left; padding: 2px;">\$0.2 M / 2</td></tr> <tr> <td></td><td></td><td></td><td></td><td style="text-align: left; padding: 2px;">2</td><td style="text-align: left; padding: 2px;">2</td></tr> </tbody> </table>	YR 1991	1992	1993	1994	1995	1996	\$/MY	\$0.1 M 1	\$0.1 M / 1					\$0.1 M / 2	\$0.2 M / 2					2	2			
YR 1991	1992	1993	1994	1995	1996																							
\$/MY	\$0.1 M 1	\$0.1 M / 1	\$0.1 M / 1	\$0.1 M / 1	\$0.1 M / 1																							
				\$0.1 M / 2	\$0.2 M / 2																							
				2	2																							

LaRC GCTI Observation Technologies

1.2 Detectors

Technology	NASA GCTI WBS	Proposal funding requirements, millions of dollars					
		FY90	FY91	FY92	FY93	FY94	FY95
Long-life detector arrays	1.21	0.5	1.0	0.8	0.8	1.0	1.0
InGaAs avalanche photodiodes	1.22	.2	.4	.4	.4	.4	.2
Multiquantum well infrared detectors	1.22	.2	.4	.4	.4	.4	.2
Broadband sensor technology	1.24	.125	.125	.125	.125	.25	.25
Far infrared technology	1.25	.5	1.1	1.0	1.0	1.0	0
Detector arrays for smart sensing	1.26		.5	2.0	2.0	1.0	0
Chip-level integration of sensor preprocessing	3.21-1		2.0	3.0	3.0	3.0	3.0
Smart sensors			.5	1.0	1.0	1.0	0
Totals		1.525	6.025	8.725	8.725	8.05	4.65

# INFRARED DETECTOR TECHNOLOGY - LONG-LIFE DETECTOR ARRAYS

W. MILLER

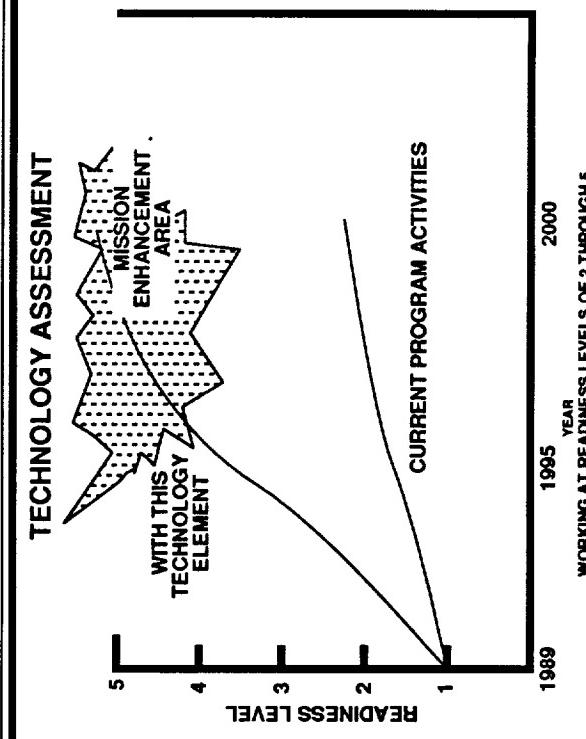
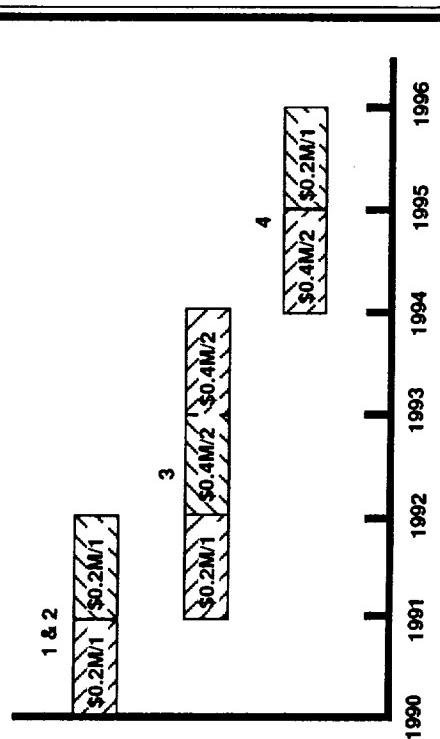
SCOPE	APPROACH																				
DEVELOP LONG-LIFE INFRARED DETECTOR ARRAY TECHNOLOGY TO SUPPORT GLOBAL CHANGE MEASUREMENTS OF ATMOSPHERIC CONSTITUENTS AND TEMPERATURE.	DEVELOP HgZnTe MATERIALS AND DEVICE TECHNOLOGY THROUGH THE USE OF SOLID-STATE RECRYSTALLIZED AND LIQUID EPITAXIAL GROWN SUBSTRATES. PERFORM LIFETIME TESTS ON PC AND PV DETECTORS IN DISCRETE AND ARRAY FORMATS FABRICATED BY LIQUID EPITAXY, METALLO-ORGANIC CHEMICAL VAPOR DEPOSITION (MOCVD), AND MOLECULAR BEAM EPITAXY (MBE) TECHNIQUES.																				
OBJECTIVE	DELIVERABLES																				
INCREASE RELIABILITY AND OPERATING LIFETIME OF DISCRETE AND ARRAYER DETECTORS. INCREASE SPECTRAL COVERAGE OF PHOTOCONDUCTIVE (PC) AND PHOTOVOLTAIC (PV) ARRAYS.	<ol style="list-style-type: none"> <li>1. HgZnTe SUBSTRATES COVERING 3-5 AND 8-20 MICRON SPECTRAL REGIONS AND SUPERIOR ELECTRO-OPTICAL (E-O) AND MECHANICAL PROPERTIES.</li> <li>2. PC AND PV TEST SAMPLES.</li> <li>3. PROTOTYPE LINEAR AND AREA ARRAYS.</li> <li>4. MONOLITHIC LINEAR AND AREA ARRAYS.</li> </ol>																				
RATIONALE	TECHNOLOGY ASSESSMENT																				
HgZnTe HAS DEMONSTRATED INCREASED STRENGTH AND RESISTANCE TO THERMAL DRIFT. DEVELOPMENT OF LONG-LIFE DISCRETE AND ARRAY IR DETECTORS ON HgZnTe COVERING THE MID-IR (3-5 MICRONS) AND FAR-IR (8-20 MICRONS) WILL ENABLE MISSION LIFETIMES OF GREATER THAN FIVE YEARS.	<p>The diagram shows a graph of technology readiness levels (1 to 5) versus time (1989 to 1995). A diagonal line represents the current program activities. A shaded area labeled "MISSION ENHANCEMENT AREA" is bounded by two curves. An arrow points from the text "WITH THIS TECHNOLOGY ELEMENT" towards the shaded area.</p> <table border="1"> <thead> <tr> <th>YEAR</th> <th>READYNESS LEVEL</th> </tr> </thead> <tbody> <tr><td>1989</td><td>1</td></tr> <tr><td>1990</td><td>2</td></tr> <tr><td>1991</td><td>3</td></tr> <tr><td>1992</td><td>4</td></tr> <tr><td>1993</td><td>5</td></tr> <tr><td>1994</td><td>4</td></tr> <tr><td>1995</td><td>3</td></tr> <tr><td>1996</td><td>2</td></tr> <tr><td>NASA-LaRC</td><td>1</td></tr> </tbody> </table> <p>CURRENT PROGRAM ACTIVITIES</p> <p>WORKING AT READINESS LEVELS OF 2 THROUGH 5</p>	YEAR	READYNESS LEVEL	1989	1	1990	2	1991	3	1992	4	1993	5	1994	4	1995	3	1996	2	NASA-LaRC	1
YEAR	READYNESS LEVEL																				
1989	1																				
1990	2																				
1991	3																				
1992	4																				
1993	5																				
1994	4																				
1995	3																				
1996	2																				
NASA-LaRC	1																				
DEVELOPMENT PLAN	<p>The timeline shows budget phases: Phase 1 &amp; 2 (\$0.5M/2), Phase 3 (\$0.8M/3), and Phase 4 (\$1.0M/4). The timeline spans from 1990 to 1996, with a specific point marked for NASA-LaRC in 1996.</p> <table border="1"> <thead> <tr> <th>YR</th> <th>BUDGET PHASE</th> </tr> </thead> <tbody> <tr><td>1990</td><td>1 &amp; 2</td></tr> <tr><td>1991</td><td>1 &amp; 2</td></tr> <tr><td>1992</td><td>1 &amp; 2</td></tr> <tr><td>1993</td><td>3</td></tr> <tr><td>1994</td><td>3</td></tr> <tr><td>1995</td><td>4</td></tr> <tr><td>1996</td><td>4</td></tr> <tr><td>NASA-LaRC</td><td>1</td></tr> </tbody> </table>	YR	BUDGET PHASE	1990	1 & 2	1991	1 & 2	1992	1 & 2	1993	3	1994	3	1995	4	1996	4	NASA-LaRC	1		
YR	BUDGET PHASE																				
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NASA-LaRC	1																				

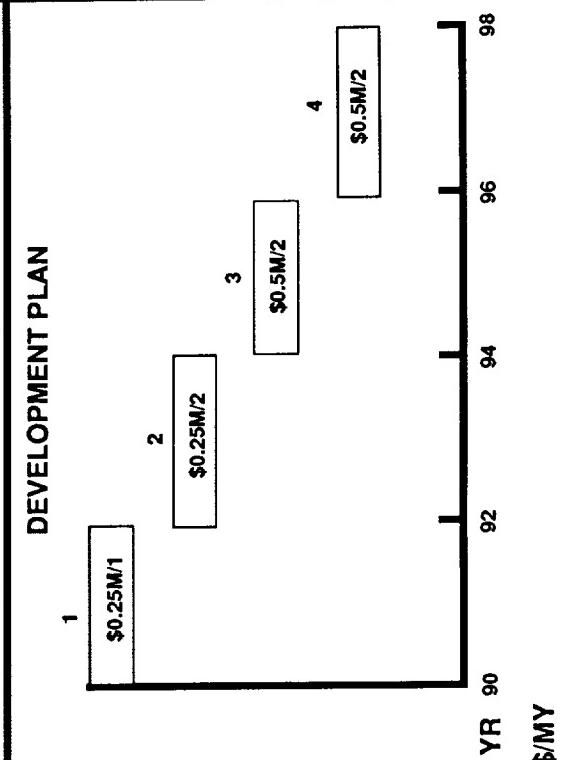
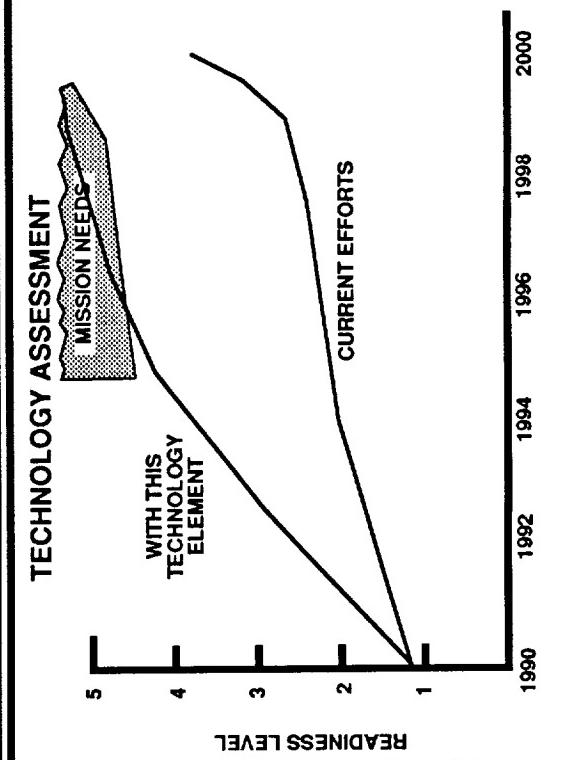
# INFRARED DETECTOR TECHNOLOGY - InGaAs AVALANCHE PHOTODIODES

SCOPE	APPROACH									
<p>DEVELOP InGaAs AVALANCHE PHOTODIODE (APD) INFRARED DETECTOR ARRAY TECHNOLOGY TO SUPPORT GLOBAL CHANGE LIDAR MEASUREMENTS OF ATMOSPHERIC CONSTITUENTS.</p> <p>OBJECTIVE</p> <p>INCREASE SPECTRAL COVERAGE OF AVALANCHE PHOTODIODES.</p> <p>INCREASE SENSITIVITY AND OPERATING LIFETIME OF DISCRETE AND ARRAYED LIDAR DETECTORS.</p>	<p>DEVELOP InGaAs AVALANCHE PHOTODIODE MATERIALS AND DEVICE TECHNOLOGY THROUGH THE USE OF METALLO-ORGANIC CHEMICAL VAPOR DEPOSITION (MOCVD) EPITAXIAL GROWN SUBSTRATES. PERFORM PERFORMANCE AND LIFETIME TESTS ON APD DETECTORS IN DISCRETE AND ARRAY FORMATS FABRICATED BY MOCVD EPITAXY.</p>									
<p>RATIONALE</p> <p>ENABLES ACCURATE GLOBAL MEASUREMENTS OF ATMOSPHERIC AEROSOLS AND OTHER IMPORTANT TRACE CHEMICALS WITH EYE-SAFE LIDAR.</p>	<p>DELIVERABLES</p> <ol style="list-style-type: none"> <li>1. InGaAs SUBSTRATES TO 2 MICRONS WITH SUPERIOR E-O AND MECHANICAL PROPERTIES.</li> <li>2. AVALANCHE PHOTODIODE TEST SAMPLES.</li> <li>3. PROTOTYPE LINEAR AND AREA ARRAYS.</li> <li>4. EVALUATION OF LINEAR AND AREA ARRAYS.</li> </ol>									
<p>TECHNOLOGY ASSESSMENT</p>	<p>DEVELOPMENT PLAN</p> <table border="1"> <tr> <td>1 &amp; 2</td> <td>\$0.2M/1</td> <td>\$0.2M/1</td> </tr> <tr> <td>3</td> <td>\$0.4M/2</td> <td>\$0.4M/2</td> </tr> <tr> <td>4</td> <td>\$0.4M/2</td> <td>\$0.2M/1</td> </tr> </table> <p>YR 1990 1991 1992 1993 1994 1995 1996 NASA-LaRC</p>	1 & 2	\$0.2M/1	\$0.2M/1	3	\$0.4M/2	\$0.4M/2	4	\$0.4M/2	\$0.2M/1
1 & 2	\$0.2M/1	\$0.2M/1								
3	\$0.4M/2	\$0.4M/2								
4	\$0.4M/2	\$0.2M/1								

# INFRARED DETECTOR TECHNOLOGY - MULTIQUANTUM WELL IR DETECTORS

W. MILLER

<b>SCOPE</b> DEVELOP AlGaAs MULTIQUANTUM WELL INFRARED PHOTODIODE DETECTOR ARRAY TECHNOLOGY TO SUPPORT GLOBAL CHANGE LIDAR MEASUREMENTS OF ATMOSPHERIC CONSTITUENTS.	<b>APPROACH</b> DEVELOP AlGaAs MULTIQUANTUM WELL PHOTODIODE MATERIALS AND DEVICE TECHNOLOGY THROUGH THE USE OF MOLECULAR BEAM EPITAXY (MBE) EPITAXIAL GROWN PROCESS. PERFORM QUANTUM CHARACTERIZATION AND LIFETIME TESTS ON MULTI-WELL DETECTORS IN DISCRETE AND ARRAY FORMATS.																		
<b>OBJECTIVE</b> INCREASE SPECTRAL COVERAGE OF MULTIQUANTUM WELL PHOTODIODES. INCREASE SENSITIVITY AND OPERATING LIFETIME OF DISCRETE AND ARRIVED LIDAR DETECTORS.	<b>DELIVERABLES</b> 1. AlGaAs OPTIMIZED FOR 4.7 MICRONS WITH SUPERIOR E-O AND MECHANICAL PROPERTIES. 2. MULTIQUANTUM PHOTODIODE TEST SAMPLES. 3. PROTOTYPE LINEAR AND AREA ARRAYS. 4. EVALUATION OF LINEAR AND AREA ARRAYS.																		
<b>RATIONALE</b> ENABLES ACCURATE GLOBAL MEASUREMENTS OF ATMOSPHERIC CO AND OTHER IMPORTANT TRACE CHEMICALS WITH EYE-SAFE LIDAR.	<b>TECHNOLOGY ASSESSMENT</b>  <p>The graph plots Technology Readiness Level (1 to 5) against Year (1990 to 2000). A diagonal line shows current program activities. A shaded area labeled 'MISSION ENHANCEMENT AREA' is bounded by two curves. The upper curve starts at RDL 1 in 1990 and rises to RDL 5 in 2000. The lower curve starts at RDL 1 in 1990 and rises to RDL 3 in 2000. A callout points to the upper curve with the text 'WITH THIS TECHNOLOGY ELEMENT'.</p> <table border="1"> <thead> <tr> <th>YEAR</th> <th>READYNESS LEVEL</th> </tr> </thead> <tbody> <tr><td>1990</td><td>1</td></tr> <tr><td>1991</td><td>1</td></tr> <tr><td>1992</td><td>1</td></tr> <tr><td>1993</td><td>1</td></tr> <tr><td>1994</td><td>1</td></tr> <tr><td>1995</td><td>1</td></tr> <tr><td>1996</td><td>1</td></tr> <tr><td>2000</td><td>5</td></tr> </tbody> </table> <p>WORKING AT READINESS LEVELS OF 2 THROUGH 5</p>	YEAR	READYNESS LEVEL	1990	1	1991	1	1992	1	1993	1	1994	1	1995	1	1996	1	2000	5
YEAR	READYNESS LEVEL																		
1990	1																		
1991	1																		
1992	1																		
1993	1																		
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1995	1																		
1996	1																		
2000	5																		
<b>DEVELOPMENT PLAN</b>  <p>The timeline shows funding levels for four phases:</p> <ul style="list-style-type: none"> <li>Phase 1 &amp; 2: \$0.2M/1</li> <li>Phase 3: \$0.4M/2</li> <li>Phase 4: \$0.4M/2</li> <li>Phase 4: \$0.2M/1</li> </ul> <p>1996 marks the NASA LaRC entry point.</p>																			

ADVANCED SENSOR CONCEPTS-BROADBAND SENSOR TECHNOLOGY	
<b>SCOPE</b>	<b>APPROACH</b> EXAMINE MATERIALS POSSESSING HIGH RESPONSE TO LOW LEVELS OF RADIANT ENERGY THAT CAN BE FASHIONED INTO HIGHLY SENSITIVE, SMALL ELEMENT DEVICES (EITHER SINGLE ELEMENT OR ARRAYS). DETERMINE THAT THESE DEVICES CAN BE OF UNIFORM SPECTRAL SENSITIVITY OVER THE RANGE OF 250 nm to GREATER THAN 50,000 nm.
<b>OBJECTIVE</b>	<b>DELIVERABLES</b> 1. EXAMINE MATERIALS POSSESSING POTENTIALLY HIGH SENSITIVITY AND WIDE SPECTRAL RESPONSE. 2. SELECT THE MOST PROMISING GROUP OF MATERIALS TO BEGIN INVESTIGATIONS ON A DETAILED SCALE. 3. PRODUCE A PROTOTYPE SENSOR AND CHARACTERIZE ITS OPERATING PARAMETERS. 4. DETERMINE REQUIREMENTS AND CHARACTERISTICS OF FABRICATING AN ARRAY DEVICE
<b>RATIONALE</b>	<b>DEVELOPMENT PLAN</b> 
<b>MISSION NEEDS</b> PRESENT TECHNOLOGY FOR EARTH RADIANCE MEASUREMENTS HAS PUSHED THE USE OF DETECTOR MATERIALS (E.G., THERMISTOR BOLOMETER, PYROELECTRIC DETECTOR) TO THEIR LIMIT. A NEW SENSOR MATERIAL WITH HIGH SENSITIVITY AND WIDE SPECTRAL RESPONSE IS NEEDED IN SCANNING AND/OR ARRAY SYSTEMS TO PROVIDE THE NEEDED GROUND RESOLUTION FROM ORBIT.	<b>TECHNOLOGY ASSESSMENT</b> 

# ADVANCED SENSOR CONCEPTS-FAR INFRARED TECHNOLOGY

SCOPE	APPROACH										
<p><b>OBJECTIVE</b></p> <ul style="list-style-type: none"> <li>ADD NEW MEASUREMENT CAPABILITIES.</li> <li>EXPAND DYNAMIC RANGE OF MEASUREMENTS.</li> <li>FILTER EARTH RADIATION NOISE.</li> </ul> <p><b>RATIONALE</b></p> <p>ENABLES ACCURATE MEASUREMENT OF THE MOST REACTIVE CHEMICAL SPECIES (OH) AND OTHER IMPORTANT REACTANTS IN THE STRATOSPHERE.</p>	<p>DEVELOP NARROW BAND FILTER TECHNOLOGY THROUGH THE USE OF PHOTOLITHOGRAPHED ETCHED METAL ETALON FILTERS TO REDUCE THE INFLUENCE OF THE BACKGROUND IR RADIATION FROM EARTH.</p> <p><b>DELIVERABLES</b></p> <ol style="list-style-type: none"> <li>TECHNOLOGY TO PRODUCE METAL ETALON FILTERS.</li> <li>TEST SAMPLES AND EVALUATION MODELS.</li> <li>MODELING AND COOLING TECHNIQUES.</li> <li>EVALUATION OF FILTERS IN HIGH BACKGROUND EXPERIMENTS.</li> </ol>										
<p><b>TECHNOLOGY ASSESSMENT</b></p> <p>EVOLUTION OF INFRARED NARROW PASSBAND TECHNOLOGY</p>	<p><b>DEVELOPMENT PLAN</b></p> <table border="1"> <thead> <tr> <th>Milestone</th> <th>Budget (\$/MY)</th> </tr> </thead> <tbody> <tr> <td>1</td> <td>\$0.5M</td> </tr> <tr> <td>2</td> <td>\$0.6M</td> </tr> <tr> <td>3</td> <td>\$1.0M</td> </tr> <tr> <td>4</td> <td>\$1.0M</td> </tr> </tbody> </table>	Milestone	Budget (\$/MY)	1	\$0.5M	2	\$0.6M	3	\$1.0M	4	\$1.0M
Milestone	Budget (\$/MY)										
1	\$0.5M										
2	\$0.6M										
3	\$1.0M										
4	\$1.0M										

# DETECTOR ARRAYS FOR SMART SENSING

A. JALINK

<p><b>SCOPE</b></p> <p>DEVELOP MID-IR CHARGE-COUPLED DEVICE (CCD) DETECTOR ARRAY TECHNOLOGY FOR SCAN MODE, RESOLUTION ZOOM, AND SPECTRAL BAND COVERAGE ABILITY.</p> <p><b>OBJECTIVE</b></p> <p>OBTAINT ON-ORBIT SMART SENSING CAPABILITY FOR IMPROVED ATMOSPHERIC EPISODE PRECURSOR DETECTION AND MEASUREMENT. MID-IR (6-16 MICRON) DETECTOR ARRAYS WHICH ALLOW POWERFUL ELECTRO-OPTICAL MEASUREMENT ARCHITECTURES, AS THOSE RECENTLY ACCOMPLISHED BY SI-CCD FOR VIDEO PROCESSING.</p> <p><b>RATIONALE</b></p> <p>MID-IR CCD ARRAYED DETECTORS HOLD PROMISE FOR EVENT SENSING. EXAMPLES ARE ELECTRONICALLY ADJUSTABLE: FOV ZOOM; FOV SCAN MODES; SPECTRAL SCAN AND SELECT; INTEGRATION; SAMPLE/HOLD; DETECTOR BIAS PRELOAD.</p>	<p><b>APPROACH</b></p> <p>DETERMINE PRECURSOR EPISODE STRATEGIES, AND SET 'SMART' SENSING DETECTION ARCHITECTURE. DEVELOP CCD DETECTOR PROCESSES, MATERIALS AND DETECTOR ARCHITECTURE. DEVELOP PROTOTYPE DETECTOR AND LABORATORY DEMO OF APPROACH.</p> <p><b>DELIVERABLES</b></p> <ul style="list-style-type: none"> <li>1. REQUIREMENTS AND DETECTOR ARCHITECTURE DEFINITION,</li> <li>2. CCD DETECTOR TECHNOLOGY DEVELOPMENT PLAN,</li> <li>3. DELIVERY OF LABORATORY SAMPLE ARRAYS,</li> <li>4. DEMONSTRATE TECHNOLOGY AND APPLICATIONS.</li> </ul>
<p><b>TECHNOLOGY ASSESSMENT</b></p> <p>YR 1991 1992 1993 1994 1995 1996 1997 1998 1999 2000</p> <p>YEAR</p> <p>READYNESS LEVEL</p> <p>1 2 3 4 5</p> <p>CURRENT PROGRAM ACTIVITIES</p> <p>MISSION ENHANCEMENT AREA</p> <p>WITH THIS TECHNOLOGY ELEMENT</p>	<p><b>DEVELOPMENT PLAN</b></p> <p>YR 1991 1992 1993 1994 1995</p> <p>YEAR</p> <p>1 2 3 4</p> <p>\$0.5M/1</p> <p>\$2.0M/2</p> <p>\$2.0M/2</p> <p>\$1.0M/2</p> <p>NASA-LARC</p>

# CHIP-LEVEL INTEGRATION OF SENSOR PREPROCESSING

18

S. JURCZYK

SCOPE	APPROACH	DELIVERABLES	DEVELOPMENT PLAN	TECHNOLOGY ASSESSMENT																										
<p><b>SCOPE</b></p> <p>Develop extremely low-power custom sensor preprocessing chip to prepare output of large detector arrays and develop enhanced detector modules with integrated (on chip) preprocessing elements for onboard image and spectral data extraction.</p> <p><b>OBJECTIVE</b></p> <ul style="list-style-type: none"> <li>• Enable use of large detector arrays within power constraint.</li> <li>• Develop high-speed (wide bandwidth) space-qualified preprocessor systems.</li> <li>• Increase system reliability.</li> <li>• Improve performance including stability.</li> </ul> <p><b>RATIONALE</b></p> <p>Preprocessing for emerging detector technologies and large detector arrays cannot be accomplished using discrete components. Low-power, space-qualified custom integrated circuits will be required to meet performance speed, power, weight, and volume constraints.</p>	<ul style="list-style-type: none"> <li>Analyze preprocessing needs for strawman GCTI sensors.</li> <li>Identify suitable semiconductor processes and foundries.</li> <li>Develop custom integrated circuit approach.</li> <li>Design, fabricate, and test custom circuit.</li> <li>Integrate custom circuit into system and test.</li> </ul>	<ul style="list-style-type: none"> <li>Report on detector preprocessing requirements.</li> <li>Report on custom integrated circuit methodology and suitable processing and foundries.</li> <li>Candidate integrated circuit designs.</li> <li>Fabricated and tested candidate circuits.</li> <li>Demonstration in system testbed.</li> </ul>	<table border="1"> <thead> <tr> <th>YEAR</th> <th>Total \$/MYR</th> </tr> </thead> <tbody> <tr> <td>92</td> <td>2.0M</td> </tr> <tr> <td>93</td> <td>3.0M</td> </tr> <tr> <td>94</td> <td>3.0M</td> </tr> <tr> <td>95</td> <td>0.6M</td> </tr> <tr> <td>96</td> <td>1.8M</td> </tr> </tbody> </table>	YEAR	Total \$/MYR	92	2.0M	93	3.0M	94	3.0M	95	0.6M	96	1.8M	<table border="1"> <thead> <tr> <th>YEAR</th> <th>READINESS LEVEL</th> </tr> </thead> <tbody> <tr> <td>95</td> <td>8</td> </tr> <tr> <td>96</td> <td>6</td> </tr> <tr> <td>97</td> <td>4</td> </tr> <tr> <td>98</td> <td>2</td> </tr> <tr> <td>01</td> <td>1</td> </tr> <tr> <td>07</td> <td>1</td> </tr> </tbody> </table>	YEAR	READINESS LEVEL	95	8	96	6	97	4	98	2	01	1	07	1
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01	1																													
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## ADVANCED SENSOR CONCEPTS--SMART SENSORS

<p><b>SCOPE</b> DEVELOP SENSOR SYSTEMS AND PROCESSES TO TRANSFER SELECTED GROUND COMMAND FUNCTIONS TO ORBIT.</p> <p><b>OBJECTIVE</b></p> <ul style="list-style-type: none"> <li>• MISSION EXPANSION.</li> <li>• SYNERGISM WITHIN A MISSION.</li> <li>• GROUND COMMANDS TO ORBIT.</li> <li>• CAPTURE OF SHORT-TERM PHENOMENON.</li> </ul> <p><b>RATIONALE</b> PROVIDES REAL-TIME RESPONSE FOR DYNAMIC PROCESSES AND A GLOBAL CONTEXT FOR NARROW-FIELD-OF-VIEW, HIGH-RESOLUTION INSTRUMENTS.</p>	<p><b>APPROACH</b></p> <p>FUNCTIONALITY DEFINITIONS WITH MAN IN THE LOOP PROVIDE AN EARLY ENTRY INTO THIS TECHNOLOGY. MISSION GOALS, SYSTEM ARCHITECTURE, AND STATE-OF-THE-ART HARDWARE WILL DETERMINE THE FINAL ARCHITECTURE AND ALGORITHM DEVELOPMENT TO BE PURSUED UNDER THIS ELEMENT. RECONFIGURATION IS A TOOL TO ACHIEVE THE TECHNICAL OBJECTIVE OF THIS EFFORT.</p> <p><b>DELIVERABLES</b></p> <ol style="list-style-type: none"> <li>1. FUNCTIONALITY DEFINITIONS.</li> <li>2. ARCHITECTURE AND ALGORITHM DEFINITIONS.</li> <li>3. RECONFIGURATION METHODOLOGIES.</li> <li>4. DEMONSTRATIONS.</li> </ol>	<p><b>DEVELOPMENT PLAN</b></p> <table border="1"> <thead> <tr> <th>Year</th> <th>Budget (\$/MY)</th> </tr> </thead> <tbody> <tr> <td>1991</td> <td>\$0.5M</td> </tr> <tr> <td>1992</td> <td>\$1.0M</td> </tr> <tr> <td>1993</td> <td>\$1.0M</td> </tr> <tr> <td>1994</td> <td>\$1.0M</td> </tr> </tbody> </table>	Year	Budget (\$/MY)	1991	\$0.5M	1992	\$1.0M	1993	\$1.0M	1994	\$1.0M	<p><b>TECHNOLOGY ASSESSMENT</b></p> <p>WORKING AT READINESS LEVELS OF 2 THROUGH 5</p>
Year	Budget (\$/MY)												
1991	\$0.5M												
1992	\$1.0M												
1993	\$1.0M												
1994	\$1.0M												

LaRC GCTI Observation Technologies

1.4 Microwave Sensing

Technology	NASA GCTI WBS	Proposal funding requirements, millions of dollars					
		FY90	FY91	FY92	FY93	FY94	FY95
Precision membrane reflector	1.41		2.8	4.1	3.7	3.0	2.3
Distributed phased array	1.41		1.25	2.05	1.85	1.55	0.65
Large space antenna	1.41		0.95	1.8	1.35	0.50	0.30
Measurement/calibration	1.41	0.50	2.0	1.50	0.50	0.50	0.50
Electronically scanning	1.42		0.90	2.00	2.80	2.50	2.00
Characterization of reflector materials	1.42		0.20	0.40	0.40	0.10	0
RF interference rejection	1.42	0.40	0.40	0.60	0.90	1.20	0
Precision ranging radar			0.10	0.10	0.20	0.20	0
Totals		0.90	8.60	12.55	11.70	9.55	5.75

## PRECISION, MEMBRANE REFLECTOR ANTENNA TECHNOLOGY (<40 GHz)

T. CAMPBELL

**SCOPE** Evaluation and development of new and innovative antenna concepts such as mesh-deployables and work of Contraves and LeGard on inflatables should be continued and augmented with feed arrays for surface error compensation and rapid beam scanning. Also, the technology for calibration of electrically large antennas, including stable loads, splash plates to cold space, etc., and control and reference systems for pointing control of scanning antennas, needs to be developed.

### OBJECTIVES

Develop lightweight mesh deployable or inflatable antennas for frequencies below 40 GHz with diameters up to 100 m for Earth remote sensing. Provide means of calibrating radiometer systems involving large scanning antennas where variations in antenna properties (boresight, pattern shape, side lobe levels and directions) occur on significantly short time scales, and where many of the antenna properties lie outside the normal radiometer calibration loops.

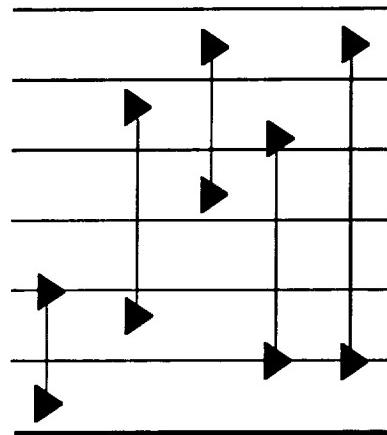
### RATIONALE

Precipitation, winds, soil moisture, and snow measurements require frequencies from 2-37 GHz with reflectors from 15-100 m. The low surface tolerances allow the use of mesh and inflatable reflector antennas. Size requires some sort of deployment. Adaptive RF surface distortion compensation techniques are required for onboard compensation of reflector surface errors. Development of new near field measurement techniques is mandatory to characterize the RF performance of these large antennas.

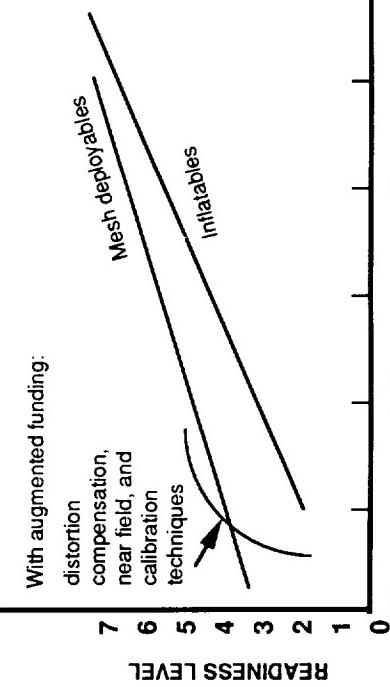
**APPROACH** Develop precision, membrane antenna technology. Develop accurate computer models of error sources involved in dynamic, on-orbit calibration of large antenna radiometer systems. Errors contributed by various possible methods of viewing cold space when the antenna cannot be slewed to view space directly.

### DELIVERABLES

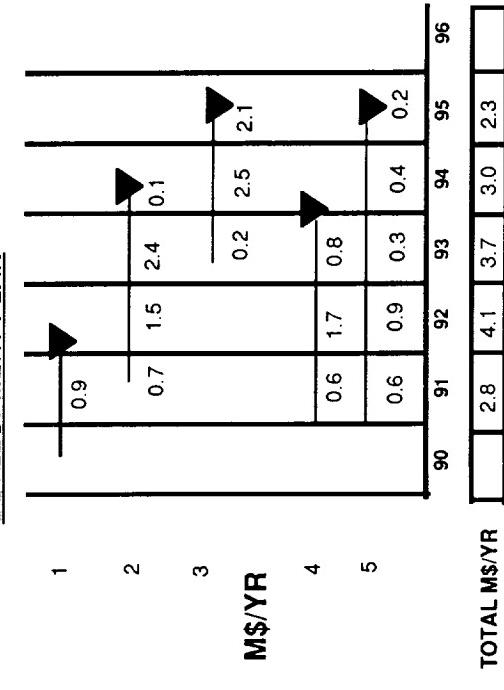
1. Study contracts - different concepts
2. Concept selection - development
3. Proof of concept demonstration
4. Distortion compensation technique (RF)
5. Near field measurement and calibration techniques



### TECHNOLOGY ASSESSMENT

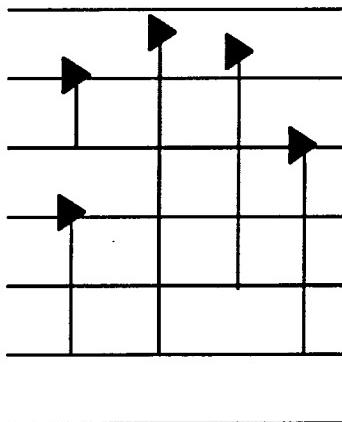
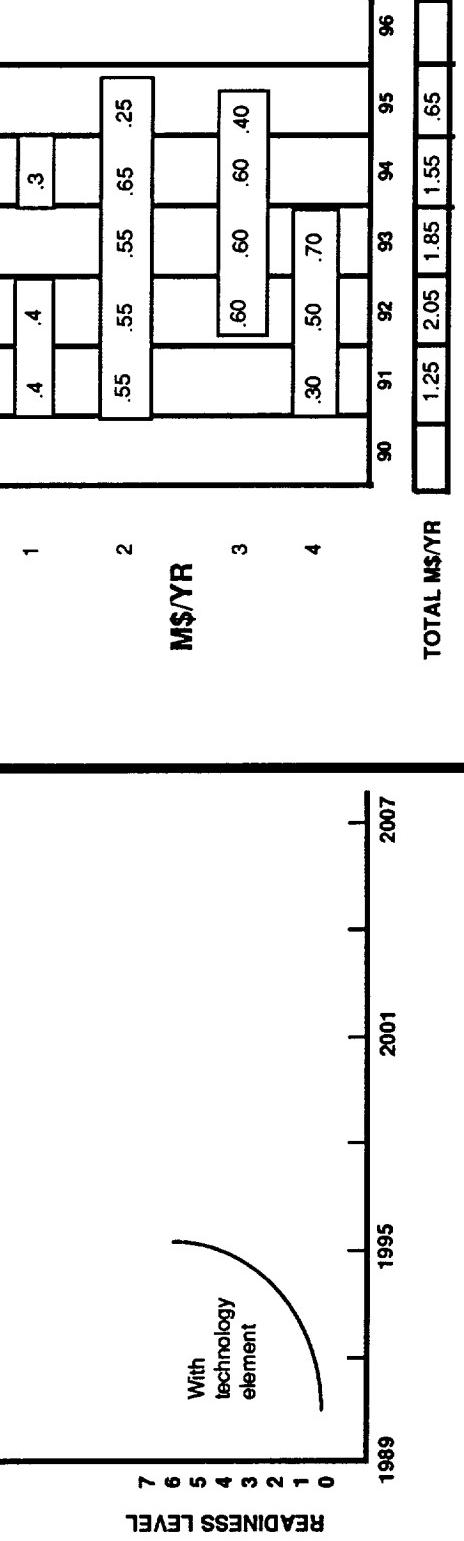


### DEVELOPMENT PLAN



## DISTRIBUTED PHASED ARRAY ANTENNA TECHNOLOGY (40-220 GHz)

T. CAMPBELL

<p><b>SCOPE</b> To demonstrate technology feasibility of large distributed phased array antennas for spaceborne radar applications for frequency range &gt;40 GHz.</p> <p><b>OBJECTIVES</b> Capabilities needed:</p> <ul style="list-style-type: none"> <li>- Large size (10-20 m long, 1-4 m wide)</li> <li>- Lightweight (&lt;1000 kg)</li> <li>- Maintaining aperture flatness of 0.08 cm at 35 GHz</li> <li>- Scan angle of 60°</li> <li>- Array surface distortion compensation techniques (RF)</li> <li>- Polarization purity of 25 to 30 dB</li> </ul> <p><b>RATIONALE</b></p> <p>Lighter and less power consuming, large distributed phased array antennas are needed at high frequencies in order to achieve adequate resolution for sufficiently large coverage areas. Currently, there are no phase array antennas larger than 3 meters at frequencies higher than X-band.</p>	<p><b>APPROACH</b> Extend Spaceborne Imaging Radar-C (SIR-C) capabilities to higher frequencies and higher resolutions.</p>  <p><b>DELIVERABLES</b></p> <ol style="list-style-type: none"> <li>1. Array system architecture/design.</li> <li>2. Radiator/subarray/beam-former technology</li> <li>3. Surface distortion compensation technique (RF).</li> <li>4. Antenna testing technique.</li> </ol>	<p><b>TECHNOLOGY ASSESSMENT</b></p>  <table border="1"> <thead> <tr> <th>Year</th> <th>1991</th> <th>92</th> <th>93</th> <th>94</th> <th>95</th> <th>96</th> <th>97</th> </tr> </thead> <tbody> <tr> <td>Total M\$YR</td> <td>1.25</td> <td>2.05</td> <td>1.85</td> <td>1.55</td> <td>.65</td> <td></td> <td></td> </tr> </tbody> </table> <p><b>DEVELOPMENT PLAN</b></p> <table border="1"> <thead> <tr> <th>Year</th> <th>1991</th> <th>92</th> <th>93</th> <th>94</th> <th>95</th> <th>96</th> <th>97</th> </tr> </thead> <tbody> <tr> <td>M\$YR</td> <td>.4</td> <td>.4</td> <td>.3</td> <td>.55</td> <td>.55</td> <td>.60</td> <td>.60</td> </tr> </tbody> </table>	Year	1991	92	93	94	95	96	97	Total M\$YR	1.25	2.05	1.85	1.55	.65			Year	1991	92	93	94	95	96	97	M\$YR	.4	.4	.3	.55	.55	.60	.60
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**LARGE SPACE ANTENNA END-TO-END THERMAL/MECHANICAL/ELECTROMAGNETIC COMPUTER  
MODELS FOR LARGE RADIOMETER ANTENNA SYSTEMS**

T. CAMPBELL

<p><b>SCOPE</b> To develop efficient electromagnetic and computational techniques for large radiometer system end-to-end computer models. This effort will include quasi-optical antenna configurations.</p> <p><b>OBJECTIVES</b></p> <ul style="list-style-type: none"> <li>- Multiple reflector system</li> <li>- Develop end-to-end thermal distortion models</li> <li>- Accurate performance prediction</li> <li>- Fast computing time</li> </ul> <p><b>RATIONALE</b></p> <p>Existing analytical and computational techniques using physical optics are too time consuming even using super computers, such as CRAY. Therefore improved computer models are required for future large radiometer systems.</p>	<p><b>APPROACH</b> Develop new analytical approach and adapt parallel processing techniques to expedite calculations.</p> <p><b>OBJECTIVES</b></p> <ol style="list-style-type: none"> <li>1) New analytical techniques</li> <li>2) Fast computational techniques</li> <li>3) Experimental verification of analysis and computational technique</li> </ol>	<p><b>TECHNOLOGY ASSESSMENT</b></p> <table border="1"> <thead> <tr> <th>YEAR</th> <th>READYNESS LEVEL</th> </tr> </thead> <tbody> <tr><td>1989</td><td>1</td></tr> <tr><td>2000</td><td>2</td></tr> <tr><td>2005</td><td>3</td></tr> <tr><td>2010</td><td>4</td></tr> <tr><td>2015</td><td>5</td></tr> <tr><td>2020</td><td>6</td></tr> <tr><td>2030</td><td>7</td></tr> </tbody> </table> <p><b>DEVELOPMENT PLAN</b></p> <table border="1"> <thead> <tr> <th>ITEM</th> <th>DURATION</th> <th>COST (\$M)</th> </tr> </thead> <tbody> <tr><td>1</td><td>.6</td><td>.3</td></tr> <tr><td>2</td><td>.35</td><td>.65</td></tr> <tr><td>3</td><td>.85</td><td>.5</td></tr> <tr><td><b>TOTAL M\$YR</b></td><td><b>.3</b></td><td><b>.96</b></td></tr> </tbody> </table>	YEAR	READYNESS LEVEL	1989	1	2000	2	2005	3	2010	4	2015	5	2020	6	2030	7	ITEM	DURATION	COST (\$M)	1	.6	.3	2	.35	.65	3	.85	.5	<b>TOTAL M\$YR</b>	<b>.3</b>	<b>.96</b>
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<b>TOTAL M\$YR</b>	<b>.3</b>	<b>.96</b>																															

## MEASUREMENT/CALIBRATION - LARGE SPACE ANTENNAS GROUND TEST METHODOLOGY

<u>SCOPE</u>	<u>APPROACH</u>															
Develop methodology for ground testing, characterization, and performance verification of large space antennas (LSA) for microwave remote sensing systems.	<p>Investigate feasibility of upgrading near-field test laboratory at Martin Marietta-Denver, Colorado (Largest NF-facility in USA) for millimeter wavelengths (<math>\sim 100</math> GHz) and provide advocacy for laboratory upgrade.</p> <p>Develop methodology for determining functional characteristics of integrated sensor/LSA system.</p>															
<u>DELIVERABLES</u>																
	<p>1) MMW-NF Design</p> <p>2) NF Development</p> <p>3) LSA- Sensor Measurement Concept</p> <p>4) Integrated Measurement System</p>															
<u>TECHNOLOGY ASSESSMENT</u>	<u>DEVELOPMENT PLAN</u>															
<p><b>OBJECTIVES</b></p> <p>Develop millimeter wavelength near field (MMW-NF) measurement techniques for measuring wide-scanning, large aperture, low side lobe antenna systems.</p> <p><b>RATIONALE</b></p> <p>Performance verification of high beam efficiency, wide-scanning antennas critical to microwave remote sensing systems, both passive and active.</p>	<table border="1"> <thead> <tr> <th>Phase</th> <th>Task</th> <th>Resource Allocation (M\$)</th> </tr> </thead> <tbody> <tr> <td>1</td> <td>Initial Planning</td> <td>.3</td> </tr> <tr> <td>2</td> <td>Design &amp; Development</td> <td>.8</td> </tr> <tr> <td>3</td> <td>Testing &amp; Validation</td> <td>.2</td> </tr> <tr> <td>4</td> <td>Final Integration</td> <td>.5</td> </tr> </tbody> </table> <p>TOTAL M\$ / YR: .5</p>	Phase	Task	Resource Allocation (M\$)	1	Initial Planning	.3	2	Design & Development	.8	3	Testing & Validation	.2	4	Final Integration	.5
Phase	Task	Resource Allocation (M\$)														
1	Initial Planning	.3														
2	Design & Development	.8														
3	Testing & Validation	.2														
4	Final Integration	.5														

# ELECTRONICALLY SCANNING FEED TECHNIQUES FOR FILLED APERTURE MICROWAVE RADIOMETER

## SCOPE

Space-qualified microwave/millimeter wave radiometers which are small, lightweight, low loss and reliable are required for application in observation of Earth geophysical and atmospheric parameters. Develop electronically scanned phasing networks for precision radiometer applications and study these array techniques for rapid wide angle scanning.

## OBJECTIVES

- Develop monolithic microwave integrated circuit (MMIC) front-end radiometer subsystem technology to support

- Reduce effects of varying parameters of combiner networks due to

## RATIONALE

- Earth observation radiometer systems will be used in multiple numbers as part of large space antenna feed systems. Therefore,

- they must be small, lightweight, and efficient to reduce antenna shadowing and excessive power consumption.

- Electronic scanning likely will be required to obtain desired large coverage for large apertures.

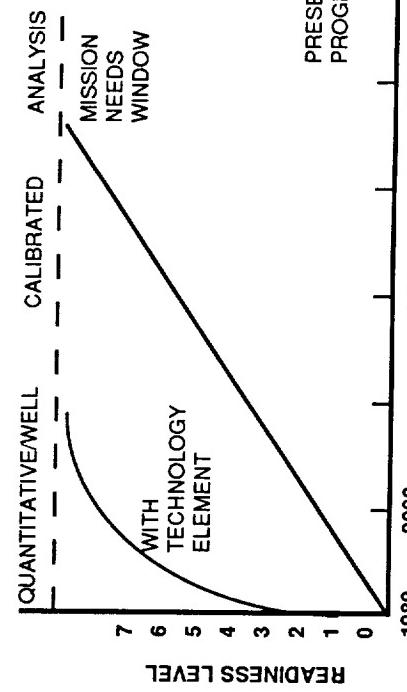
## APPROACH

Study techniques to integrate portions of the radiometer system or feed networks to improve radiometer performance. Model effects of variations due to phase shifters on radiometer performance. Develop integrated radiometer front-end, phase shifters, combiners, etc., specifically for radiometer applications. Determine possibility of semiconductor application. Study a large array for soil monitor mapping.

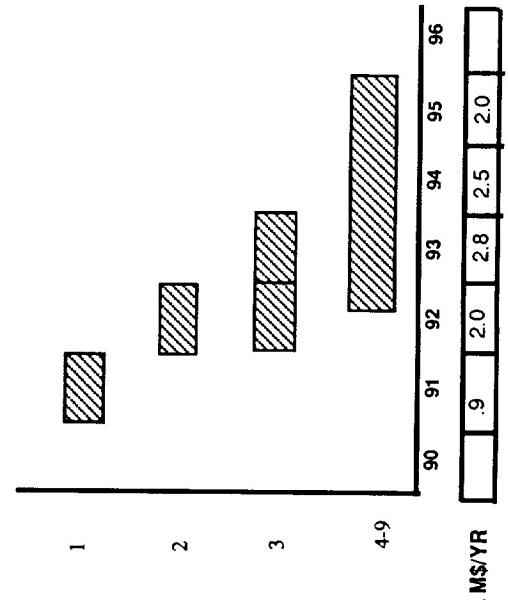
## DELIVERABLES

- (1) System performance trade-off reports.
- (2) Design study reports.
- (3) Computer-aided design software.
- (4) Demonstrate 60 GHz unit.
- (5) Test and validate report.
- (6) 118 GHz MMIC low-noise amplifier.
- (7) 220 GHz MMIC low-noise amplifier.
- (8) Prototype radiometer front-end phasing network. Low frequency parameters.
- (9) Identify technology question for higher frequency applications.

## TECHNOLOGY ASSESSMENT



## DEVELOPMENT PLAN



T. CAMPBELL

**CHARACTERIZATION OF REFLECTOR MATERIALS FOR RADIOMETER APPLICATIONS**

**SCOPE**

The performance of radiometer systems employing mesh antenna systems is strongly dependent on material properties of the mesh and detailed radiometric properties of the mesh and mesh structure.

**OBJECTIVES**

Characterize the radiometric performance and long-term stability of mesh antenna system for 1 - 37 GHz, and determine the impact on overall radiometer system performance.

**RATIONALE**

Mesh antenna systems are under consideration for radiometer application for 1 - 37 GHz. To determine overall radiometric system performance, it is essential to completely characterize the effects of the mesh.

**APPROACH**

Using existing radiometric mesh measurement systems and developing new measurement systems and test procedures, characterize the radiometric properties of typical mesh material.

Using these results, model the effect of mesh antenna on overall radiometer system performance.

Identify techniques to minimize adverse effects of mesh performance or changes in performance (aging) on overall radiometer system performance.

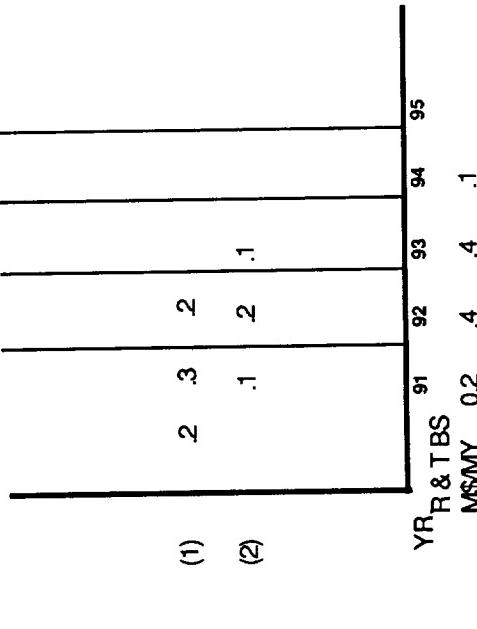
**DELIVERABLES**

- (1) Radiometric mesh measurement system.
- (2) Study report modeling effects of mesh antenna on radiometer system performance and indicating improvements possible.

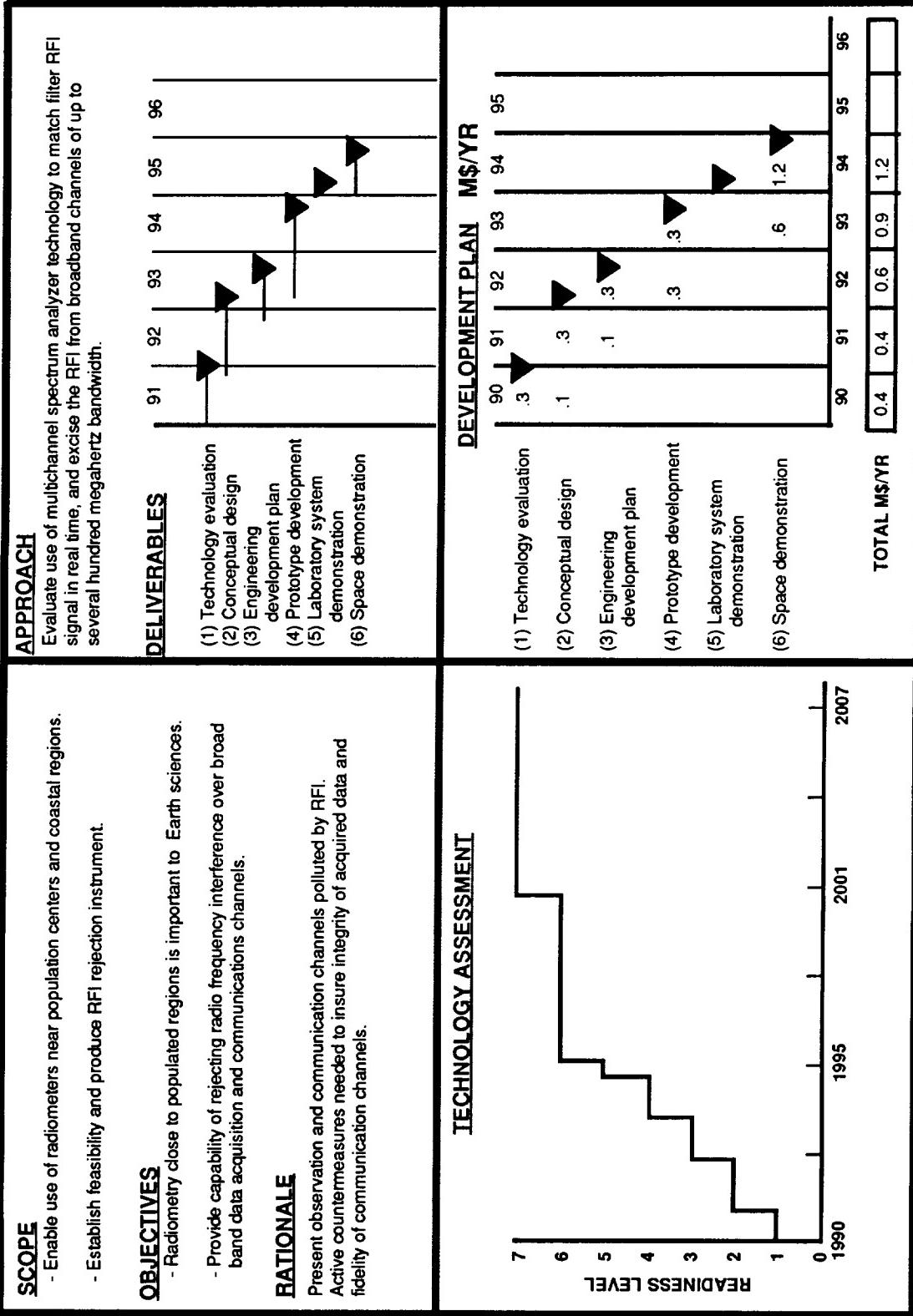
**TECHNOLOGY ASSESSMENT**



**DEVELOPMENT PLAN**



## RADIO FREQUENCY INTERFERENCE (RFI) REJECTION TECHNOLOGY FOR RADIOMETER APPLICATIONS



## Precision Ranging Radar

**SCOPE**  
DEVELOP A PULSED PHASE LOCK LOOP SYSTEM FOR RADAR  
RANGING OF CLOUD TOPS FROM SATELLITES.

### OBJECTIVE

- IMPROVE RADAR RANGING METHODS FROM DIFFICULT REFLECTION SYSTEMS.

### RATIONALE

- SOME RADAR REFLECTION SYSTEMS HAVE TROUBLE RANGING TO CLOUD TOPS THAT ARE POOR REFLECTORS.
- A PHASE SENSITIVE MEASUREMENT SYSTEM THAT IS LESS DEPENDENT ON AMPLITUDE VARIATIONS CAN BE MORE SENSITIVE.
- WE HAVE SUCCESSFULLY DEMONSTRATED THIS TECHNOLOGY FOR OPTICAL, ELECTROMAGNETIC, AND ULTRASONIC APPLICATIONS.

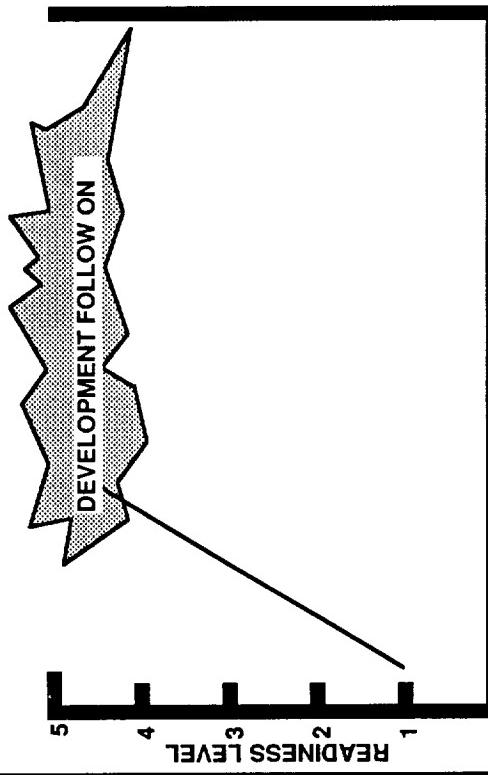
**APPROACH**

- CONSTRUCT A RADAR FREQUENCY PULSE PHASE LOCK LOOP SYSTEM.
- EVALUATE THE SYSTEM FROM A GROUND-BASED SYSTEM.

### DELIVERABLES

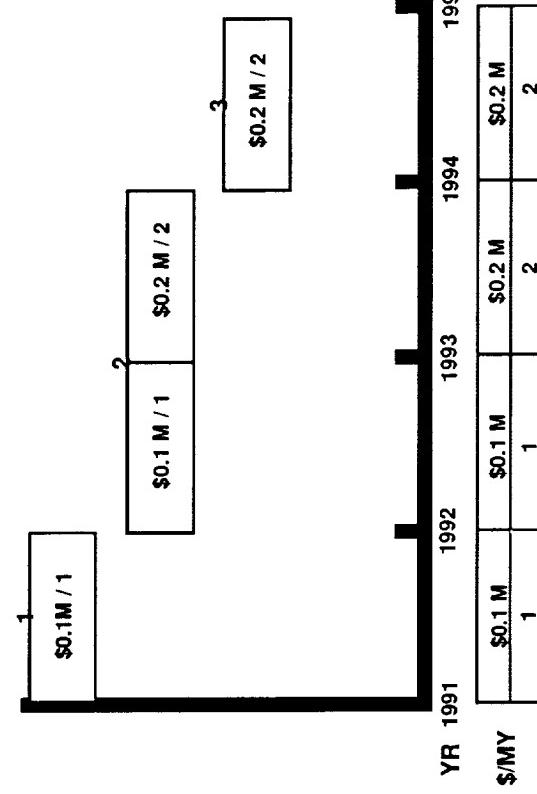
1. DEVELOPMENT OF TECHNOLOGY FOR RADAR SYSTEM.
2. DEVELOPMENT OF RADAR PULSED PHASE LOCK LOOP LAB SYSTEM.
3. EVALUATION OF SYSTEM.

### TECHNOLOGY ASSESSMENT



1990 1995 2000 2005 2010  
YEAR  
WORKING AT READINESS LEVELS OF 2 THROUGH 5

### DEVELOPMENT PLAN



## LaRC GCTI Observation Technologies

### 1.5 Optics

Technology	NASA GCTI WBS	Proposal funding requirements, millions of dollars					
		FY90	FY91	FY92	FY93	FY94	FY95
Radiation tolerant materials	1.51	0.2	0.3	0.6	0.5	0.4	0.1
Contamination	1.51	0.2	0.25	0.3	0.2	0.1	
Cryogenic materials	1.51	0.1	0.15	0.55	0.75	0.25	
Optics/thermal/control/structure interaction	1.52		0.15	0.3	0.4	0.25	
Unwanted radiation	1.52	0.2	0.4	0.5	0.5	0.2	0.2
Lightweight optics	1.53		0.75	1.0	3.0	2.5	
Ultrastable optical mounts	1.53		0.25	0.35	0.45	0.40	0.30
Microlens technology	1.53	0.15	0.3	0.4	0.5	0.1	
Active cavity radiometer		0.125	0.125	0.2	0.2	0.5	0.5
Totals		0.975	2.675	4.2	6.5	4.70	1.10

## RADIATION TOLERANT MATERIALS

**SCOPE**  
DEVELOP HIGHLY REFLECTIVE, BROAD SPECTRAL BAND DIELECTRIC OPTICAL COATINGS WHICH ARE HIGHLY RESISTANT TO ELECTROMAGNETIC AND PARTICLE RADIATION.

**OBJECTIVE**

DEVELOP OPTICAL COATINGS THAT CAN BE USED FOR LONG DURATION SPACE APPLICATIONS. THESE COATINGS WILL BE USED ON INTERNAL ELEMENTS OF HIGH ENERGY LASER SYSTEMS AND ON OPTICAL ELEMENTS EXPOSED TO SPACE RADIATION, INCLUDING SOLAR ULTRAVIOLET.

**RATIONALE**

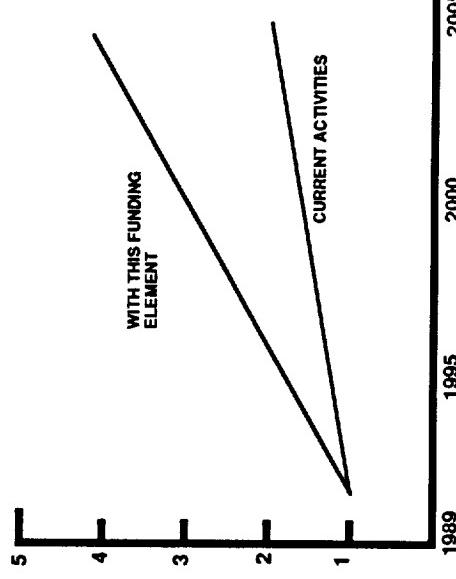
PRESENT OPTICAL COATINGS SUFFER FROM RADIATION DAMAGE IN HIGH ENERGY LASER SYSTEMS RESULTING IN DEGRADED PERFORMANCE AND DAMAGE TO SUBSTRATE MATERIALS. LONG-TERM MISSIONS REQUIRE HIGH INTEGRITY OPTICAL SYSTEMS WHOSE FRONT END ELEMENTS ARE NOT DEGRADED WHEN EXPOSED TO CONTINUOUS HIGH ENERGY PARTICLE AND UV BOMBARDMENT.

**APPROACH**  
EXAMINE METHODS AND MATERIALS OF DEPOSITING COATINGS, E.G., DIAMOND-LIKE MATERIALS, WHICH DEMONSTRATE HIGH RADIATION RESISTANCE. DEVELOP MATERIAL COMBINATIONS WHICH PERMIT BROADENING SPECTRAL RANGE. ESTABLISH EXPERIMENTAL PROGRAM TO DEFINE RADIATION DAMAGE PROPERTIES.

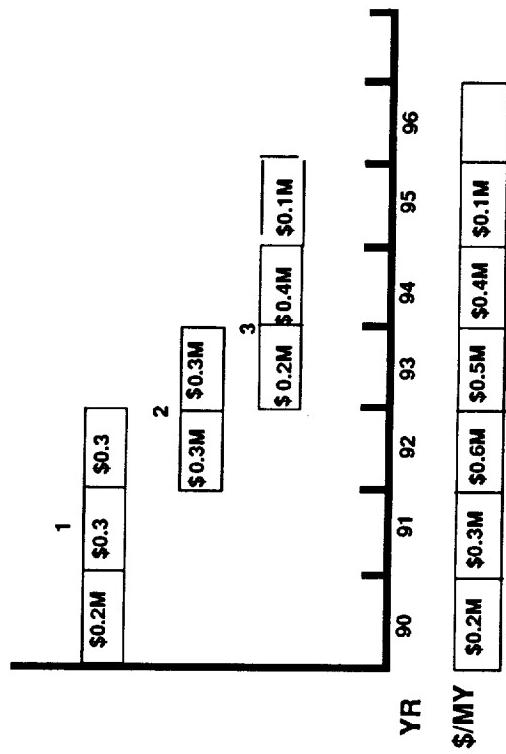
**DELIVERABLES**

1. DEVELOP COATING MATERIAL AND COATING PROCESSES WHICH SURVIVE MULTIGIGAWATT INCIDENT RADIATION IN THE UV AND NEAR-UV SPECTRAL RANGE.
2. DEMONSTRATE APPLICABILITY OF COATINGS TO BROAD SPECTRAL BAND COVERAGE.
3. DEMONSTRATE PERFORMANCE OF THESE COATINGS FOR SPACE-BASED LASER AND OPTICAL COMPONENT USE.

## TECHNOLOGY ASSESSMENT



## DEVELOPMENT PLAN



# CONTAMINATION

J. GOAD

<b>SCOPE</b>	<p><b>APPROACH</b></p> <p>A PUBLICATION AND INDUSTRIAL SURVEY WILL BE CONDUCTED TO COMPARE THE ADVANTAGES AND DISADVANTAGES OF AVAILABLE METHODS. ONCE DEFINED, A TWO-LEVEL ANALYSIS WILL BE DEVELOPED TO ASSESS PERFORMANCE. THIS ANALYSIS WILL BE VERIFIED BY EXPERIMENT. NEW NONCONTACT CLEANING METHODS WILL BE DEVELOPED.</p>															
<b>OBJECTIVE</b>	<p>THE OBJECTIVES OF THIS PROGRAM ARE TO MODEL, DEVELOP, TEST, AND INTEGRATE ANALYSIS AND EXPERIMENTAL TECHNIQUES TO EVALUATE IMAGE AND/OR OPTICAL PERFORMANCE DEGRADATION FROM CONTAMINATION.</p> <p><b>RATIONALE</b></p> <p>HIGHER RESOLUTION DATA FROM INFRARED DETECTION SYSTEMS AND THE REQUIREMENTS OF COHERENT DETECTION OF LASER SIGNALS, AS IN LIDAR, OR IN SCANNING LIDAR, DEMAND BETTER PERFORMANCE FROM THE GEOMETRIC SYSTEM THAT COMPRIMES THE OPTICS. THIS WORK IS REQUIRED TO IMPROVE THEIR DESIGN EASE, ANALYSIS, PERFORMANCE, AND LIFETIMES. UNDERSTANDING OF PERFORMANCE DEGRADATION AND LIFETIMES DUE TO CONTAMINATION SIGNIFICANTLY IMPROVES THE PREDICTABILITY OF OPTICAL SYSTEMS PERFORMANCE.</p>															
<b>DELIVERABLES</b>	<ol style="list-style-type: none"> <li>1. MATERIALS RESOURCE CATALOG.</li> <li>2. TWO-LEVEL ANALYSIS.</li> <li>3. EXPERIMENTAL RESULTS.</li> <li>4. DEVELOPMENT OF CLEANING AND/OR CORRECTION TECHNIQUES.</li> </ol>															
<p><b>TECHNOLOGY ASSESSMENT</b></p> <p><b>DEVELOPMENT PLAN</b></p> <table border="1"> <thead> <tr> <th>YR</th> <th>\$/MY</th> </tr> </thead> <tbody> <tr> <td>90</td> <td>\$0.2M</td> </tr> <tr> <td>91</td> <td>\$0.25M</td> </tr> <tr> <td>92</td> <td>\$0.3M</td> </tr> <tr> <td>93</td> <td>\$0.3M</td> </tr> <tr> <td>94</td> <td>\$0.3</td> </tr> <tr> <td>95</td> <td>\$0.3</td> </tr> <tr> <td>96</td> <td>\$0.1M</td> </tr> </tbody> </table> <p>LaRC</p>	YR	\$/MY	90	\$0.2M	91	\$0.25M	92	\$0.3M	93	\$0.3M	94	\$0.3	95	\$0.3	96	\$0.1M
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# CRYOGENIC OPTICAL MATERIALS

<p><b>SCOPE</b></p> <p>OPTICAL SYSTEMS OPERATING IN CRYOGENIC ENVIRONMENTS REQUIRE STABLE OPTICAL MATERIALS. THIS WILL INCLUDE THE DEVELOPMENT OF SPECIAL MATERIALS AND MANUFACTURING PROCESSES.</p> <p><b>OBJECTIVE</b></p> <p>THE OBJECTIVES OF THIS PROGRAM ARE TO PROVIDE A BASELINE SET OF PRODUCTS THAT WILL SUPPLY THE BROAD NEEDS OF THE OPTICAL SYSTEMS OF THE 1994 ERA. FROM THIS BASELINE SET OF MATERIALS, OPTICAL SYSTEMS, AND MANUFACTURING PROCESSES, NEW CRYOGENIC OPTICAL INSTRUMENTATION SYSTEMS WILL BE DEVELOPED.</p>	<p><b>APPROACH</b></p> <p>DEVELOP A MATERIALS RESOURCE CATALOG FOR CRYOGENIC OPTICAL MATERIALS. THIS CATALOG WILL BE REVIEWED TO ESTABLISH THE REQUIREMENTS FOR NEW MATERIALS. DEVELOPMENT OF NEW MATERIALS WILL BE INITIATED AND A TEST PROGRAM COMPLETED.</p>																						
<p><b>RATIONALE</b></p> <p>HIGHER RESOLUTION DATA FROM INFRARED DETECTION SYSTEMS AND THE REQUIREMENTS OF COHERENT DETECTION OF LASER SIGNALS, AS IN LIDAR, OR IN SCANNING LIDAR, DEMAND BETTER PERFORMANCE FROM THE GEOMETRIC SYSTEM THAT COMPRISES THE OPTICS. THIS WORK IS REQUIRED TO IMPROVE THEIR DESIGN EASE, ANALYSIS, PERFORMANCE, AND LIFETIMES.</p>	<p><b>DELIVERABLES</b></p> <ol style="list-style-type: none"> <li>1. MATERIALS RESOURCE CATALOG.</li> <li>2. REQUIREMENTS FOR NEW MATERIALS.</li> <li>3. DEVELOP NEW MATERIALS.</li> <li>4. TEST PROPERTIES OF NEW MATERIALS.</li> </ol>																						
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## OPTICS-THERMAL-CONTROL-STRUCTURES INTERACTION

<p><b>SCOPE</b> Develop integrated thermal-structural-control-optical analysis capability for space instrument applications.</p> <p><b>OBJECTIVE</b> Develop an integrated analysis tool for evaluating optical system performance with thermal and structural disturbances (including adaptive systems).</p> <p><b>RATIONALE</b></p> <ul style="list-style-type: none"> <li>With increased optical beam stability requirements, a tool is necessary to assure performance over representative thermal and dynamic environments.</li> <li>Tools required to efficiently evaluate and integrate the design of precision optical systems as well as entire optical experiments. With long-life missions (active cooling), larger flexible platforms (structural coupling), and higher orbits (better stability), analysis tools are required to evaluate disturbance effects.</li> <li>Analysis tools are needed to evaluate the optical system performance with adaptive optical elements.</li> </ul>	<p><b>APPROACH</b> Review existing candidate analysis codes in each discipline and select the most compatible.</p> <p>Develop the selected codes into an integrated tool and demonstrate its capability.</p> <p>Provide technology to industry to market.</p>	<p><b>DELIVERABLES/MILESTONES</b></p> <ol style="list-style-type: none"> <li>Selection of compatible codes.</li> <li>Development of interfaces and data bases necessary to integrate codes.</li> <li>Demonstration of integrated analysis capability.</li> </ol>	<p><b>DEVELOPMENT PLAN</b></p> <table border="1"> <thead> <tr> <th>FY</th> <th>91</th> <th>92</th> <th>93</th> <th>94</th> <th>95</th> </tr> </thead> <tbody> <tr> <td>TOTALS</td> <td>\$150K</td> <td>\$300K</td> <td>\$400K</td> <td>\$250K</td> <td></td> </tr> </tbody> </table>	FY	91	92	93	94	95	TOTALS	\$150K	\$300K	\$400K	\$250K	
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## UNWANTED RADIATION (SCATTERED THERMAL)

<p><b>SCOPE</b> DEVELOP MODELING AND DESIGN PROCESSES TO PREDICT THERMAL INFRARED SYSTEM PERFORMANCE</p> <p><b>OBJECTIVE</b> CREATE AN ANALYTICAL TOOL FOR THE OPTICAL DESIGN AND OPTIMIZATION OF THERMAL INFRARED SYSTEMS FOR REMOTE SENSING SYSTEMS IN THE INFRARED (IR) REGION OF THE SPECTRUM. MODEL THERMAL IR BACKGROUND SIGNAL, ATMOSPHERIC TRANSMISSION, AND PROPAGATION THROUGH THE OPTICAL SYSTEM.</p> <p><b>RATIONALE</b> THERMAL IMAGING IS USED FOR MEASURING GLOBAL WARMING TRENDS, GREENHOUSE GASES, AND EVAPOTRANSPIRATION. THERMAL BACKGROUND CHARACTERISTICS BECOME MORE CRITICAL WITH INCREASING INTEREST TOWARD USING IR MATERIALS AT HIGHER OPERATING TEMPERATURES. THESE IMPROVEMENTS YIELD BETTER INFORMATION ON THE OPTIMUM PERFORMANCE, SENSITIVITY, DURABILITY, AND UNIFORMITY OF OPTICAL MATERIAL AND DETECTOR ARRAYS. THIS WORK PROVIDES SIGNIFICANT NEW SCIENTIFIC INFORMATION IN THE THERMAL IR AT LOWER DETECTABLE LEVELS AND BETTER PRECISION.</p>	<p><b>APPROACH</b> DEVELOP COMPUTER-AIDED DESIGN (CAD) SOFTWARE FOR THE ANALYSIS AND OPTIMIZATION OF THERMAL INFRARED SYSTEMS. ADEQUATELY MODEL THERMAL CHARACTERISTICS WITHIN THE SENSOR AND QUANTIFY NOISE TERMS FROM EACH COMPONENT. USE THE DEVELOPED MODEL AS A DESIGN AND ANALYSIS TOOL TO SIMULATE SYSTEM CHARACTERISTICS, QUANTIFY SYSTEM BACKGROUND NOISE AS A FUNCTION OF TEMPERATURE, PERFORM LABORATORY MEASUREMENTS TO VERIFY THE ACCURACY OF THE SOFTWARE.</p>	<p><b>DELIVERABLES</b></p> <ol style="list-style-type: none"> <li>1. DEVELOP CAD ANALYSIS FOR THERMAL IR SYSTEMS.</li> <li>2. MODEL SENSORS AND QUANTIFY NOISE TERMS.</li> <li>3. MODEL SYSTEM CHARACTERISTICS.</li> <li>4. PERFORM LABORATORY MEASUREMENTS TO VERIFY MODEL PREDICTIONS.</li> </ol>	<p><b>TECHNOLOGY ASSESSMENT</b></p> <p>The graph plots 'PRESENT TRENDS' against time. The vertical axis ranges from 1 to 5, and the horizontal axis shows years from 1990 to 2002. A curve starts at (1990, 1), rises to (1994, 4), and then plateaus at a value of 4 until 2002. An arrow points from the curve to the text 'PRODUCTS OF THIS INITIATIVE'.</p>	<p><b>DEVELOPMENT PLAN</b></p> <p>The graph plots '\$/MY' (millions of dollars per year) against time. The vertical axis ranges from \$0.2M to \$0.5M, and the horizontal axis shows years from 1990 to 1996. Four phases are shown: Phase 1 (1990-1991) with budget \$0.2M; Phase 2 (1991-1992) with budget \$0.4M; Phase 3 (1992-1993) with budget \$0.5M; Phase 4 (1993-1994) with budget \$0.2M; Phase 5 (1994-1995) with budget \$0.2M; Phase 6 (1995-1996) with budget \$0.2M. The LRC logo is in the bottom right corner.</p> <table border="1"> <thead> <tr> <th>YR</th> <th>\$/MY</th> </tr> </thead> <tbody> <tr><td>90</td><td>\$0.2M</td></tr> <tr><td>91</td><td>\$0.4M</td></tr> <tr><td>92</td><td>\$0.5M</td></tr> <tr><td>93</td><td>\$0.5M</td></tr> <tr><td>94</td><td>\$0.2M</td></tr> <tr><td>95</td><td>\$0.2M</td></tr> <tr><td>96</td><td>\$0.2M</td></tr> </tbody> </table>	YR	\$/MY	90	\$0.2M	91	\$0.4M	92	\$0.5M	93	\$0.5M	94	\$0.2M	95	\$0.2M	96	\$0.2M
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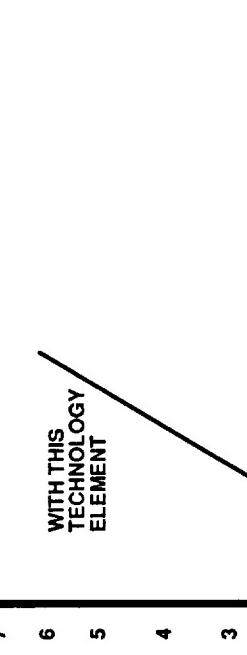
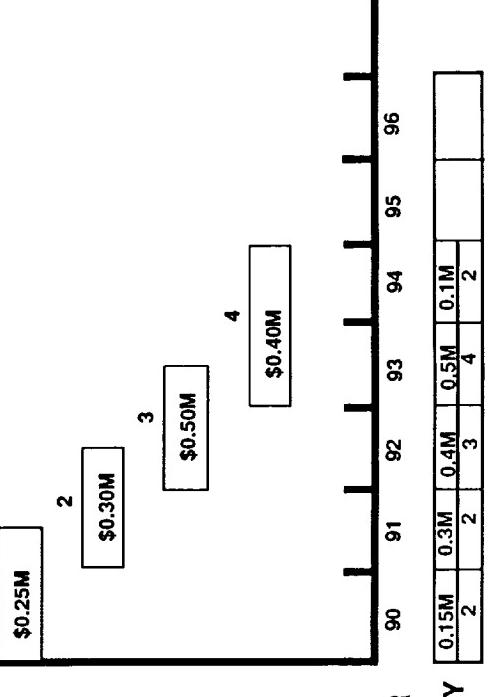
## LIGHTWEIGHT OPTICS

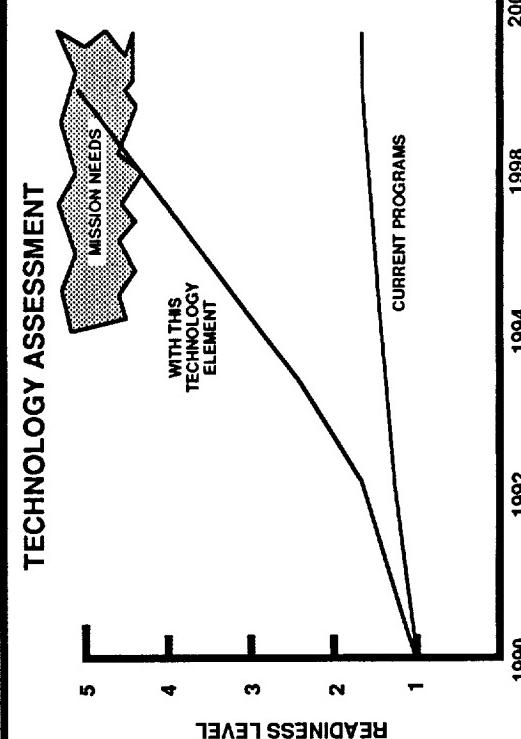
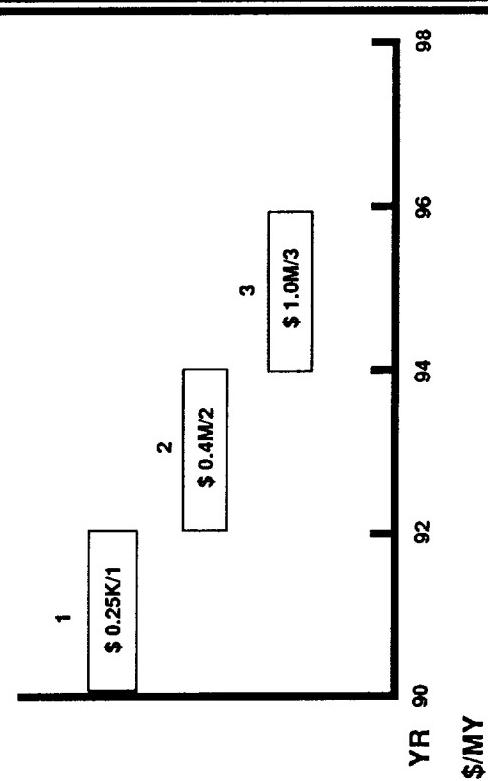
<p><b>SCOPE</b> Develop and demonstrate technology for lightweight and low cost optical systems for spaceflight instrument systems.</p> <p><b>OBJECTIVES</b> Enable large precision optical systems for spaceflight lidar and infrared systems, including the expanded use of scanning and pointing systems for large systems.</p> <p><b>RATIONALE</b> Many instrument concepts are seriously constrained by the mass and cost of large-scale optical systems.</p> <p>The performance and operational capabilities of lidar systems are seriously constrained by the mass and cost of current optical technology for return-signal systems.</p> <p>DOD research and technology programs are rapidly evolving materials and manufacturing technologies for lightweight optical systems.</p>	<p><b>APPROACH</b> Maintain NASA funding of selected technology efforts.</p> <p>Develop a concept for an initial target application, potentially lidar in-space technology experiment (LITE).</p> <p>Develop and conduct test bed demonstration of lightweight optical system on laser atmospheric sounding experiment (LASE) or LITE.</p>	<p><b>DELIVERABLES</b></p> <ol style="list-style-type: none"> <li>1. Evaluation of candidate technologies under lidar and infrared operating conditions.</li> <li>2. Development of design for test bed application.</li> <li>3. Development, test, and application of test bed system (optical system development cost only).</li> </ol> <p><b>TECHNOLOGY ASSESSMENT</b></p> <table border="1"> <thead> <tr> <th>Year</th> <th>Without GCTI Funding</th> <th>With GCTI Funding</th> </tr> </thead> <tbody> <tr> <td>1989</td> <td>1</td> <td>1</td> </tr> <tr> <td>1995</td> <td>2</td> <td>5</td> </tr> <tr> <td>2000</td> <td>2</td> <td>5</td> </tr> </tbody> </table> <p>WORKING AT READINESS LEVELS OF 2 THROUGH 5</p>	Year	Without GCTI Funding	With GCTI Funding	1989	1	1	1995	2	5	2000	2	5						
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## ULTRASTABLE OPTICAL MOUNTS AND BENCH

<p><b>SCOPE</b></p> <p>Develop ultrastable optical bench and mounts for space applications.</p> <p><b>OBJECTIVES</b></p> <p>Develop lightweight optical mount and bench for application to remote sensing instruments.</p> <p>Maintenance of optical beam stability under representative thermal and dynamic environments.</p> <p><b>RATIONALE</b></p> <p>Future missions need ultrastable optical systems for achieving measurement accuracy and spatial and temporal resolution. Development of thermally stable and vibration-resistant mounts and benches will permit accommodation of long-life missions that have inherent disturbance sources.</p>	<p><b>APPROACH</b></p> <p>Review candidate advanced materials and structural concepts.</p> <p>Develop the most promising concepts and demonstrate hardware performance under simulated space environments.</p>	<p><b>DELIVERABLES/MILESTONES</b></p> <ol style="list-style-type: none"> <li>1. Select candidate materials and identify candidate design concepts.</li> <li>2. Select most promising concept.</li> <li>3. Complete detailed design of concept.</li> <li>4. Complete fabrication of concept hardware.</li> <li>5. Demonstrate stability in thermal/vacuum environment.</li> </ol>	<p><b>DEVELOPMENT PLAN</b></p> <table border="1"> <thead> <tr> <th>FY</th> <th>91</th> <th>92</th> <th>93</th> <th>94</th> <th>95</th> </tr> </thead> <tbody> <tr> <td>\$250K</td> <td>\$350K</td> <td>\$450K</td> <td>\$400K</td> <td>\$300K</td> </tr> </tbody> </table>	FY	91	92	93	94	95	\$250K	\$350K	\$450K	\$400K	\$300K
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## ADVANCED SENSOR CONCEPTS--MICROLENS TECHNOLOGY FOR PUMPING SOLID-STATE LASERS

<b>SCOPE</b> DEVELOP MICROLENS TECHNOLOGY TO PROVIDE EFFICIENT OPTICAL MATCHING AND IMPROVED COOLING OF LASER DIODES USED TO PUMP SOLID-STATE LASER MATERIALS.  <b>OBJECTIVE</b> TO PUMP SOLID-STATE LASER MATERIALS, LASER DIODE PUMPING CAN PROVIDE LONG LIFETIMES AND HIGH EFFICIENCY TUNABLE LASERS NEEDED FOR SPACECRAFT APPLICATIONS.	<b>APPROACH</b> OPTICAL DESIGN PROGRAMS AND THERMAL COOLING MODELS WILL BE USED TO PREDICT THE BEST DESIGNS. THESE DESIGNS WILL BE BREADBOARDED FOR MODEL VALIDATION. ONCE VALIDATED, A PROTOTYPE LASER SYSTEM WILL BE DEVELOPED.	<b>DELIVERABLES</b> 1. OPTICAL DESIGN AND THERMAL MODELING 2. BREADBOARD DESIGN 3. BREADBOARD LABORATORY VALIDATION 4. PROTOTYPE TECHNOLOGY DEMONSTRATION															
<b>RATIONALE</b> PROPER OPTICAL MATCHING WITH MICROLENS TECHNOLOGY WILL PROVIDE MORE EFFICIENT PUMP COOLING FOR SOLID-STATE MATERIALS AND ALLOW MORE EFFICIENT COOLING OF THE LASER DIODE PUMPS.	<b>TECHNOLOGY ASSESSMENT</b>  <b>DEVELOPMENT PLAN</b>  <table border="1"> <thead> <tr> <th>YR</th> <th>\$/MY</th> </tr> </thead> <tbody> <tr> <td>90</td> <td>0.15M</td> </tr> <tr> <td>91</td> <td>0.3M</td> </tr> <tr> <td>92</td> <td>0.4M</td> </tr> <tr> <td>93</td> <td>0.5M</td> </tr> <tr> <td>94</td> <td>0.1M</td> </tr> <tr> <td>95</td> <td>0.2</td> </tr> <tr> <td>96</td> <td></td> </tr> </tbody> </table>	YR	\$/MY	90	0.15M	91	0.3M	92	0.4M	93	0.5M	94	0.1M	95	0.2	96	
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ADVANCED SENSOR CONCEPTS-CRYOGENIC ACTIVE CAVITY RADIOMETER TECHNOLOGY																			
<b>SCOPE</b> DEVELOP A HIGH-SENSITIVITY, NARROW-FIELD-OF-VIEW ABSOLUTE RADIOMETER CAPABLE OF BEING USED AS EARTH RADIANCE SENSOR.	<b>APPROACH</b> EXPAND PRESENT INVESTIGATIONS TO INCLUDE SCANNING AND/OR ARRAY TECHNIQUES FOR THE PACKAGING OF CRYOGENICALLY COOLED ACTIVE CAVITY RADIOMETER. DETERMINE THE THERMAL, CALIBRATION, AND OPERATIONAL CONSTRAINTS AND INTERFACE RESTRICTIONS FOR SUCH A SYSTEM COMPATIBLE WITH CLIMATE MODELING REQUIREMENTS. REDUCE TIME CONSTANT, INCREASE SENSITIVITY AND THE FIELD OF VIEW, AND IMPROVE IMAGE FORMATS.																		
<b>OBJECTIVE</b> PRODUCE HIGHLY ACCURATE, LOW RESOLUTION RADIANCE IMAGERY OF THE EMITTED AND REFLECTED RADIATION FROM THE EARTH FOR CLIMATE STUDIES AND GLOBAL CIRCULATION APPLICATIONS.	<b>DELIVERABLES</b> 1. PACKAGING REQUIREMENTS OF SENSOR (MULTIELEMENT SENSOR ARRAY VS. SINGLE ELEMENT SCANNING DEVICE) 2. THERMAL AND OPERATIONAL RESTRICTIONS (INCLUDING CALIBRATION) OF CRYOGENICALLY COOLED CAVITY RADIOMETER. 3. PROTOTYPE SYSTEM TO DEMONSTRATE FEASIBILITY.																		
<b>RATIONALE</b> PRESENT ABSOLUTE RADIOMETRY INVOLVES THE USE OF ACTIVE CAVITY RADIOMETERS HAVING LONG RESPONSE TIME AND LOW SENSITIVITY. THE USE OF A DEVICE OF THIS TYPE FOR NARROW FIELD, EARTH-VIEWING APPLICATIONS (WHETHER SCANNING OR STARING ARRAY) REQUIRES THAT THE DEVICE(S) BE COOLED TO LIQUID HELIUM TEMPERATURES TO OBTAIN THE REQUISITE OPERATIONAL CHARACTERISTICS.	<b>TECHNOLOGY ASSESSMENT</b>  <table border="1"> <caption>Technology Readiness Assessment Data</caption> <thead> <tr> <th>Year</th> <th>Readiness Level (Current Programs)</th> <th>Readiness Level (With Technology Element)</th> </tr> </thead> <tbody> <tr> <td>1990</td> <td>1</td> <td>1</td> </tr> <tr> <td>1992</td> <td>2</td> <td>4</td> </tr> <tr> <td>1994</td> <td>3</td> <td>5</td> </tr> <tr> <td>1996</td> <td>4</td> <td>5</td> </tr> <tr> <td>1998</td> <td>5</td> <td>5</td> </tr> </tbody> </table>	Year	Readiness Level (Current Programs)	Readiness Level (With Technology Element)	1990	1	1	1992	2	4	1994	3	5	1996	4	5	1998	5	5
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LaRC GCTI Observation Technologies

1.6 Pointing and Control

Technology	NASA GCTI WBS	Proposal funding requirements, millions of dollars					
		FY90	FY91	FY92	FY93	FY94	FY95
Advanced pointing/servo	1.61		0.5	0.5	0.5	0.5	0.4
Mechanical scanning			0.2	0.4	2.0	0.7	
Advanced fiber optics			0.2	0.2	0.2	0.3	0.3
Totals			0.9	1.1	2.7	1.5	0.7

## ADVANCED POINTING/SERVO TECHNOLOGY

<p><b>SCOPE</b> Explore techniques for advanced pointing/servo technology for instrument pointing.</p> <p><b>OBJECTIVE</b> Develop new pointing control strategies and technologies for high accuracy/high stability servo applications.</p>	<p><b>APPROACH</b></p> <p>Evaluate pointer/servo requirements for EOS and beyond. Survey manufacturers and scientific literature to identify promising sensor technologies. Develop and model new control strategies and mechanisms to satisfy high accuracy/high stability servo applications. Develop and test proof-of-concept model(s).</p>																
<p><b>RATIONALE</b></p> <p>Conventional pointing control sensors (encoders, resolvers, etc.) are at their limits in control of present space instrument pointing. Higher accuracy/stability of future pointing systems will require a new generation of internal position-sensing mechanisms and control strategies. Techniques for isolation and pointing control via high accuracy and high compliance magnetic bearings show great promise, but have had limited attention.</p>	<p><b>DELIVERABLES/MILESTONES</b></p> <ul style="list-style-type: none"> <li>• Survey EOS and beyond pointing requirements in terms of required gimbal parameters.</li> <li>• Survey of promising sensor technologies.</li> <li>• Report "Pointing and Control Using Advanced Strategies and Mechanisms" (excluding magnetic bearings).</li> <li>• Report "Pointing and Control Using Advanced Strategies and Mechanisms with Magnetic Bearing Technology."</li> </ul>																
<p><b>TECHNOLOGY ASSESSMENT</b></p>	<p><b>DEVELOPMENT PLAN</b></p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="text-align: left;">FY Total</th> <th style="text-align: right;">\$20K</th> <th style="text-align: right;">\$30K</th> <th style="text-align: right;">\$50K</th> <th style="text-align: right;">\$175K</th> <th style="text-align: right;">\$200K</th> <th style="text-align: right;">\$300K</th> <th style="text-align: right;">\$400K</th> </tr> </thead> <tbody> <tr> <td style="text-align: left;">FY Total</td> <td style="text-align: right;">\$400K</td> <td style="text-align: right;">\$325K</td> <td style="text-align: right;">\$300K</td> <td style="text-align: right;">\$200K</td> <td style="text-align: right;">\$200K</td> <td style="text-align: right;">\$300K</td> <td style="text-align: right;">\$400K</td> </tr> </tbody> </table>	FY Total	\$20K	\$30K	\$50K	\$175K	\$200K	\$300K	\$400K	FY Total	\$400K	\$325K	\$300K	\$200K	\$200K	\$300K	\$400K
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## MECHANICAL SCANNING CONCEPTS FOR LARGE OPTICAL SYSTEMS

<p><b>SCOPE</b> DEVELOP AND DEMONSTRATE CONCEPTS AND TECHNOLOGIES TO ENABLE SCANNING BY FUTURE INSTRUMENTS WITH LARGE OPTICAL SYSTEMS.</p> <p><b>OBJECTIVE</b></p> <ul style="list-style-type: none"> <li>• ENABLE COVERAGE OF THE FULL EARTH DISC WITH HIGH RESOLUTION.</li> <li>• ENHANCE THE CAPABILITY TO PROVIDE MULTIPLE SATELLITE/ INSTRUMENT COVERAGE OF AREAS OF SCIENTIFIC INTEREST.</li> <li>• AVOID THE TRADE-OFFS BETWEEN RESOLUTION AND COVERAGE.</li> <li>• ENHANCE THE POSSIBILITIES OF IDENTIFYING AND STUDYING UNANTICIPATED EVENTS AND/OR PHENOMENA.</li> </ul> <p><b>RATIONALE</b> THE SCIENTIFIC RETURN AND VIABILITY OF MANY INSTRUMENT CONCEPTS COULD BE SIGNIFICANTLY ENHANCED BY THE ADDITION OF SCANNING CAPABILITY. EVOLVING TECHNOLOGIES IN LIGHTWEIGHT, LARGE APERTURE, OPTICAL SYSTEMS ARE BROADENING THE RANGE OF INSTRUMENT SYSTEMS WHERE SCANNING SYSTEMS CAN BE EMPLOYED.</p>	<p><b>APPROACH</b> MULTIDISCIPLINE APPROACH WHICH WILL ENCOMPASS SERVO DESIGNS, MECHANICAL SYSTEMS, AND MOMENTUM COMPENSATION SYSTEMS IN THE DEVELOPMENT OF CANDIDATE SCANNING CONCEPTS.</p>
	<p><b>DELIVERABLES</b></p> <ol style="list-style-type: none"> <li>1. DEVELOPMENT OF CANDIDATE CONCEPT(S) WITH TRADE-OFF ANALYSIS.</li> <li>2. CONCEPT SELECTION.</li> <li>3. DESIGN DEVELOPMENT.</li> <li>4. DEVELOPMENT OF FULL-SCALE FUNCTIONAL MODEL.</li> <li>5. TEST AND EVALUATION.</li> </ol>
	<p><b>TECHNOLOGY ASSESSMENT</b></p> <p>The graph plots Readiness Level (1 to 5) against Year (1991 to 1995). A diagonal line labeled 'CURRENT EVOLUTION' shows progress from level 1 in 1991 to level 5 in 1995. A horizontal line labeled 'MISSION NEEDS' is at readiness level 4. A diagonal line labeled 'WITH AUGMENTATION' starts at level 2 in 1991 and reaches level 5 in 1995, crossing the 'MISSION NEEDS' line.</p>
	<p><b>DEVELOPMENT PLAN</b></p> <p>The timeline spans from 1991 to 1995. Milestones include:</p> <ul style="list-style-type: none"> <li>1991: \$0.2M / 4</li> <li>1992: \$2.0M / 5</li> <li>1993: \$0.5M / 5</li> <li>1994: \$0.4M / 6</li> <li>1995: \$0.2M / 5</li> </ul> <p>Costs are in millions of dollars (\$M).</p>

## Advanced Fiber Optic Sensors for NDE of Critical Structures

**E. MADARAS**

**SCOPE**  
DEVELOP AND INTEGRATE FIBER OPTIC SENSORS WITH CRITICAL STRUCTURES FOR ADVANCED NDE NEEDS.

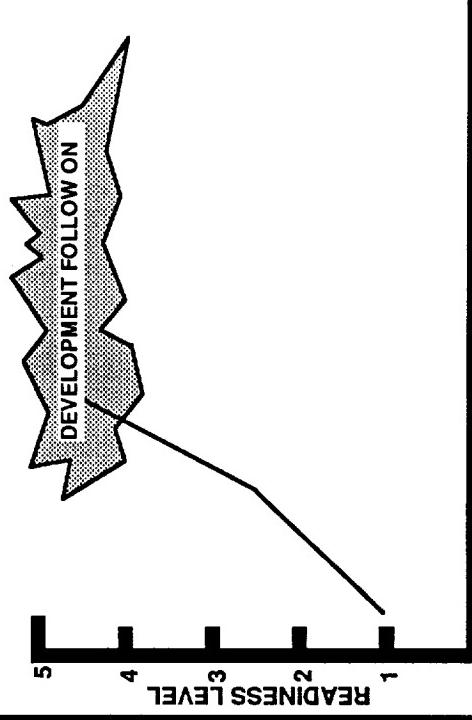
### OBJECTIVE

- PROVIDE REAL-TIME INFORMATION ABOUT STRAIN, TEMPERATURE, CONFIGURATION, IMPACT DAMAGE, THERMAL DEGRADATION, AND RADIATION DEGRADATION.

### RATIONALE

- PROVIDE A SENSOR FEEDBACK LOOP FOR STRUCTURAL CONFIGURATION OF ANTENNA DISTORTION.
- MONITOR MATERIAL CONDITIONS AND DEGRADATIONS.
- NEED FOR A MODAL FIBER-OPTIC SMART SENSOR FOR DYNAMIC ANALYSIS.

### TECHNOLOGY ASSESSMENT



WORKING AT READINESS LEVELS OF 2 THROUGH 5

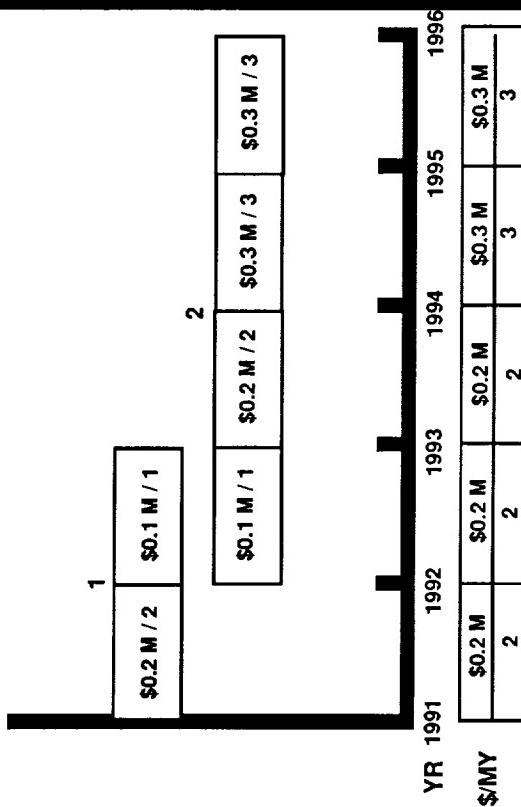
**APPROACH**  
• DEVELOP METHODS FOR INCORPORATING FIBER OPTICS INTO SPACE STRUCTURES.

- DEVELOP THE RELATIONSHIP OF ACOUSTIC EMISSION SIGNALS TO DAMAGE.
- DEVELOP THE RELATIONSHIP BETWEEN THERMAL AND STRAIN BEHAVIOR OF FIBER OPTICS.

### DELIVERABLES

1. DEVELOP THE METHODS FOR INCORPORATING FIBER OPTICS INTO SPACE STRUCTURES.
2. DEVELOP A PROTOTYPE SYSTEM TO VERIFY THE CAPABILITIES OF MEASURING STRAIN, CONFIGURATION, TEMPERATURE, IMPACT DAMAGE, AND DEGRADATION OF A STRUCTURAL SYSTEM.

### DEVELOPMENT PLAN



LaRC GCTI Observation Technologies

1.7 Lasers

Technology	NASA GCTI WBS	Proposal funding requirements, millions of dollars					
		FY90	FY91	FY92	FY93	FY94	FY95
Semiconductor laser arrays	1.75		1.0	1.2	1.2	2.0	0
Midinfrared lidar technology	1.71		1.0	1.0	1.5	2.0	0
Coherent doppler lidar	1.72		0.3	0.7	1.3	2.4	4.0
CO <sub>2</sub> laser catalyst	1.72		1.0	1.0	2.0	2.0	2.0
Scanning lidar technology	1.73		0.25	0.5	1.5	1.0	2.0
Laser wavemeter	1.73	0.1	0.3	0.5	0.4	0.4	0.1
Nonlinear frequency conversion	1.71		1.1	1.6	1.6	0.9	0
High-resolution lidar	1.73		0.2	0.2	0.3	0.4	0.4
Differential absorption measurements	1.73		0.3	0.8	0.8	0.6	0
Gas filter correlation radiometer	1.81		0.5	1.0	1.0	1.5	0
<b>Totals</b>		<hr/> 0.1	<hr/> 5.95	<hr/> 8.5	<hr/> 11.6	<hr/> 13.2	<hr/> 8.5

# ADVANCED SENSOR CONCEPTS--SEMICONDUCTOR LASER ARRAYS

N. BARNES

SCOPE	APPROACH												
DEVELOP GaIA's LASER DIODE ARRAY FOR PUMPING MIDINFRARED SOLID STATE LASERS.	<ul style="list-style-type: none"> <li>UTILIZE GAIA'S LASER DIODE TECHNOLOGY.           <ul style="list-style-type: none"> <li>- GaIA's DEVICES EMERGING FOR Nd:YAG APPLICATIONS</li> <li>- SAME TECHNOLOGY APPLICABLE FOR OTHER LASER MATERIALS.</li> </ul> </li> <li>TAILOR LASER DIODES FOR APPLICATIONS.           <ul style="list-style-type: none"> <li>- VARY Al/Ga RATIO TO LASER DIODE WAVELENGTH</li> <li>- UTILIZE QUANTUM WELL STRUCTURE</li> </ul> </li> </ul>												
OBJECTIVE	DELIVERABLES												
<ul style="list-style-type: none"> <li>PROVIDE HIGH-EFFICIENCY PUMPS FOR MIDINFRARED LASERS.</li> <li>PROVIDE LONG-LIFE, <math>&gt;10^8</math> SHOTS, PUMPS FOR MID-INFRARED LASERS.</li> </ul>	<ol style="list-style-type: none"> <li>EVALUATION OF QUANTUM WELL STRUCTURE.</li> <li>EVALUATION OF SHIFT OF LASER DIODE WAVELENGTH.</li> <li>TEST DATA ON LASER DIODE EVALUATION.</li> <li>1.0-CM-LONG LASER DIODE BARS.</li> </ol>												
RATIONALE	TECHNOLOGY ASSESSMENT												
<ul style="list-style-type: none"> <li>MIDINFRARED LASERS ARE REQUIRED FOR           <ul style="list-style-type: none"> <li>- EYE SAFETY</li> <li>- STRONG ABSORPTION FEATURES OF TRACE GASES</li> </ul> </li> <li>HIGH-EFFICIENCY, LONG-LIFE PUMPS ARE NEEDED FOR MIDINFRARED LASERS.</li> <li>REMOTE SENSORS NEEDED FOR ATMOSPHERIC MONITORING           <ul style="list-style-type: none"> <li>- GREENHOUSE EFFECT: CO<sub>2</sub>, CH<sub>4</sub></li> <li>- OZONE HOLE: O<sub>3</sub>, CFC</li> </ul> </li> </ul>	<p>The graph plots Laser Diode Wavelength (nm) on the y-axis (ranging from 0.6 to 0.9) against Al As concentration on the x-axis (ranging from 0 to 0.15). A solid line shows a non-linear increase in wavelength as Al As concentration increases. Two specific points on the curve are labeled: Nd:YAG at approximately 0.82 nm and Tm:YAG at approximately 0.87 nm. Arrows point from these labels to their respective points on the curve.</p> <table border="1"> <caption>Data points estimated from the graph</caption> <thead> <tr> <th>Al As Concentration</th> <th>Laser Diode Wavelength (nm)</th> </tr> </thead> <tbody> <tr> <td>0.00</td> <td>0.65</td> </tr> <tr> <td>0.05</td> <td>0.80</td> </tr> <tr> <td>0.10</td> <td>0.85</td> </tr> <tr> <td>0.15</td> <td>0.90</td> </tr> </tbody> </table>	Al As Concentration	Laser Diode Wavelength (nm)	0.00	0.65	0.05	0.80	0.10	0.85	0.15	0.90		
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TECHNOLOGY ASSESSMENT	DEVELOPMENT PLAN												
	<p>The bar chart illustrates the projected development timeline and costs over four years (90-94).</p> <table border="1"> <caption>Development Plan Timeline</caption> <thead> <tr> <th>Year</th> <th>Budget (\$M/Y)</th> </tr> </thead> <tbody> <tr> <td>90</td> <td>\$1.0M</td> </tr> <tr> <td>91</td> <td>\$0.6M</td> </tr> <tr> <td>92</td> <td>\$0.6M</td> </tr> <tr> <td>93</td> <td>\$1.2M</td> </tr> <tr> <td>94</td> <td>\$2.0M</td> </tr> </tbody> </table>	Year	Budget (\$M/Y)	90	\$1.0M	91	\$0.6M	92	\$0.6M	93	\$1.2M	94	\$2.0M
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94	\$2.0M												

## ADVANCED SENSOR CONCEPTS—MIDINFRARED LIDAR TECHNOLOGY

SCOPE	APPROACH
DEVELOP THULIUM LASER TECHNOLOGY FOR MEASUREMENTS OF CONCENTRATION AND GROWTH OF ATMOSPHERIC SPECIES OVER WAVELENGTHS FROM 1 TO 10 $\mu\text{m}$ .	MATERIAL DEVELOPMENT AND SELECTION TO IMPROVE QUANTUM EFFICIENCY, RELIABILITY AND LIFETIME, THROUGH LABORATORY VALIDATION AND SYSTEMS OPTIMIZATION, DEMONSTRATE IMPROVEMENTS AND FIGURES OF MERIT.
OBJECTIVE	DELIVERABLES
OBTAIN AND EVALUATE GREENHOUSE PARAMETRICS AND GROWTH, BIOMASS BURNING, VOLCANIC VENTS, INDUSTRIAL PRODUCTION, AND STRESS REMEDY PATTERNING.	<ol style="list-style-type: none"> <li>1. REPORT ON BEST CANDIDATE GARNET STRUCTURE MATERIAL; SELECT CANDIDATE MATERIAL.</li> <li>2. LABORATORY DEMONSTRATION OF TUNABILITY OVER THE CRITICAL WAVENUMBERS OF INTEREST.</li> <li>3. DELIVERY OF LABORATORY SAMPLES AND EVALUATION REPORT.</li> <li>4. DEMONSTRATE TECHNOLOGY AND APPLICATIONS.</li> </ol>
RATIONALE	TECHNOLOGY ASSESSMENT
IMPROVED SENSOR LIFETIMES AND NOISE DISCRIMINATION TO MEASURE ATMOSPHERIC SPECIES OVER A GLOBAL SCALE TO IMPROVE THE UNDERSTANDING OF THE SPECIES DIFFUSION AND MIGRATION PROCESSES.	<p>PULSE CYCLE LIFE X ABSORBANCE</p> <p>MISSION NEEDS REGION</p> <p>WITH THE TECHNOLOGY ELEMENT</p> <p>EVOLUTIONARY IMPROVEMENTS</p> <p>YR 90 91 92 93 94</p> <p>\$/MY</p> <p>1989 1995 2000</p>
TECHNOLOGY ASSESSMENT	DEVELOPMENT PLAN
	<p>YR 90 91 92 93 94</p> <p>\$/MY</p>

# COHERENT DOPPLER LIDAR (WIND SENSING)

R. NELMS

**SCOPE**  
DEVELOP SOLID-STATE EYE-SAFE LASER TECHNOLOGY FOR  
MEASUREMENT OF WIND VELOCITY (WIND FIELD VECTORS)  
FROM EARTH ORBIT.

## OBJECTIVE

- GLOBAL MEASUREMENT OF WIND VELOCITY TO IMPROVE  
UNDERSTANDING OF CLIMATE AND POLLUTANT TRANSPORT  
MECHANISMS.

- PROVIDE SOLID-STATE (LONG-LIFE) LASER TECHNOLOGY  
COMPATIBLE WITH LAUNCH AND SPACE ENVIRONMENTS.

- OPTIMIZE SOURCE WAVELENGTH TO PARTICLE SIZE FOR  
MAXIMUM DETECTABILITY WITHIN EYE-SAFE SPECTRUM.

## RATIONALE

- BETTER MATCH BETWEEN PARTICLE SIZE DISTRIBUTION AND  
WAVELENGTH - IMPROVED PERFORMANCE.

- TUNABLE TO WATER ABSORPTION SPECTRUM - PROVIDING  
EYE-SAFE OPERATION

- COHERENT DETECTORS FOR THE 1- TO 2-MICRON REGION  
REQUIRE LESS ONBOARD SUPPORT (COOLING, etc.) AND PROVIDE  
HIGHER SENSITIVITY.

## APPROACH

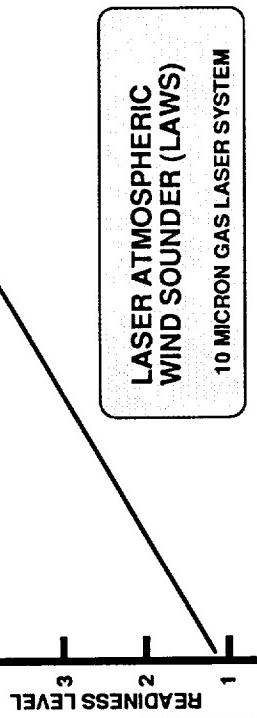
- DEVELOP A 2-MICRON LIDAR SOURCE, BASED ON  
TECHNOLOGY EFFORT INITIATED UNDER OAST/AERO  
WIND SHEAR PROGRAM.
- DEVELOP COHERENT DETECTOR/SENSOR SYSTEMS  
FOR THE 2-MICRON REGION

- INTEGRATE THESE SYSTEMS AND DEMONSTRATE SYSTEM-LEVEL  
TECHNOLOGY FOR A FOLLOW-ON TO THE EOS LAWS  
SYSTEM.

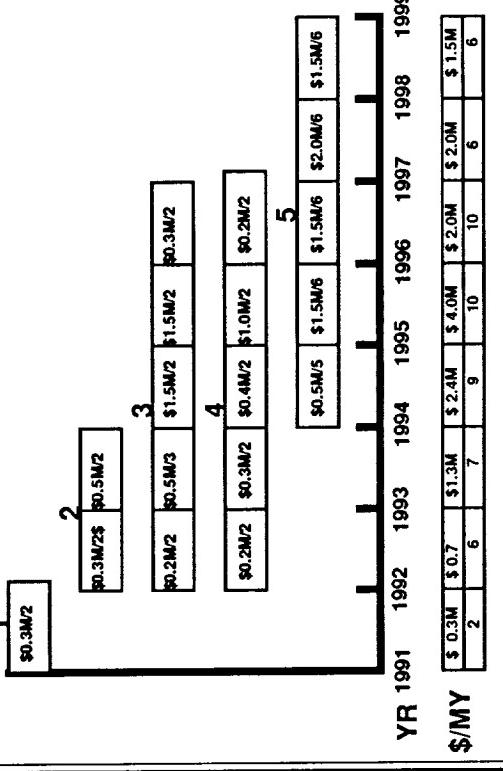
## DELIVERABLES

1. TECHNOLOGY ASSESSMENT FOR LASER AND COHERENT  
DETECTOR/SENSOR SYSTEMS
2. CONCEPT DEVELOPMENT
3. DEVELOP AND DEMONSTRATE LASER SYSTEM
4. DEVELOP AND DEMONSTRATE COHERENT DETECTOR/SENSOR  
TECHNOLOGY
5. DEVELOP AND DEMONSTRATE DOPPLER LIDAR SYSTEM

## TECHNOLOGY ASSESSMENT



## DEVELOPMENT PLAN



# CARBON DIOXIDE LASER CATALYST

P. BROCKMAN

<b>SCOPE</b>	Develop technology to provide high-efficiency, ambient temperature, CO-O <sub>2</sub> recombination catalysts for long-life, closed cycle operation of pulsed common and rare isotope CO <sub>2</sub> lasers.	<b>APPROACH</b>	Continue the current research effort in noble-metal/reducible-oxide materials to achieve the maximum catalyst activity with minimum decay for long-lifetime CO <sub>2</sub> laser operation. The catalyst will be developed to be fully compatible with rare isotope operation, and the mechanism of operation will be modeled to allow reliable predictions of long-life behavior. This will be tested in lasers and surrogate facilities.																					
<b>OBJECTIVE</b>	<ul style="list-style-type: none"> <li>• Develop high-efficiency, ambient temperature CO-O<sub>2</sub> recombination catalysts.</li> <li>• Develop technology to allow the use of these catalysts with rare isotope laser gases.</li> <li>• Demonstrate long-lifetime operation of these catalysts.</li> </ul>	<b>DELIVERABLES</b>	<ol style="list-style-type: none"> <li>1. Formulation for high-efficiency long-life catalyst.</li> <li>2. Computer models of catalyst mechanisms and long-life behavior.</li> <li>3. Long-life tests of catalyst behavior.</li> <li>4. Catalyst for LAWS flight instrument.</li> </ol>																					
<b>RATIONALE</b>	The Laser Atmospheric Wind Sounder (LAWS) program and other space-based remote sensing programs will depend on high-energy pulsed CO <sub>2</sub> lasers. The operation of these lasers results in breakdown of the CQ into CO and Q with subsequent laser degradation and failure. The catalysts recombine these gases and allow long-lifetime operation without replacing the laser gas.	<b>TECHNOLOGY ASSESSMENT</b>	<p>READYNNESS LEVEL</p> <p>YEAR</p> <p>1990 1991 1992 1993 1994 1995</p>																					
		<b>DEVELOPMENT PLAN</b> Schedule, Dollars, and Civil-Service Manpower	<p>\$/MY</p> <p>YEAR</p> <p>1990 1991 1992 1993 1994 1995</p> <table border="1"> <tr> <td>\$1.0M/2.5</td> <td>\$1.0M/2.5</td> <td>\$1.0M/2.5</td> <td>1</td> </tr> <tr> <td></td> <td></td> <td></td> <td>\$1.5M/1.5</td> <td>2</td> </tr> <tr> <td></td> <td></td> <td></td> <td>\$0.5M/1</td> <td>\$2.0M/2.5</td> <td>3</td> </tr> <tr> <td></td> <td></td> <td></td> <td></td> <td>\$2.0M/2.5</td> <td>4</td> </tr> </table>	\$1.0M/2.5	\$1.0M/2.5	\$1.0M/2.5	1				\$1.5M/1.5	2				\$0.5M/1	\$2.0M/2.5	3					\$2.0M/2.5	4
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			\$0.5M/1	\$2.0M/2.5	3																			
				\$2.0M/2.5	4																			

## ADVANCED SENSOR CONCEPTS-SCANNING LIDAR TECHNOLOGY

SCOPE	APPROACH	DELIVERABLES
DEVELOP AND DEMONSTRATE DESIGN CONCEPT(S) TO ENABLE SCANNING LIDAR SYSTEMS WHICH CAN PROVIDE COVERAGE OVER THE EARTH'S DISC. CONCEPT STUDIES WILL CONSIDER FOCAL-PLANE SCANNING, OPTICAL ELEMENT SCANNING, AND MECHANICAL SCANNING TECHNIQUES.	USE EXISTING LIDAR TECHNOLOGY AS A PRECURSOR AND DESIGN TOOL. A SCANNING LIDAR SYSTEM WILL BE DESIGNED AND IMPLEMENTED WITH IMPROVED OPTICS, DETECTORS, ELECTRONICS, AND POINTING CONTROL TO DEMONSTRATE FEASIBILITY.	1. SCANNING LIDAR SYSTEM DEFINITION AND COMPONENT TECHNOLOGY REQUIREMENTS. 2. OPTICS AND COMPONENT ANALYSIS AND DEFINITION. 3. IMPROVED POINTING SYSTEM. 4. IMPROVED COMPONENT TECHNOLOGY. 5. LABORATORY DEMONSTRATION.
OBJECTIVE		
PRODUCE REAL-TIME SYNOPTIC MAPS OF UPPER ATMOSPHERIC SPECIES TO DETERMINE CAUSE AND EFFECT FACTORS RELATING TO ATMOSPHERIC CONSTITUENT DISTRIBUTIONS.		
RATIONALE	<p>PRESENT TECHNOLOGY GENERATES: (1) SINGLE-POINT MEASUREMENTS OF SPECIES DISTRIBUTIONS THAT DO NOT PRODUCE MAPS IN A COMPREHENSIVE AND TIMELY MANNER, AND (2) DATA THAT DO NOT PERMIT ADEQUATE INCLUSION, INTERPRETATION, OR UNDERSTANDING OF ANOMALOUS ATMOSPHERIC PERTURBATIONS.</p>	
TECHNOLOGY ASSESSMENT		
DEVELOPMENT PLAN		

## ADVANCED SENSOR CONCEPTS--LASER WAVEMETER AND CALIBRATION TECHNOLOGY

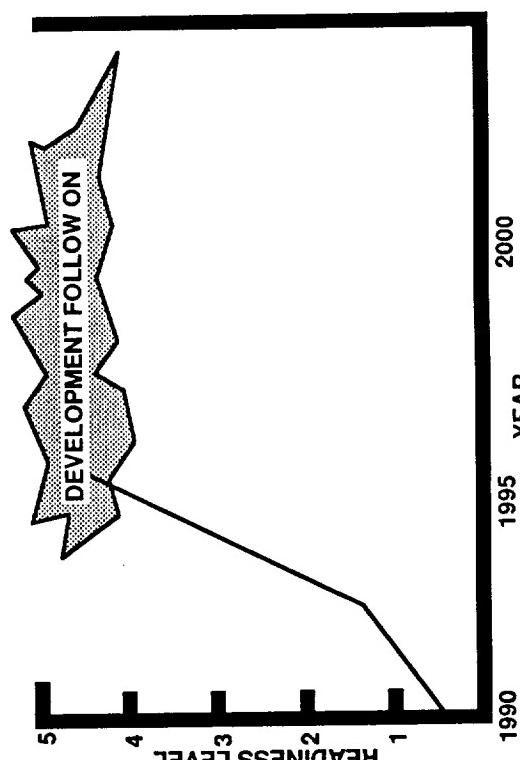
<p><b>SCOPE</b></p> <p>TO DEVELOP TECHNOLOGY TO PROVIDE WAVELENGTH KNOWLEDge TO CONTROL ELEMENT TUNED AND INJECTION (SEEDED) TUNED SOLID-STATE LASERS.</p> <p><b>OBJECTIVE</b></p> <p>TO DEVELOP:</p> <ul style="list-style-type: none"> <li>1. HIGH-SPEED SELF-CORRECTING DATA RETRIEVAL ALGORITHMS.</li> <li>2. MONOLITHIC FABRY-PEROT INTERFEROMETERS.</li> <li>3. THERMO-MECHANICAL STABLE SUPPORTING STRUCTURES.</li> <li>4. HIGHLY ACCURATE CALIBRATION TECHNIQUES.</li> <li>5. BROAD-WAVELENGTH HIGH-REFLECTIVITY COATINGS.</li> </ul> <p><b>RATIONALE</b></p> <p>ADVANCED WAVELENGTH KNOWLEDGE IS NEEDED FOR:</p> <ul style="list-style-type: none"> <li>1. ELEMENT TUNED AND INJECTION TUNED SOLID-STATE LASERS.</li> <li>2. DIAL MEASUREMENTS OF <math>H_2O</math>, <math>O_3</math>, TEMPERATURE, PRESSURE, AND AEROSOLS.</li> <li>3. EARTH AND ATMOSPHERIC REMOTE SENSING.</li> </ul>	<p><b>APPROACH</b></p> <p>USE FABRY-PEROT INTERFEROMETRY WITH SELF-CORRECTING DATA RETRIEVAL ALGORITHMS RUNNING IN ADVANCED COMPUTERS TO PROVIDE HIGHLY ACCURATE LASER WAVELENGTH CENTROID DATA.</p> <p><b>DELIVERABLES</b></p> <ul style="list-style-type: none"> <li>1. END-TO-END INSTRUMENT MODEL THAT VALIDATES APPROACH.</li> <li>2. OPERATE BREADBOARD THAT DEMONSTRATES LASER WAVELENGTH CENTROID RETRIEVAL TO SEVERAL HUNDREDTHS OF A PICOMETER.</li> <li>3. HIGH-SPEED COMPUTER DEMONSTRATION.</li> </ul>	<p><b>TECHNOLOGY ASSESSMENT</b></p> <p>READYNNESS LEVEL</p> <p>YR</p> <p>\$/MY</p> <table border="1"> <tr> <td>1989</td> <td>1995</td> <td>2000</td> <td>2005</td> <td>CURRENT PROGRAMS</td> </tr> <tr> <td>0</td> <td>0</td> <td>0</td> <td>0</td> <td>0</td> </tr> <tr> <td>1</td> <td>1</td> <td>1</td> <td>1</td> <td>1</td> </tr> <tr> <td>2</td> <td>2</td> <td>2</td> <td>2</td> <td>2</td> </tr> <tr> <td>3</td> <td>3</td> <td>3</td> <td>3</td> <td>3</td> </tr> <tr> <td>4</td> <td>4</td> <td>4</td> <td>4</td> <td>4</td> </tr> <tr> <td>5</td> <td>5</td> <td>5</td> <td>5</td> <td>5</td> </tr> <tr> <td>6</td> <td>6</td> <td>6</td> <td>6</td> <td>6</td> </tr> <tr> <td>7</td> <td>7</td> <td>7</td> <td>7</td> <td>7</td> </tr> </table> <p>MISSION REQUIREMENTS</p> <p>WITH THIS TECHNOLOGY ELEMENT</p>	1989	1995	2000	2005	CURRENT PROGRAMS	0	0	0	0	0	1	1	1	1	1	2	2	2	2	2	3	3	3	3	3	4	4	4	4	4	5	5	5	5	5	6	6	6	6	6	7	7	7	7	7	<p><b>DEVELOPMENT PLAN</b></p> <p>YR</p> <p>\$/MY</p> <table border="1"> <tr> <td>1990</td> <td>1991</td> <td>1992</td> <td>1993</td> <td>1994</td> <td>1995</td> </tr> <tr> <td>0.1/2</td> <td>0.3/3</td> <td>0.5/4</td> <td>0.4/4</td> <td>0.4/3</td> <td>0.1/2</td> </tr> </table>	1990	1991	1992	1993	1994	1995	0.1/2	0.3/3	0.5/4	0.4/4	0.4/3	0.1/2
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## ADVANCED SENSOR CONCEPTS-NONLINEAR FREQUENCY CONVERSION TECHNOLOGY

SCOPE	APPROACH
DEVELOP NONLINEAR FREQUENCY CONVERSION TECHNOLOGY FOR THE MIDINFRARED REGION BETWEEN 2.5 AND 12.0 $\mu\text{m}$ .	<ul style="list-style-type: none"> <li>UTILIZE MIDINFRARED LASERS AS PUMP SOURCE. <ul style="list-style-type: none"> <li>FLASHLAMP-PUMPED LASERS FOR INITIAL DEMONSTRATION</li> <li>LASER-DIODE-PUMPED LASERS EVENTUALLY</li> </ul> </li> <li>ALLOWS PARALLEL DEVELOPMENT</li> <li>DEVELOP/EVALUATE AVAILABLE NONLINEAR MATERIALS.</li> </ul>
OBJECTIVE	DELIVERABLES
<ul style="list-style-type: none"> <li>PROVIDE HIGH-EFFICIENCY FREQUENCY CONVERSION TECHNIQUES.</li> <li>PROVIDE LASER SOURCE TUNABLE BETWEEN 2.5 AND 12.0 <math>\mu\text{m}</math>.</li> <li>PROVIDE SINGLE-FREQUENCY LASER SOURCE.</li> </ul>	<ol style="list-style-type: none"> <li>1. DEVELOP ZnGaP<sub>2</sub> CRYSTALS.</li> <li>2. EVALUATION OF NONLINEAR MATERIALS.</li> <li>3. OPTICAL PARAMETRIC AMPLIFIER.</li> <li>4. OPTICAL PARAMETRIC OSCILLATOR.</li> </ol> <ul style="list-style-type: none"> <li>BROADBAND</li> <li>SINGLE FREQUENCY</li> </ul>
RATIONALE	TECHNOLOGY ASSESSMENT
<ul style="list-style-type: none"> <li>MIDINFRARED LASERS ARE REQUIRED FOR REMOTE SENSORS.</li> <li>EYE SAFETY CONSIDERATIONS</li> <li>STRONG ABSORPTION FEATURES OF TRACE GASES</li> <li>SOLID-STATE LASERS DO NOT OPERATE MUCH BEYOND 2.1 <math>\mu\text{m}</math>.</li> <li>SOLID-STATE FREQUENCY CONVERTER COULD PROVIDE A TUNABLE SOURCE BETWEEN 2.5 AND 12.0 <math>\mu\text{m}</math>.</li> </ul>	<p>MISSION NEEDS</p> <p>PROGRESS WITH THIS ELEMENT</p> <p>CURRENT PROGRESS</p> <p>1990 1992 1994 1996 1998 2000 YR 91 92 93 94 95</p> <p>\$/MY</p>
DEVELOPMENT PLAN	
	<p>1 \$1.5 M</p> <p>2 \$0.8 M</p> <p>3 \$0.2 M</p> <p>4 \$2.5 M</p> <p>YR 91 92 93 94 95</p> <p>\$/MY</p>

## HIGH-RESOLUTION LIDAR

### E. MADARAS

<b>SCOPE</b> DEVELOP ADVANCED OPTICAL METHODS FOR ATMOSPHERIC MONITORING.	<b>APPROACH</b> CONSTRUCT A RADAR FREQUENCY PULSE, PHASE LOCK LOOP SYSTEM THAT IS ALSO A PART OF A LIDAR SYSTEM. • EVALUATE THE SYSTEM FROM A GROUND-BASED SYSTEM.
<b>OBJECTIVE</b> • PROVIDE CAPABILITY TO MAP OUT ATMOSPHERIC INFORMATION WITH HIGH-RESOLUTION RANGE SENSING	<b>DELIVERABLES</b> 1. DEVELOPMENT OF TECHNOLOGY FOR RADAR SYSTEM. 2. DEVELOPMENT OF RADAR-PULSED, PHASE LOCK LOOP/LIDAR LAB SYSTEM. 3. EVALUATION OF SYSTEM.
<b>RATIONALE</b> • A PHASE SENSITIVE MEASUREMENT SYSTEM WILL ALLOW MORE ACCURATE RANGE RESOLUTION THAN IS CURRENTLY CAPABLE ON LIDAR ALONE. • WE HAVE DEMONSTRATED A LASER PHASE SENSITIVE MEASUREMENT SYSTEM WITH RANGE ACCURACIES OF ONE PART IN A MILLION. • COUPLING LIDAR WITH A PHASE SENSITIVE MEASUREMENT SYSTEM COULD IMPROVE LIDAR CAPABILITIES SIGNIFICANTLY.	<b>TECHNOLOGY ASSESSMENT</b>  <p>DEVELOPMENT FOLLOW ON</p>
<b>READYNESS LEVEL</b> 1 2 3 4 5	<b>YEAR</b> 1990 1995 2000 1992 1993 1994 1995 <b>YR</b> 1991 1992 1993 1994 1995 <b>\$/MY</b> 2 2 2 1 1 1 1 <b>WORKING AT READINESS LEVELS OF 2 THROUGH 5</b>

## ADVANCED SENSOR CONCEPTS-- DIFFERENTIAL ABSORPTION MEASUREMENTS

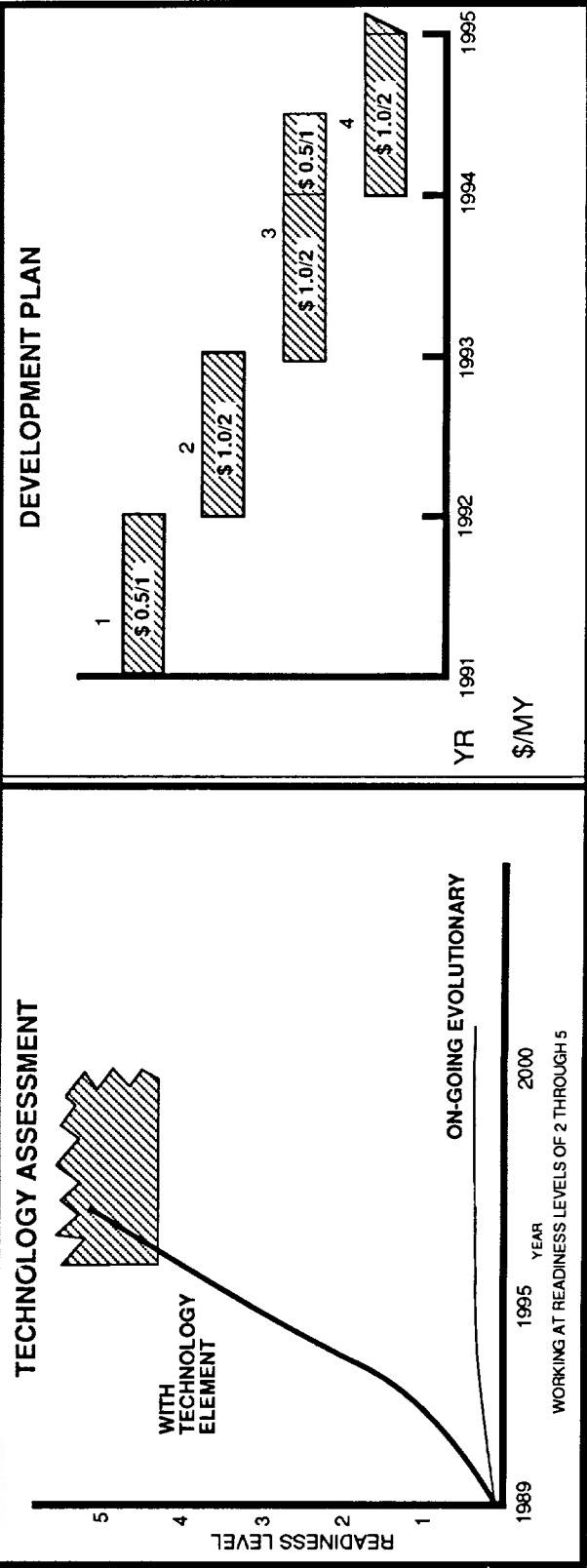
<b>SCOPE</b>	<b>APPROACH</b>	<b>DELIVERABLES</b>	<b>DEVELOPMENT PLAN</b>	<b>TECHNOLOGY ASSESSMENT</b>										
DEVELOPMENT AND DEMONSTRATION OF IMPROVED SEMICONDUCTOR DIODE LASERS FOR IN SITU HIGH SENSITIVITY MEASUREMENTS OF TRACE ATMOSPHERIC SPECIES.	IMPROVE DIODE LASER MATERIAL GROWTH USING STATE-OF-THE-ART SEMICONDUCTOR TECHNOLOGIES SUCH AS MOLECULAR BEAM AND LIQUID PHASE EPITAXY. TRANSFER DIODE LASER FABRICATION TECHNOLOGY PREVIOUSLY DEVELOPED FOR OPTICAL COMMUNICATIONS TO THE DIODE LASER MATERIALS SUITED FOR THE MID IR.	<ol style="list-style-type: none"> <li>1. MODEL LASER RELIABILITY AND LIFETIME DRIVERS.</li> <li>2. IMPROVE CRYSTAL GROWTH TECHNOLOGY.</li> <li>3. IMPROVE DIODE LASER FABRICATION TECHNOLOGY.</li> <li>4. PERFORMANCE AND RELIABILITY EVALUATIONS.</li> <li>5. DELIVER LASERS FOR SYSTEM DEMONSTRATIONS.</li> </ol>	<table border="1"> <thead> <tr> <th>Milestone</th> <th>Cost (\$M/Y)</th> </tr> </thead> <tbody> <tr> <td>1</td> <td>\$0.3M/1</td> </tr> <tr> <td>2</td> <td>\$0.8M/1</td> </tr> <tr> <td>3</td> <td>\$0.8M/2</td> </tr> <tr> <td>4</td> <td>\$0.6M/2</td> </tr> </tbody> </table> <p>YR 1991      1992      1993      1994      1995 \$/MY</p>	Milestone	Cost (\$M/Y)	1	\$0.3M/1	2	\$0.8M/1	3	\$0.8M/2	4	\$0.6M/2	<p>READYNESS LEVEL</p> <p>YEAR</p> <p>1989      1995      2000</p> <p>WORKING AT READINESS LEVELS OF 2 THROUGH 5</p>
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1	\$0.3M/1													
2	\$0.8M/1													
3	\$0.8M/2													
4	\$0.6M/2													
<b>OBJECTIVE</b>	<b>RATIONALE</b>													
DEVELOP AND DEMONSTRATE HIGHLY RELIABLE, SINGLE MODE, HIGH TEMPERATURE (>100K) SEMICONDUCTOR DIODE LASERS FOR THE 2 TO 15 MICRON SPECTRAL REGION.	IN SITU MEASUREMENTS OF THE CONCENTRATION AND FLUX OF KEY TRACE SPECIES WOULD SERVE AS VALUABLE INPUTS TO ATMOSPHERIC MODELS THAT WILL PROVIDE A BETTER UNDERSTANDING OF IMPORTANT ATMOSPHERIC PROCESSES SUCH AS THE GREENHOUSE EFFECT, OZONE DEPLETION, ETC.													

# GAS FILTER CORRELATION RADIOMETER

G. SACHSE

<b>SCOPE</b>	DEVELOP AND DEMONSTRATE A NEW SOLID-STATE GAS FILTER CORRELATION RADIOMETER (GFCR) CONCEPT FOR SPACEBORNE SENSING OF TROPOSPHERIC TRACE GASES.
<b>OBJECTIVE</b>	<ul style="list-style-type: none"> <li>• DEMONSTRATE FEASIBILITY OF SOLID-STATE GFCR CONCEPT</li> <li>• AIRCRAFT VALIDATION OF GFCR CONCEPT</li> <li>• INSTRUMENT SYSTEM CONCEPT DEVELOPMENT FOR SPACE-FLIGHT APPLICATIONS</li> </ul>
<b>RATIONALE</b>	<ul style="list-style-type: none"> <li>• ENABLE MEASUREMENT OF GLOBAL DISTRIBUTION OF TRACE GASES NEEDED IN THE STUDY OF ENVIRONMENTAL CONCERN'S (GREENHOUSE PROCESSES, OZONE DEPLETION, ETC.)</li> <li>• POTENTIAL FOR SIGNIFICANTLY HIGHER SENSITIVITY IN REMOTE SENSING OF MANY TROPOSPHERIC GAS SPECIES.</li> <li>• HIGHER RELIABILITY AND LIFETIME THROUGH ELIMINATION OF HIGH-RATE MOVING COMPONENTS.</li> </ul>

<b>APPROACH</b>	<ul style="list-style-type: none"> <li>• ANALYZE GAS FILTER CORRELATION RADIOMETER CONCEPT WHICH UTILIZES "OPTICAL PATH MODULATION" APPROACH INVOLVING SOLID-STATE POLARIZATION LIGHT MODULATORS.</li> <li>• PERFORM LABORATORY DEMONSTRATION OF GFCR CONCEPT.</li> <li>• DEVELOP AND TEST PROTOTYPE GFCR SYSTEM ON AIRCRAFT PLATFORM.</li> <li>• EXECUTE DESIGN STUDY FOR A SPACEFLIGHT INSTRUMENT.</li> </ul>
<b>DELIVERABLES</b>	<ol style="list-style-type: none"> <li>1. STUDY/ANALYSIS OF SOLID-STATE GAS FILTER CORRELATION APPROACH</li> <li>2. LABORATORY DEMONSTRATION OF THE SOLID-STATE GFCR CONCEPT.</li> <li>3. DEVELOPMENT AND FLIGHT DEMONSTRATION OF AN AIRCRAFT GFCR SYSTEM.</li> <li>4. DESIGN STUDY FOR A SPACECRAFT INSTRUMENT.</li> </ol>



LaRC GCTI Observation Technologies

1.8 Calibration

Technology	NASA GCTI WBS	Proposal funding requirements, millions of dollars					
		FY90	FY91	FY92	FY93	FY94	FY95
Earth radiation instrument calibration facility	1.81		1.5 —	1.1 —	0.2 —	—	—
Totals			1.5	1.1	0.2	—	—

# EARTH RADIATION INSTRUMENT CALIBRATION FACILITY

L. TAYLOR

<b>SCOPE</b>	<b>APPROACH</b>																										
Provide a calibration facility, including thermal vacuum chamber, sources, on-line control and data system, and methodology for simultaneous ground and in-flight calibration under simulated mission environments.	Utilize the system concept and a major part of the hardware design from the calibration facility which was developed under the Earth Radiation Budget Experiment (ERBE), and which was key to the success of the ERBE mission.																										
<b>OBJECTIVE</b>																											
<ul style="list-style-type: none"> <li>Provide a key enabling capability for the EOS CERES instrument system.</li> <li>Provide a sustained NASA calibration capability which is adaptable to a number of spaceflight and aircraft atmospheric research instrument systems.</li> </ul>																											
<b>RATIONALE</b>	NASA ownership key to multiproject utilization and long-term upgrade and evolution of such a facility.																										
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## **Appendix B**

### **Spacecraft and Operations Technology Proposals (WBS 2.0)**

#### **LaRC GCTI Spacecraft Technologies**

##### **2.1 Materials**

Technology	NASA GCTI WBS	Proposal funding requirements, millions of dollars					
		FY90	FY91	FY92	FY93	FY94	FY95
Materials	2.11-13	3.6	7.2	9.7	10.6	10.0	
Nondestructive evaluation (NDE):							
Fiber optics for tethers		0.2	0.2	0.3	0.5	0.5	
Thermal properties for tethers		0.15	0.15	0.2	0.2	0.3	
Platform materials		0.15	0.2	0.2	0.2	0.15	
Sensors for structures		0.15	0.15	0.2	0.2	0.2	
Totals		4.25	7.90	10.6	11.7	11.15	

# SPACE PLATFORM THRUST: MATERIALS ELEMENT (LARC Role)

B. STEIN

SCOPE	APPROACH																																								
<b>OBJECTIVE</b> <ul style="list-style-type: none"> <li>DEVELOP HIGH-PERFORMANCE, LONG-LIFE STRUCTURAL MATERIALS/COATINGS, AND CHARACTERIZE THE DURABILITY OF THESE MATERIALS IN EARTH-ORBITING ENVIRONMENTS BY MODELING, GROUND/FLIGHT TESTING, AND THE DEVELOPMENT OF ADVANCED NDE TECHNOLOGY.</li> <li>CHARACTERIZE LONG-TERM ENVIRONMENTAL MATERIAL RESPONSE.</li> <li>DEVELOP HIGH-PERFORMANCE, SPACE-DURABLE MATERIALS/COATINGS FOR INSTRUMENT SUPPORTS, REFLECTORS, AND LARGE PLATFORMS.</li> <li>DEVELOP ADVANCED NDE/NDI TECHNOLOGY FOR INCREASING THE RELIABILITY AND SAFETY OF EARTH-ORBITING MATERIALS AND STRUCTURES.</li> </ul>	<ul style="list-style-type: none"> <li>ACCURATELY QUANTIFY SPACE ENVIRONMENTS AND INTERACTIONS WITH MATERIALS.</li> <li>DEVELOP LIFE PREDICTION MODELS AND VERIFY WITH GROUND/FLIGHT TEST DATA.</li> <li>DEVELOP ADVANCED HIGH-PERFORMANCE MATERIALS/COATINGS AND DEMONSTRATE THEIR SPACE DURABILITY.</li> <li>DEVELOP TEST/VERIFICATION METHODOLOGY FOR MATERIAL INSPECTION AND PROCESS CONTROL.</li> <li>DEVELOP NDE SENSOR FOR IN SITU MONITORING OF MATERIAL STRUCTURE INTEGRITY.</li> </ul>																																								
<b>RATIONALE</b> <p>EFFICIENT LONG-LIFE PERFORMANCE OF MATERIALS IN GEO AND LEO ENVIRONMENTS IS CRITICAL TO FUTURE LARGE GLOBAL MONITORING SPACECRAFT.</p>	<b>DELIVERABLES</b> <ol style="list-style-type: none"> <li>1. SPACE ENVIRONMENT/MATERIAL INTERACTIONS MODELS</li> <li>2. ADVANCED HIGH-PERFORMANCE MATERIALS AND COATINGS</li> <li>3. NDE METHODOLOGY AND INSTRUMENTATION</li> </ol>																																								
<b>TECHNOLOGY ASSESSMENT</b>	<b>DEVELOPMENT PLAN</b> <table border="1"> <thead> <tr> <th>NDE/NDI</th> <th>FY</th> <th>\$M</th> <th>MY</th> </tr> </thead> <tbody> <tr> <td>Space Environment</td> <td>1.0M</td> <td>2.5M</td> <td>3.0M</td> <td>1.5M</td> <td>1.5M</td> </tr> <tr> <td>Advanced Materials</td> <td>1.5M</td> <td>2.0M</td> <td>3.0M</td> <td>4.0M</td> <td>2.5M</td> </tr> <tr> <td></td> <td>1.1M</td> <td>2.7M</td> <td>3.7M</td> <td>5.1M</td> <td>6.0M</td> </tr> <tr> <td></td> <td>91</td> <td>92</td> <td>93</td> <td>94</td> <td>95</td> </tr> <tr> <td></td> <td>3.6</td> <td>7.2</td> <td>9.7</td> <td>10.6</td> <td>10.0</td> </tr> <tr> <td></td> <td>12</td> <td>16</td> <td>20</td> <td>20</td> <td>20</td> </tr> </tbody> </table>	NDE/NDI	FY	\$M	MY	Space Environment	1.0M	2.5M	3.0M	1.5M	1.5M	Advanced Materials	1.5M	2.0M	3.0M	4.0M	2.5M		1.1M	2.7M	3.7M	5.1M	6.0M		91	92	93	94	95		3.6	7.2	9.7	10.6	10.0		12	16	20	20	20
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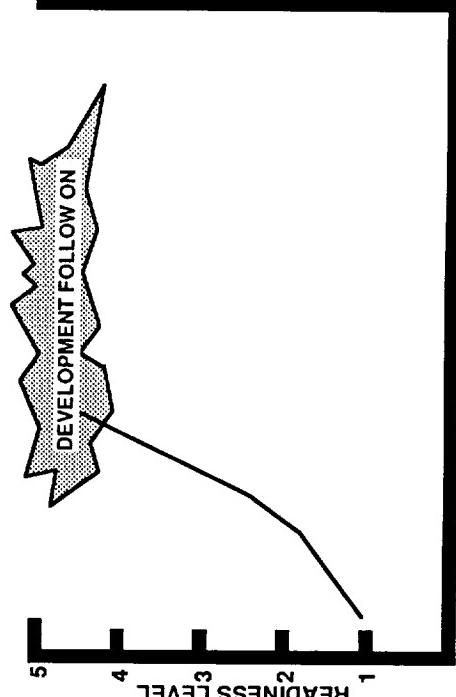
## E. MADARAS

### Fiber Optical Sensors for Tether NDE

<p><b>SCOPE</b> INTEGRATE FIBER-OPTICS SENSORS WITH TETHERS.</p> <p><b>OBJECTIVE</b></p> <ul style="list-style-type: none"> <li>• TO PROVIDE A METHOD TO MONITOR TEMPERATURE, STRAIN, ELECTRIC FIELDS, ACOUSTIC EMISSION, AND CHEMICAL DEGRADATION.</li> </ul> <p><b>RATIONALE</b></p> <ul style="list-style-type: none"> <li>• IMPROVE TETHER RELIABILITY MONITORING.</li> <li>• ALLOW FOR MONITORING DURING MANUFACTURING STAGES AND THROUGHOUT DEPLOYMENT.</li> <li>• AN EXCELLENT METHOD TO PROVIDE A COMMUNICATIONS LINK.</li> </ul> <p><b>APPROACH</b></p> <ul style="list-style-type: none"> <li>• DEVELOP CUSTOM FIBER FABRICATION METHODS FOR MONITORING PROPERTIES.</li> <li>• DEVELOP METHODS FOR SIGNAL PROCESSING THE VARIOUS SIGNALS THAT WILL BE USED.</li> <li>• DEMONSTRATE SYSTEM IN LABORATORY SETTING.</li> </ul> <p><b>DELIVERABLES</b></p> <ol style="list-style-type: none"> <li>1. ADVANCED FIBERS THAT CAN BE INTEGRATED INTO TETHERS.</li> <li>2. DEVELOP A PROTOTYPE SYSTEM TO VERIFY THE CAPABILITIES OF THE FIBER-OPTIC-INSTRUMENTED TETHER SYSTEM.</li> </ol>	<p><b>DEVELOPMENT PLAN</b></p> <table border="1"> <thead> <tr> <th>YR</th> <th>1991</th> <th>1992</th> <th>1993</th> <th>1994</th> <th>1995</th> <th>1996</th> </tr> </thead> <tbody> <tr> <td>\$/MY</td> <td>\$0.2 M 2</td> <td>\$0.2 M 2</td> <td>\$0.2 M / 2 3</td> <td>\$0.2 M / 2 5</td> <td>\$0.3 M / 3 5</td> <td>\$0.3 M / 3 5</td> </tr> </tbody> </table>	YR	1991	1992	1993	1994	1995	1996	\$/MY	\$0.2 M 2	\$0.2 M 2	\$0.2 M / 2 3	\$0.2 M / 2 5	\$0.3 M / 3 5	\$0.3 M / 3 5
YR	1991	1992	1993	1994	1995	1996									
\$/MY	\$0.2 M 2	\$0.2 M 2	\$0.2 M / 2 3	\$0.2 M / 2 5	\$0.3 M / 3 5	\$0.3 M / 3 5									
<p><b>TECHNOLOGY ASSESSMENT</b></p> <p>1995    YEAR</p> <p>1990    2000</p> <p>WORKING AT READINESS LEVELS OF 2 THROUGH 5</p>															

## Thermal Properties NDE for Tether Materials

E. MADARAS

<b>SCOPE</b> DEVELOP NDE METHODS TO MEASURE THERMAL PROPERTIES OF THERMAL MATERIALS FOR TETHERS.	<b>APPROACH</b> <ul style="list-style-type: none"> <li>• TO EXTEND OUR CURRENT TECHNIQUES TO LOW THERMAL CONDUCTIVITY MATERIALS.</li> </ul>																												
<b>OBJECTIVE</b> <ul style="list-style-type: none"> <li>• TO PROVIDE A METHOD TO DETERMINE THE EFFECTIVENESS OF THERMAL PROTECTION COATINGS AND DETECTION OF BOND PROBLEMS IN PROTECTIVE COATINGS.</li> </ul>	<b>DELIVERABLES</b> <ol style="list-style-type: none"> <li>1. A MATERIALS DATA BASE WITH RESPECT TO THE THERMAL BEHAVIOR OF TETHER MATERIALS.</li> <li>2. A METHOD TO MONITOR THERMAL PROTECTIVE COATING INTEGRITY.</li> </ol>																												
<b>RATIONALE</b> <ul style="list-style-type: none"> <li>• DEVELOP A BETTER UNDERSTANDING OF TETHER THERMAL LOADS.</li> <li>• IMPROVE THERMAL PROTECTIVE COATING INTEGRITY.</li> </ul>	<b>TECHNOLOGY ASSESSMENT</b> 																												
<b>YEAR</b> 1990      1995      2000	<table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="text-align: left; width: 10%;">\$ / MY</th> <th style="text-align: left; width: 15%;">1991</th> <th style="text-align: left; width: 15%;">1992</th> <th style="text-align: left; width: 15%;">1993</th> <th style="text-align: left; width: 15%;">1994</th> <th style="text-align: left; width: 15%;">1995</th> <th style="text-align: left; width: 15%;">1996</th> </tr> </thead> <tbody> <tr> <td style="text-align: left;">READYNESS LEVEL</td> <td style="text-align: left;">5</td> <td style="text-align: left;">4</td> <td style="text-align: left;">3</td> <td style="text-align: left;">2</td> <td style="text-align: left;">1</td> <td style="text-align: left;">1</td> </tr> <tr> <td style="text-align: left;">WORKING AT READINESS LEVELS OF 2 THROUGH 5</td> <td style="text-align: left;">\$0.15 M / 1</td> <td style="text-align: left;">\$0.15 M / 1</td> <td style="text-align: left;">\$0.1 M / 1</td> <td style="text-align: left;">\$0.1 M / 1</td> <td style="text-align: left;">\$0.1 M / 1</td> <td style="text-align: left;">\$0.2 M / 2</td> </tr> <tr> <td style="text-align: left;">\$ / MY</td> <td style="text-align: left;">1</td> <td style="text-align: left;">1</td> <td style="text-align: left;">2</td> <td style="text-align: left;">2</td> <td style="text-align: left;">2</td> <td style="text-align: left;">3</td> </tr> </tbody> </table>	\$ / MY	1991	1992	1993	1994	1995	1996	READYNESS LEVEL	5	4	3	2	1	1	WORKING AT READINESS LEVELS OF 2 THROUGH 5	\$0.15 M / 1	\$0.15 M / 1	\$0.1 M / 1	\$0.1 M / 1	\$0.1 M / 1	\$0.2 M / 2	\$ / MY	1	1	2	2	2	3
\$ / MY	1991	1992	1993	1994	1995	1996																							
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\$ / MY	1	1	2	2	2	3																							

## NDE for Platform Materials and Structures

E. MADARAS

**SCOPE**  
DEVELOP A MEASUREMENT SYSTEM TO MEASURE ENGINEERING PROPERTIES THROUGHOUT CRITICAL PARTS.

### OBJECTIVE

• DEVELOP A SYSTEM TO MEASURE THE LOCAL STIFFNESS PROPERTIES OF CRITICAL MATERIALS FOR ACCURATE STRAIN PREDICTIONS.

### RATIONALE

• NEED TO DEVELOP NDE METHODS THAT CAN MEASURE THE LOCAL ENGINEERING PROPERTIES OF MATERIALS.  
 • A MEASUREMENT SYSTEM THAT IS COUPLED WITH FINITE ELEMENT MODEL CODES COULD THEN ACCURATELY PREDICT THE BEHAVIOR OF A CRITICAL PART FOR ENHANCED SAFETY AND RELIABILITY OF STRUCTURES.

**APPROACH**

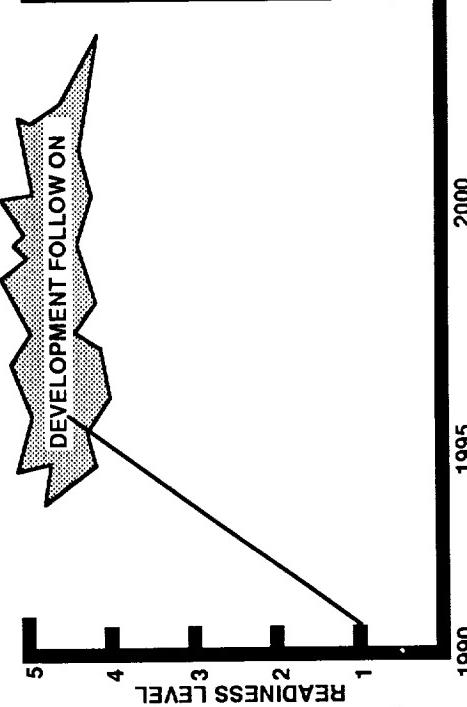
- DEVELOP AN ULTRASONIC SCANNING METHOD THAT CAN MEASURE THE LOCAL STIFFNESS PROPERTIES OF MATERIALS.

- DEVELOP IMPROVED NONLINEAR COMPUTATIONAL ALGORITHMS FOR FASTER COMPUTATIONS.
- DEVELOP THE SYSTEM SO THAT IT CAN COUPLE THE LOCAL STIFFNESS VALUES INTO AN FEM CODE.

### DELIVERABLES

1. A SYSTEM THAT WILL BE CAPABLE OF MEASURING THE STIFFNESS MODULI OF MATERIALS RAPIDLY AND WILL BE COUPLED TO A STANDARD FEM CODE.

### TECHNOLOGY ASSESSMENT

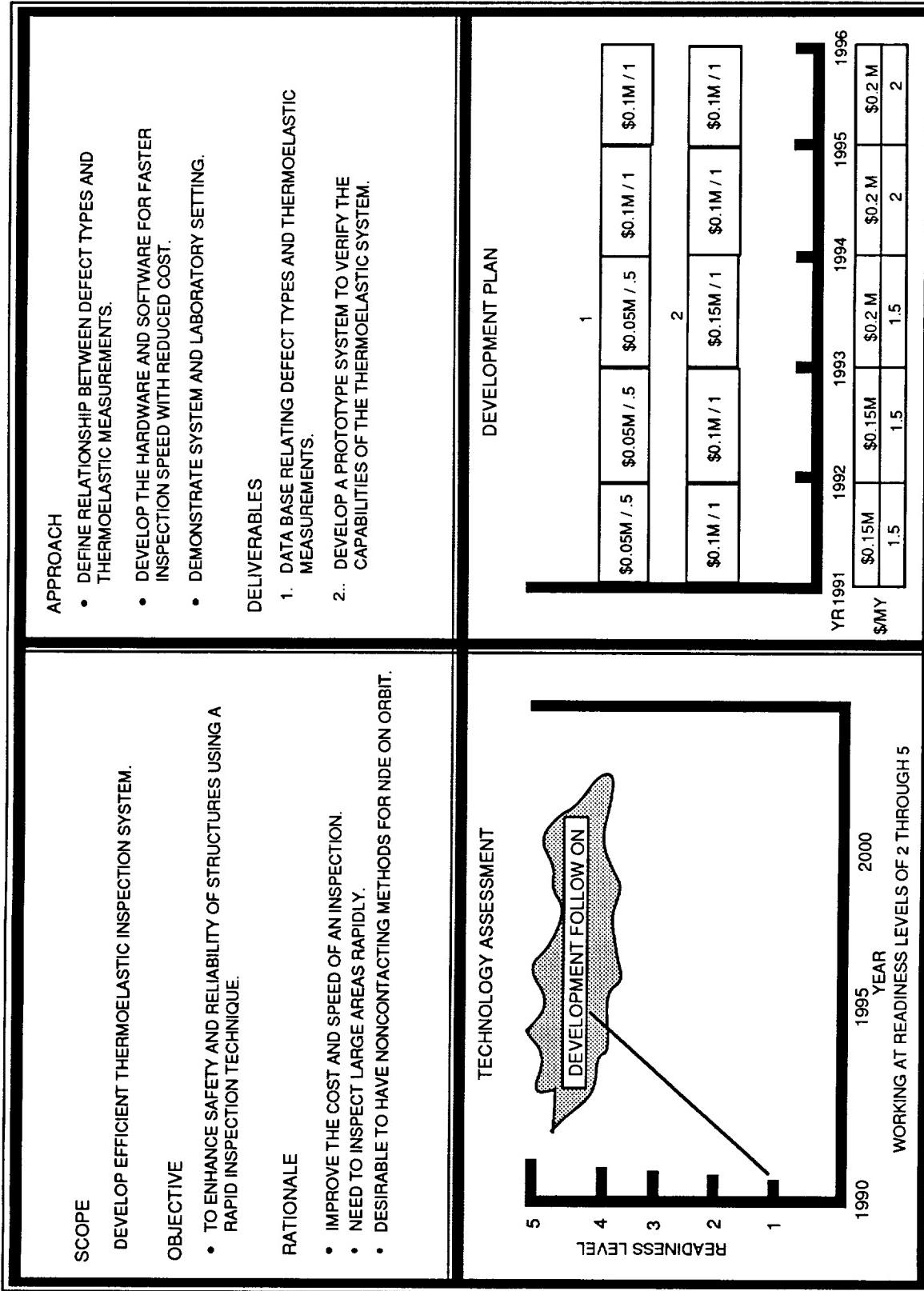


### DEVELOPMENT PLAN

YR	1991	1992	1993	1994	1995	1996
\$/MY	\$0.15 M / 1	\$0.2 M / 2	\$0.2 M / 2	\$0.2 M / 2	\$0.15 M / 2	
	1	1	1	1	1	

## Advanced NDE Sensors for Critical Structures

E. MADARAS



LaRC GCTI Spacecraft Technologies

2.2 Structures and Control

Technology	NASA GCTI WBS	Proposal funding requirements, millions of dollars					
		FY90	FY91	FY92	FY93	FY94	FY95
Structures	2.21		2	4	7.5	9	
Pointing dynamics and control	2.22		6	6	8	12	15
Totals			8	10	15.5	21	15

## SPACECRAFT/PLATFORM THRUST - STRUCTURES

<p><b>SCOPE</b></p> <p>Develop components and stable platform/payload concepts to enable construction and operation of large Earth science platforms and precision reflectors with emphasis on geostationary applications.</p> <p><b>OBJECTIVE</b></p> <p>To develop new high-performance structures for platform/precision reflectors which enable multiple payload/platform combinations for 20 m - 80 m deployable mesh reflectors up to 40 GHZ, 10 m - 40 m solid surface reflectors to 220 GHZ, 10 m - 20 m deployable reflectors up to 90 GHZ, and other precision payloads.</p> <p><b>RATIONALE</b></p> <p>Current technology for 20 m - 30 m mesh antennas limited to less than 30 GHZ. For 200 GHZ, size is limited to 4 m. Interaction of multiple precision payloads will further limit system performance. Cannot presently validate in Earth environment. Need 20 - 30 percent weight reduction.</p>	<p><b>APPROACH</b></p> <p>Develop erectable and deployable concepts appropriate to 6 GHZ - 220 GHZ frequency range for reflectors and their combination with platforms.</p> <p>Enhance thermal, isolation, damping, and precision alignment characteristics by both passive and active means.</p> <p>Enhance analysis and ground test methodology and perform ground tests.</p> <p><b>DELIVERABLES</b></p> <ol style="list-style-type: none"> <li>1. Demonstrate 10 - 20 m, 40 - 90 GHZ deployable reflectors.</li> <li>2. Demonstrate 25 - 40 m, 220 GHZ erectable reflectors.</li> <li>3. Demonstrate platform bus structure and feed mast.</li> <li>4. Demonstrate large (100 m) class deployable mesh reflector.</li> </ol>																													
<p><b>TECHNOLOGY ASSESSMENT</b></p> <table border="1"> <thead> <tr> <th>YR 1991</th> <th>1992</th> <th>1993</th> <th>1994</th> <th>1995</th> </tr> </thead> <tbody> <tr> <td>\$M MY</td> <td>2</td> <td>4</td> <td>7.5</td> <td>9</td> </tr> <tr> <td></td> <td>5</td> <td>7</td> <td>9</td> <td>12</td> </tr> </tbody> </table> <p>WORKING AT READINESS LEVELS OF 2 THROUGH 5</p> <p><b>DEVELOPMENT PLAN SCHEDULE, DOLLARS, AND CIVIL-SERVICE MANPOWER</b></p> <table border="1"> <thead> <tr> <th>YR 1991</th> <th>1992</th> <th>1993</th> <th>1994</th> <th>1995</th> </tr> </thead> <tbody> <tr> <td>\$M MY</td> <td>2</td> <td>4</td> <td>7.5</td> <td>9</td> </tr> <tr> <td></td> <td>5</td> <td>7</td> <td>9</td> <td>12</td> </tr> </tbody> </table>	YR 1991	1992	1993	1994	1995	\$M MY	2	4	7.5	9		5	7	9	12	YR 1991	1992	1993	1994	1995	\$M MY	2	4	7.5	9		5	7	9	12
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**POINTING, DYNAMICS, AND CONTROL (PD&C)****SCOPE**

Develop and demonstrate precision pointing and stabilization concepts and components for integrated multipayload pointing.

**OBJECTIVE**

Establish enabling technology for the integrated design and implementation of precision control techniques of multiuser platforms and attendant payloads.

**APPROACH**

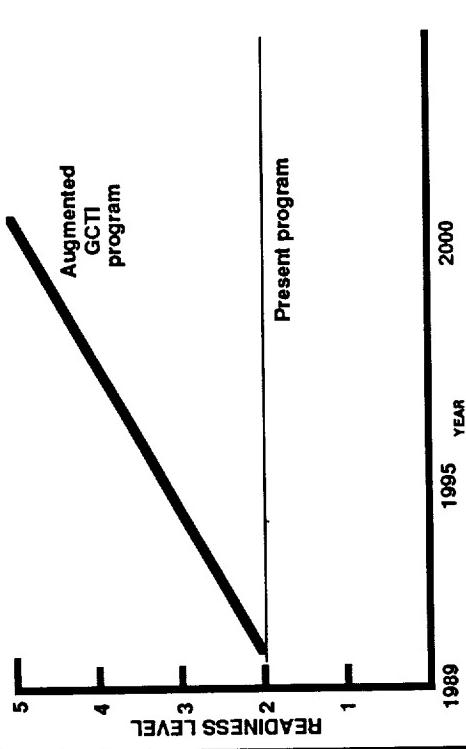
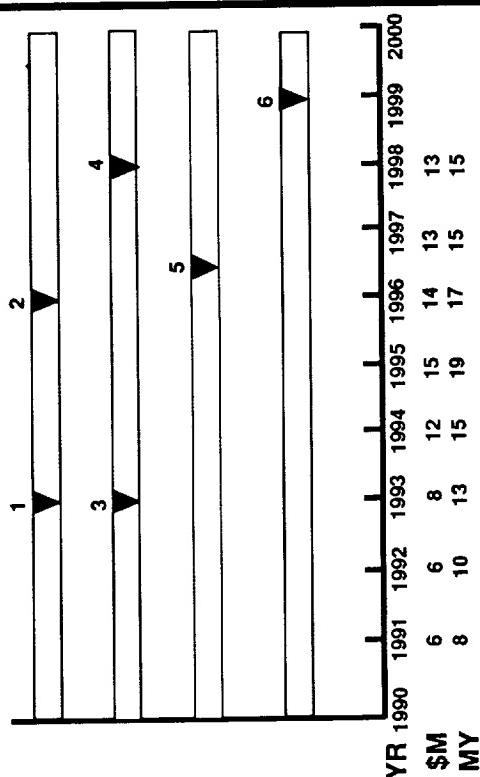
Acquire requirements; develop concepts, analysis and design methodology, and integrated system architecture for multiuser platforms and attendant payloads. Develop precision optical sensor/processors and payload auxiliary pointers for sub-arcsecond pointing and stabilization of science payloads. Integrate and demonstrate technologies through simulation and PD & C test bed.

**DELIVERABLES**

1. Integrated system design tools.
2. PD&C simulation.
3. Feature assisted pointing.
4. Auxiliary pointer for precision pointing and stabilization.
5. Advanced optical sensor/processors.
6. Technology readiness for multiuser platforms.

**RATIONALE**

Current pointing capability for multipayload spacecraft is limited to hundreds of arcseconds. Interaction between payloads provides further degradation. Need technology which will result in accuracies of a few arcseconds (approx. 3) with sub-arcsecond stability.

**TECHNOLOGY ASSESSMENT****SCHEDULE, DOLLARS, AND CIVIL-SERVICE MANPOWER**

YR	1990	1991	1992	1993	1994	1995	1996	1997	1998	1999	2000
\$M	6	6	8	12	15	14	13	13	13	13	15
MY	8	10	13	15	19	17	15	15	15	15	15

1995 YEAR  
WORKING AT READINESS LEVELS OF 2 THROUGH 5

## LaRC GCTI Spacecraft Technologies

### 2.3 Systems Analysis

Technology	NASA GCTI WBS	Proposal funding requirements, millions of dollars					
		FY90	FY91	FY92	FY93	FY94	FY95
Systems engineering analysis	2.31	1.5	5.5	7.0	9.0	34.0	37.0
Certification and verification	2.32		2.0	6.0	7.5	9.0	10.0
Operations	2.33		2.1	2.6	3.0	3.2	3.4
Nondestructive evaluation (NDE):							
Robotic servicing			0.3	0.25	0.2	0.25	0.25
Fastener recertification			0.15	0.15	0.15	0.15	0.05
Characterization of contaminants			0.2	0.2	0.2	0.3	0.2
Totals		1.5	10.25	16.2	20.05	46.9	50.9

## SYSTEMS ENGINEERING ANALYSIS AND INTEGRATION

<p><b>SCOPE</b> Identify technology needs/opportunities and develop integrated technology objectives for Earth science and operational systems through an end-to-end system study of overall system architecture. Conduct Phases A&amp;B System Level Study Efforts</p> <p><b>OBJECTIVES</b></p> <ul style="list-style-type: none"> <li>-To develop an optimum mix of LEO and GEO spacecraft and platform concepts to meet the science objectives at minimum cost to the Agency.</li> <li>- To determine economies of scale of spacecraft platforms and appropriate mission profiles.</li> <li>- To establish the high-priority enabling and enhancing technologies necessary to meet the science requirements and implement Phases A&amp;B R&amp;T efforts.</li> <li>- To develop the integrated multidisciplinary systems analysis software necessary to conduct trades and technology assessments.</li> </ul> <p><b>RATIONALE</b> Diverse science requirements call for a number of different types of spacecraft and mission options. The GCTI Spacecraft and antennas are of unprecedented size with stringent sensor performance and pointing requirements. Advanced technologies must be developed to meet these in-flight requirements. The necessary systems R&amp;T efforts must be accomplished during Phases A&amp;B to ensure the subsequent development of viable, low risk flight systems.</p>	<p><b>APPROACH</b> Interactive processes between the mission and science requirements, the spacecraft/antenna designs, and subsystem technologies are required to establish overall mission performance and to quantify the high payoff technologies.</p> <p><b>DELIVERABLES</b></p> <ol style="list-style-type: none"> <li>1. End-to-end systems studies of spacecraft and antenna concepts, definition of enhancing and enabling technologies, and quantification of on-orbit performance of the system to meet the science and mission requirements.</li> <li>2. Integrated multidisciplinary analysis software that couples the controls, structures, thermal, and electromagnetic technology areas with optimum spacecraft conceptual design programs to assess on-orbit performance. Does not include test hardware for validation.</li> <li>3. Systems studies and trades between mission options, spacecraft concepts, and technology options.</li> <li>4. Development of systems and technologies during Phases A and B.</li> </ol>	<p><b>DEVELOPMENT PLAN</b></p> <table border="1"> <thead> <tr> <th>Phase</th> <th>Start Year</th> <th>End Year</th> <th>FY \$M/MY</th> </tr> </thead> <tbody> <tr> <td>1</td> <td>1990</td> <td>1992</td> <td>1.5</td> </tr> <tr> <td>2</td> <td>1992</td> <td>1994</td> <td>2.0</td> </tr> <tr> <td>3</td> <td>1994</td> <td>1996</td> <td>2.0</td> </tr> <tr> <td>4</td> <td>1996</td> <td>1998</td> <td>2.0</td> </tr> </tbody> </table> <p><b>TECHNOLOGY ASSESSMENT</b></p> <p>Assumes availability of ground test hardware for technology validation</p> <p>Without Phases A&amp;B Development Program</p> <p>With Phases A&amp;B Program</p> <p>Pre-Phase A</p> <p>Phase A</p> <p>Phase B</p> <p>Mission Needs Window</p> <p>Readiness Level</p> <p>FY \$M/MY</p>	Phase	Start Year	End Year	FY \$M/MY	1	1990	1992	1.5	2	1992	1994	2.0	3	1994	1996	2.0	4	1996	1998	2.0
Phase	Start Year	End Year	FY \$M/MY																			
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2	1992	1994	2.0																			
3	1994	1996	2.0																			
4	1996	1998	2.0																			

**SPACECRAFT/PLATFORM THRUST – CERTIFICATION AND VERIFICATION**

<b>SCOPE</b> Certification and verification capabilities for predicting and identifying effects of environment and operations of the platform baseline throughout the integration, test, launch, and orbital lifetime.	<b>APPROACH</b> <ul style="list-style-type: none"> <li>• Develop new test techniques.</li> <li>• Develop nonintrusive measurement techniques and methods for both ground and space utilization.</li> <li>• Define and establish the required modeling tasks to analyze the measurement data.</li> <li>• Ground tests and flight test.</li> </ul>																																													
<b>OBJECTIVES</b> <ul style="list-style-type: none"> <li>• Develop new ground test techniques</li> <li>• Develop measurement techniques</li> <li>• Methods for modeling and predicting system effects</li> <li>• Coupling measured/predictions to enable corrective action</li> </ul>	<b>DELIVERABLES</b> <ol style="list-style-type: none"> <li>1. New test techniques</li> <li>2. Analytical methods</li> <li>3. Instrument components, measurement system, data system, hardware</li> <li>4. Ground test validation</li> <li>5. Flight demonstration</li> </ol>																																													
<b>RATIONALE</b> <ul style="list-style-type: none"> <li>• Large system cannot be ground tested</li> <li>• Interactive, multiple sensors require correlative data</li> <li>• Reliable, long-life operations will require knowledge, identification, and compensation to meet mission goals</li> </ul>	<b>TECHNOLOGY ASSESSMENT</b> 																																													
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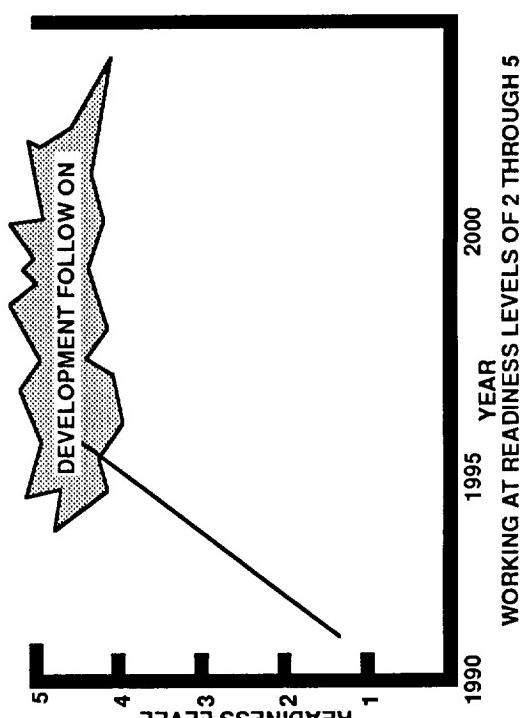
SPACECRAFT/PLATFORM OPERATIONS

L. GARRETT

SCOPE	ADVANCED TECHNOLOGY TO ACHIEVE HIGH EFFICIENCY AND EXTENDED PLATFORM LIFE.																																				
OBJECTIVE	<ul style="list-style-type: none"> <li>STANDARD INTERFACES FOR INSTRUMENT COMPATIBILITY.</li> <li>ROBOTICS AND AUTOMATION FOR SPACECRAFT SERVICING, TEST, AND UPGRADE</li> <li>INTERINSTRUMENT COMPATIBILITY FOR COMBINED OPERATIONS.</li> <li>ON-ORBIT INSPECTION, CLEANING, AND RESURFACING OF SENSORS AND OPTICS.</li> <li>MAXIMAL ON-ORBIT RECONFIGURATION FOR MISSION ENHANCEMENT.</li> </ul>																																				
RATIONALE	<ul style="list-style-type: none"> <li>NO CURRENT CAPABILITY FOR ON-ORBIT CHECKOUT, SERVICING, AND REMOTE ASSEMBLY.</li> <li>ALTERNATIVES ARE NEEDED TO EXTEND PLATFORM LIFE AND ENHANCE PERFORMANCE.</li> </ul>																																				
APPROACH	<ul style="list-style-type: none"> <li>REQUIREMENTS ANALYSIS, TECHNOLOGY DEVELOPMENT, AND GROUND AND ON-ORBIT TESTS OF REMOTE SERVICING, INSPECTION, REFURBISHMENT, AND PLATFORM UPGRADE.</li> <li>DEVELOP AUTOMATED METHODS FOR SCHEDULING AND SELECTION OF COMPLEMENTARY SENSOR SETS.</li> <li>DEFINE GROUND-BASED AND SPACE-BASED SUPPORT REQUIREMENTS FOR PLATFORM OPERATIONS.</li> </ul>																																				
DELIVERABLES	<ul style="list-style-type: none"> <li>DESIGN OF SYSTEMS FOR AUTOMATED INSPECTION, MAINTENANCE, AND SERVICING.</li> <li>INTERFACE REQUIREMENTS AND STANDARDS FOR SENSOR AND INSTRUMENTATION COMPATIBILITY.</li> <li>REFURBISHMENT MATERIALS AND METHODS FOR EXTENDED LIFETIME.</li> <li>AUTOMATED METHODS FOR INSTRUMENT PRIORITIZATION AND OPERATIONS SCHEDULING.</li> </ul>																																				
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	ASSEMBLY INSPECTION AND SERVICING	INTERFACE AND COMPATIBILITY	EXTENDED LIFE AND EFFICIENCY	AUTOMATED SCHEDULING AND PRIORITIZATION	\$M TOTAL*																																
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## E. MADARAS

### NDE Input for Robotic Servicing

<b>SCOPE</b> DEVELOP THE ABILITY TO OBTAIN NDE SERVICE FOR CAUSE INFORMATION.	<b>APPROACH</b> • DEVELOP METHODS FOR COUPLING ENERGY INTO MATERIALS AND STRUCTURES TO INTERROGATE THE SYSTEM, SUCH AS WITH NONCONTACTING OPTICAL OR THERMAL METHODS.  • INCORPORATE THESE METHODS INTO SYSTEMS THAT ARE ROBOT COMPATIBLE.																																																	
<b>OBJECTIVE</b>  • PROVIDE ROBOTIC NDE CAPABILITY FOR PRIORITIZATION OF SERVICING NEEDS AND REDUCE EVA REQUIREMENTS.	<b>DELIVERABLES</b> 1. DEVELOP THERMAL AND OPTICAL SYSTEMS THAT CAN PERFORM NDE ON SPACE STRUCTURES WITHOUT REQUIRING COUPLANTS OR CONTACT AS IS THE CASE FOR EARTH-BASED NDE SYSTEMS.  2. DEVELOP PROTOTYPE SYSTEMS THAT CAN BE DEMONSTRATED WITH ROBOTICS.																																																	
<b>RATIONALE</b>  • DEVELOP NDE CAPABILITIES THAT ARE COMPATIBLE WITH ROBOTICS TO IDENTIFY AND ASSESS PROBLEMS AND TO EVALUATE THEIR REPAIR. • ALLOW FOR THE MONITORING OF MATERIAL CONDITIONS AND DEGRADATIONS SUCH AS INSPECTING THERMAL CONTROL COATINGS AND IMPACT DAMAGE WITHOUT EVA ACTIVITIES.	<b>TECHNOLOGY ASSESSMENT</b>    <b>DEVELOPMENT PLAN</b> <table border="1"><thead><tr><th>YR</th><th>1991</th><th>1992</th><th>1993</th><th>1994</th><th>1995</th><th>1996</th></tr></thead><tbody><tr><th>\$/MY</th><td>\$0.3 M</td><td>\$0.25 M</td><td>\$0.2 M</td><td>\$0.25 M</td><td>\$0.25 M</td><td>\$0.25 M</td></tr><tr><td>1</td><td>\$0.3 M / 3</td><td>\$0.25 M / 3</td><td>\$0.1 M / 1</td><td></td><td></td><td></td></tr><tr><td>2</td><td></td><td></td><td>\$0.1 M / 1</td><td>\$0.25 M / 2</td><td>\$0.25 M / 2</td><td></td></tr><tr><td>3</td><td></td><td></td><td></td><td></td><td></td><td></td></tr><tr><td>4</td><td></td><td></td><td></td><td></td><td></td><td></td></tr><tr><td>5</td><td></td><td></td><td></td><td></td><td></td><td></td></tr></tbody></table>	YR	1991	1992	1993	1994	1995	1996	\$/MY	\$0.3 M	\$0.25 M	\$0.2 M	\$0.25 M	\$0.25 M	\$0.25 M	1	\$0.3 M / 3	\$0.25 M / 3	\$0.1 M / 1				2			\$0.1 M / 1	\$0.25 M / 2	\$0.25 M / 2		3							4							5						
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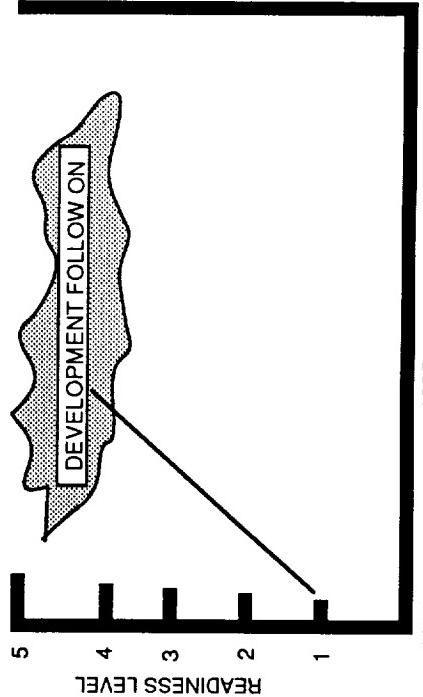
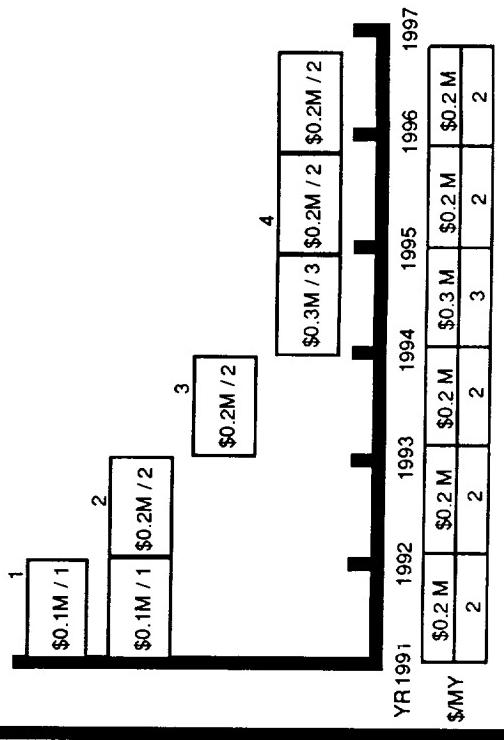
## Fastener Recertification in Space

E. MADARAS

<b>SCOPE</b> DEVELOP FASTENER CERTIFICATION AND RECERTIFICATION TECHNIQUES FOR SPACE-BASED NDE APPLICATIONS.	<b>APPROACH</b> <ul style="list-style-type: none"> <li>• DEVELOP METHODS SUCH AS ACOUSTOELASTIC AND THERMOELECTRIC FOR APPLICATION TO FASTENER QUALITY.</li> <li>• DEVELOP AN ACCURATE METHOD TO EVALUATE THE LOADS ON CRITICAL FASTENERS.</li> </ul>																													
<b>OBJECTIVE</b> <ul style="list-style-type: none"> <li>• DEVELOP A MORE RELIABLE SYSTEM FOR MONITORING, CERTIFYING, OR RECERTIFYING FASTENERS.</li> </ul>	<b>DELIVERABLES</b> <ol style="list-style-type: none"> <li>1. DEVELOP BOTH AN ACOUSTOELASTIC AND A THERMOELECTRIC SYSTEM FOR EVALUATING FASTENER QUALITY.</li> <li>2. DEVELOP A PROTOTYPE PULSED PHASE LOCK LOOP SYSTEM THAT COULD BE USED IN SPACE AND WHICH COULD MEASURE CRITICAL FASTENER LOADS WITH HIGH ACCURACY FOR FASTENER CERTIFICATION OR RECERTIFICATION.</li> </ol>																													
<b>RATIONALE</b> <ul style="list-style-type: none"> <li>• NEED A SYSTEM TO IDENTIFY COUNTERFEIT FASTENERS.</li> <li>• NEED A SYSTEM THAT CAN ACCURATELY MEASURE FASTENER LOADS, EVEN IN A SPACE-BASED ENVIRONMENT.</li> </ul>	<b>TECHNOLOGY ASSESSMENT</b>																													
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## Quantitative Surface Characterization Of Contaminants

E. MADARAS

<b>SCOPE</b> DEVELOP QUANTITATIVE INSTRUMENTATION FOR DETECTION OF SURFACE CONTAMINANTS ON CRITICAL AND SENSITIVE COMPONENTS.  <b>OBJECTIVE</b> • TO ENSURE CONTAMINATION SENSITIVE SURFACES ARE CLEAN. • IDENTIFY CONTAMINANTS QUANTITATIVELY.  <b>RATIONALE</b> • CONTAMINANTS REDUCE THE EFFICIENCY OF OPTICAL SYSTEMS • CONTAMINANTS CAN BE THE SOURCE OF PLASM GENERATION AND ELECTRICAL DISCHARGES THAT INTERFERE OR DAMAGE SENSITIVE ELECTRONIC EQUIPMENT.	<b>APPROACH</b> <ul style="list-style-type: none"> <li>• DEVELOP A NARROW BAND FLUORESCENCE SYSTEM CAPABLE OF DETECTING MINUTE QUANTITIES OF CONTAMINANTS.</li> <li>• EVALUATE THE SYSTEM ON A SERIES OF COMMON CONTAMINANTS THAT WILL DEFINE THE SYSTEM ACCURACY.</li> <li>• EXPAND THE SYSTEM TO MULTIPLE BANDS FOR ACCURATE, QUANTITATIVE IDENTIFICATION OF CONTAMINANTS</li> </ul>	<b>DELIVERABLES</b> <ol style="list-style-type: none"> <li>1. ASSESSMENT OF TECHNOLOGY FOR QUANTITATIVE SYSTEM.</li> <li>2. INCORPORATE APPROPRIATE EXCITATION SYSTEMS.</li> <li>3. EVALUATION OF NARROW BAND SYSTEM.</li> <li>4. DEVELOP AND DEMONSTRATE A MULTIBAND SYSTEM.</li> </ol>	<b>TECHNOLOGY ASSESSMENT</b> 	<b>DEVELOPMENT PLAN</b>  <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr> <th>YR 1991</th> <th>1992</th> <th>1993</th> <th>1994</th> <th>1995</th> <th>1996</th> <th>1997</th> </tr> </thead> <tbody> <tr> <td>\$M/Y</td> <td>\$0.2 M</td> <td>\$0.2 M</td> <td>\$0.2 M</td> <td>\$0.3 M</td> <td>\$0.2 M</td> <td>\$0.2 M</td> </tr> <tr> <td></td> <td>2</td> <td>2</td> <td>2</td> <td>3</td> <td>2</td> <td>2</td> </tr> </tbody> </table>	YR 1991	1992	1993	1994	1995	1996	1997	\$M/Y	\$0.2 M	\$0.2 M	\$0.2 M	\$0.3 M	\$0.2 M	\$0.2 M		2	2	2	3	2	2
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LaRC GCTI Spacecraft Technologies

2.4 Power

Technology	NASA GCTI WBS	Proposal funding requirements, millions of dollars					
		FY90	FY91	FY92	FY93	FY94	FY95
Electronics nondestructive evaluation (NDE)		0.2	0.25	0.2	0.25	0.25	0.25
Totals		0.2	0.25	0.2	0.25	0.25	0.25

## E. MADARAS

### Electronics NDE

<b>SCOPE</b> DEVELOP ELECTRONICS NDE METHODS FOR CRITICAL ELECTRONIC ELEMENTS.	<b>APPROACH</b> <ul style="list-style-type: none"><li>• TO EXTEND OUR CURRENT TECHNIQUES IN NDE (THERMAL WAVE ANALYSIS/TECHNOLOGY, BONDING, FATIGUE, PROCESS CONTROL MONITORS, AND INTEGRATED SENSORS) TO APPLICATIONS OF ELECTRONICS NDE.</li></ul>														
<b>OBJECTIVE</b> <ul style="list-style-type: none"><li>• DEVELOP HIGHER RELIABILITY ELECTRONICS AND SYSTEMS.</li></ul>	<b>DELIVERABLES</b> <ul style="list-style-type: none"><li>1. METHODS TO DETECT ELECTRONIC COMPONENT PROBLEMS AND PROVIDE FOR REAL-TIME MONITORS FOR ELECTRONICS NDE "HEALTH" MONITORING.</li></ul>														
<b>RATIONALE</b> <ul style="list-style-type: none"><li>• INTRODUCE ELECTRONICS RELIABILITY RESEARCH INTO PROGRAM.</li><li>• WILL BUILD ON THE EXISTING ELECTRONICS NDE PROGRAM AT LANGLEY.</li><li>• WILL TAKE ADVANTAGE OF NEW LEAD NDE CENTER TECHNOLOGY IN ULTRASONICS, MAGNETICS, THERMAL, X-RAY, AND FIBER OPTICS.</li></ul>	<b>TECHNOLOGY ASSESSMENT</b> <p>Development Follow On</p>														
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LaRC GCTI Spacecraft Technologies

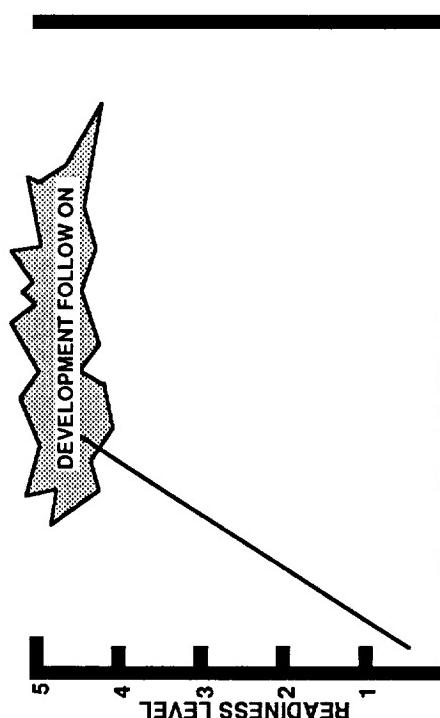
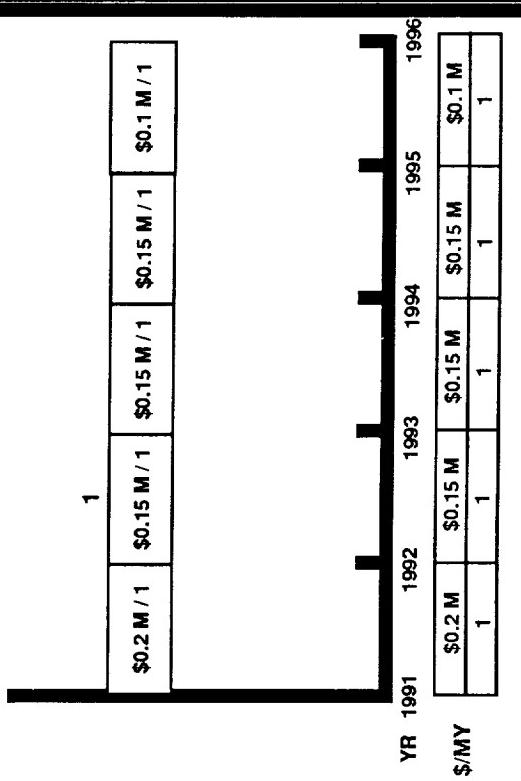
2.5 Propulsion

Technology	NASA GCTI WBS	Proposal funding requirements, millions of dollars					
		FY90	FY91	FY92	FY93	FY94	FY95
Thermal NDE for pressurized vessels		0.15	0.15	0.2	0.3	0.1	
Weld inspection		0.2	0.15	0.15	0.15	0.15	0.1
Totals		0.35	0.3	0.35	0.45	0.2	

## Thermal NDE for Pressurized Vessels

<p><b>SCOPE</b> DEVELOP AN IMPROVED THERMAL INSPECTION SYSTEM FOR PRESSURIZED VESSELS.</p> <p><b>OBJECTIVE</b></p> <ul style="list-style-type: none"> <li>DEVELOP THE ABILITY TO INSPECT FOR STRESS DISTRIBUTIONS, CRACKS, AND LEAKS OVER LARGE AREAS AND UNDER LOAD.</li> </ul> <p><b>RATIONALE</b></p> <ul style="list-style-type: none"> <li>REDUCE COST OF INSPECTION BY INSPECTING LARGE AREAS IN A SHORT PERIOD OF TIME.</li> <li>IMPROVE SAFETY AND RELIABILITY OF PROPULSION SYSTEMS.</li> </ul>	<p><b>APPROACH</b></p> <ul style="list-style-type: none"> <li>DEVELOP A DATA BASE BETWEEN DEFECT TYPES AND MEASUREMENT RESOLUTION.</li> <li>IMPROVE HARDWARE AND SOFTWARE FOR FASTER INSPECTION SPEED WITH REDUCED COST.</li> </ul> <p><b>DELIVERABLES</b></p> <ol style="list-style-type: none"> <li>A DATA BASE ON THE ACCURACY AND RELIABILITY OF THE METHOD.</li> <li>A PROTOTYPE SYSTEM THAT WILL HAVE IMPROVED SPEED.</li> </ol>	<p><b>TECHNOLOGY ASSESSMENT</b></p> <p><b>DEVELOPMENT PLAN</b></p> <table border="1" style="width: 100%; border-collapse: collapse; text-align: center;"> <thead> <tr> <th style="width: 10%;">YR</th> <th style="width: 10%;">1991</th> <th style="width: 10%;">1992</th> <th style="width: 10%;">1993</th> <th style="width: 10%;">1994</th> <th style="width: 10%;">1995</th> <th style="width: 10%;">1996</th> </tr> </thead> <tbody> <tr> <td style="width: 10%;"><b>\$/M/Y</b></td> <td>\$0.15 M / 1</td> <td>\$0.15 M / 1</td> <td>\$0.15 M / 1</td> <td>\$0.1 M / 1</td> <td>\$0.3 M / 2</td> <td>\$0.1 M / 1</td> </tr> <tr> <td style="width: 10%;"><b>READYNESS LEVEL</b></td> <td>1</td> <td>2</td> <td>3</td> <td>4</td> <td>5</td> <td>5</td> </tr> </tbody> </table> <p>WORKING AT READINESS LEVELS OF 2 THROUGH 5</p>	YR	1991	1992	1993	1994	1995	1996	<b>\$/M/Y</b>	\$0.15 M / 1	\$0.15 M / 1	\$0.15 M / 1	\$0.1 M / 1	\$0.3 M / 2	\$0.1 M / 1	<b>READYNESS LEVEL</b>	1	2	3	4	5	5
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<b>READYNESS LEVEL</b>	1	2	3	4	5	5																	

## Weld Inspection of Pressurized Vessels

SCOPE DEVELOP IMPROVED NDE INSPECTION SYSTEM FOR MICROCRACKS NEAR WELDS IN PRESSURIZED VESSELS.		APPROACH • DEVELOP A SYSTEM THAT CAN INSPECT FOR MICROCRACKS AND OTHER WELDMENT PROBLEMS.	DELIVERABLES 1. A PROTOTYPE SYSTEM THAT WILL HAVE THE CAPABILITY TO INSPECT FOR WELD INTEGRITY.																					
<b>OBJECTIVE</b> <ul style="list-style-type: none"> <li>• PROVIDE A PRACTICAL ABILITY TO INSPECT WELD INTEGRITY, NEARBY STRESS DISTRIBUTIONS, AND HYDROGEN-RELATED METAL PROBLEMS.</li> </ul> <b>RATIONALE</b> <ul style="list-style-type: none"> <li>• NO SINGLE NDE TECHNIQUE HAS BEEN SUCCESSFUL IN EVALUATING WELD DEFECTS IN PRACTICAL MEASUREMENT SYSTEMS.</li> <li>• PROVIDE A QUANTITATIVE ASSESSMENT OF MECHANICAL PROPERTIES OF CRITICAL PARTS.</li> <li>• ENHANCE SAFETY AND RELIABILITY OF PROPULSION SYSTEMS.</li> </ul>	<b>TECHNOLOGY ASSESSMENT</b> 	<b>DEVELOPMENT PLAN</b> <table border="1" style="width: 100%; border-collapse: collapse;"> <tr> <td style="width: 10%;">YR</td> <td style="width: 10%;">1991</td> <td style="width: 10%;">1992</td> <td style="width: 10%;">1993</td> <td style="width: 10%;">1994</td> <td style="width: 10%;">1995</td> <td style="width: 10%;">1996</td> </tr> <tr> <td>\$/MY</td> <td>\$0.2 M</td> <td>\$0.15 M</td> <td>\$0.15 M / 1</td> <td>\$0.15 M / 1</td> <td>\$0.15 M / 1</td> <td>\$0.1 M</td> </tr> <tr> <td></td> <td>1</td> <td>1</td> <td>1</td> <td>1</td> <td>1</td> <td>1</td> </tr> </table> <p style="text-align: center;">WORKING AT READINESS LEVELS OF 2 THROUGH 5</p>	YR	1991	1992	1993	1994	1995	1996	\$/MY	\$0.2 M	\$0.15 M	\$0.15 M / 1	\$0.15 M / 1	\$0.15 M / 1	\$0.1 M		1	1	1	1	1	1	
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## LaRC GCTI Spacecraft Technologies

### 2.6 Thermal Control

Technology	NASA GCTI WBS	Proposal funding requirements, millions of dollars					
		FY90	FY91	FY92	FY93	FY94	FY95
NDE for thermal control		0.2	0.2	0.3	0.3	0.3	0.3
Thermoelastic NDE		0.15	0.15	0.2	0.3	0.1	
Totals		0.35	0.35	0.5	0.6	0.4	

## NDE For Thermal Control Systems

E. MADARAS

<b>SCOPE</b> DEVELOP ADVANCED OPTICAL METHODS FOR TESTING THERMAL SYSTEMS.	<b>APPROACH</b> <ul style="list-style-type: none"> <li>ACQUIRE LASERS AND DETECTORS WITH HIGH BANDWIDTHS.</li> <li>DEVELOP REAL-TIME IMAGE ANALYSIS ALGORITHMS FOR STRESS MAPS.</li> </ul>														
<b>OBJECTIVE</b> <ul style="list-style-type: none"> <li>ENABLE ACCURATE EVALUATION OF STRESSES IN THERMAL CONTROL SYSTEMS.</li> </ul>	<b>DELIVERABLES</b> <ol style="list-style-type: none"> <li>1. A NONCONTACTING METHOD TO DETECT STRESS MAPS OF SURFACES WITH HIGH RESOLUTION IN A REASONABLE AMOUNT OF TIME AND TO MAP OUT STRUCTURAL IRREGULARITIES OF THERMAL CONTROL SYSTEMS.</li> </ol>														
<b>RATIONALE</b> <ul style="list-style-type: none"> <li>TECHNOLOGY WILL PROVIDE HIGH RESOLUTION STRESS MAPS OF SURFACES.</li> <li>PROVIDE NONCONTACTING METHOD TO MONITOR STRUCTURAL IRREGULARITIES AND DISTORTIONS.</li> </ul>	<b>TECHNOLOGY ASSESSMENT</b>														
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## Thermoelastic NDE For Thermal Control Systems

<p><b>SCOPE</b> DEVELOP FAST THERMOELASTIC INSPECTION SYSTEM.</p> <p><b>OBJECTIVE</b></p> <ul style="list-style-type: none"> <li>• THE DETECTION OF DEFECTS LOCATED IN JOINTS AND BONDS.</li> </ul>	<p><b>APPROACH</b></p> <ul style="list-style-type: none"> <li>• DEVELOP A DATA BASE BETWEEN DEFECT TYPES AND MATERIALS MEASUREMENTS.</li> <li>• IMPROVE HARDWARE AND SOFTWARE FOR FASTER INSPECTION SPEED WITH REDUCED COST.</li> </ul>	<p><b>DELIVERABLES</b></p> <ol style="list-style-type: none"> <li>1. A DATA BASE ON THE ACCURACY AND RELIABILITY OF THE METHOD.</li> <li>2. A PROTOTYPE SYSTEM THAT WILL HAVE IMPROVED SPEED.</li> </ol>	<p><b>RATIONALE</b></p> <ul style="list-style-type: none"> <li>• REDUCE COST OF INSPECTION BY INSPECTING LARGE AREAS IN A SHORT PERIOD OF TIME.</li> <li>• IMPROVE SAFETY AND RELIABILITY OF THERMAL SYSTEMS.</li> </ul>	<p><b>TECHNOLOGY ASSESSMENT</b></p> <p>1990      1995      YEAR      2000</p> <p>1      2      3      4      5</p> <p>READYNESS LEVEL</p> <p>DEVELOPMENT FOLLOW ON</p>	<p><b>DEVELOPMENT PLAN</b></p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="text-align: left;">YR</th> <th style="text-align: left;">1991</th> <th style="text-align: left;">1992</th> <th style="text-align: left;">1993</th> <th style="text-align: left;">1994</th> <th style="text-align: left;">1995</th> <th style="text-align: left;">1996</th> </tr> </thead> <tbody> <tr> <td style="text-align: left;">\$/M</td> <td>\$0.15 M</td> <td>\$0.15 M</td> <td>\$0.15 M</td> <td>\$0.2 M</td> <td>\$0.3 M</td> <td>\$0.1 M</td> </tr> <tr> <td style="text-align: left;">\$/M Y</td> <td>1</td> <td>1</td> <td>2</td> <td>2</td> <td>1</td> <td>1</td> </tr> <tr> <td style="text-align: left;">1</td> <td colspan="2"></td> <td colspan="2"></td> <td colspan="2">2</td> </tr> <tr> <td style="text-align: left;">\$0.15 M / 1</td> <td colspan="2">\$0.15 M / 1</td> <td colspan="2">\$0.1 M / 1</td> <td colspan="2">\$0.3 M / 2</td> </tr> <tr> <td style="text-align: left;">\$0.1 M / 1</td> <td colspan="2"></td> <td colspan="2"></td> <td colspan="2">\$0.1 M / 1</td> </tr> </tbody> </table> <p>WORKING AT READINESS LEVELS OF 2 THROUGH 5</p>	YR	1991	1992	1993	1994	1995	1996	\$/M	\$0.15 M	\$0.15 M	\$0.15 M	\$0.2 M	\$0.3 M	\$0.1 M	\$/M Y	1	1	2	2	1	1	1					2		\$0.15 M / 1	\$0.15 M / 1		\$0.1 M / 1		\$0.3 M / 2		\$0.1 M / 1					\$0.1 M / 1	
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## Appendix C

### Data and Information Systems Technology Proposals (WBS 3.0)

#### LaRC GCTI Information Technologies

##### 3.1 Systems

Technology	NASA GCTI WBS	Proposal funding requirements, millions of dollars					
		FY90	FY91	FY92	FY93	FY94	FY95
Tool development and integration	3.11-2		0.45	0.65	0.95	0.6	0.2
Architectures	3.11-1		0.8	1.5	1.0	0.5	
Software engineering	3.12-4		1.0	1.3	2.0	1.5	1.0
Dependable software	3.12-5		0.7	1.1	1.2	1.1	0.8
Software library and reuse	3.12-3		0.5	1.0	1.0	1.0	1.0
Automated parallel software	3.12-1		0.5	1.0	2.0	1.0	0.5
			3.95	6.55	8.15	5.7	3.5

## DATA SYSTEMS DESIGN & EVALUATION TOOL DEVELOPMENT & INTEGRATION

<p><b>SCOPE</b> INTEGRATE DESIGN TOOLS IN AN ENVIRONMENT TO SUPPORT AN EFFECTIVE DESIGN METHOD.</p> <p><b>OBJECTIVES</b></p> <ul style="list-style-type: none"> <li>• IDENTIFY / REFINER METHODOLOGY FOR EFFECTIVE DATA SYSTEM DESIGN.</li> <li>• DETERMINE EXISTING / NEEDED TOOLS TO SUPPORT METHODOLOGY.</li> <li>• INTEGRATE TOOLS INTO COMMON ENVIRONMENT TO SUPPORT METHOD.</li> </ul> <p><b>RATIONALE</b> EXISTING COMPUTER-AIDED DESIGN (CAD/CAE) DESIGN TOOLS ARE NOT COMPATIBLE WITH EACH OTHER, NOR DO THEY COLLECTIVELY ADDRESS ALL COMPUTING SYSTEMS DESIGN PHASES</p>	<p><b>APPROACH</b></p> <p>USE AN EXISTING DESIGN METHODOLOGY ON GCT APPLICATION TO IDENTIFY EXISTING / NEEDED TOOLS TO SUPPORT METHOD. DEVELOP NEW TOOLS AND INTEGRATE WITH EXISTING ONES.</p>	<p><b>DELIVERABLES</b></p> <ol style="list-style-type: none"> <li>1. ENHANCED DESIGN METHOD FOR GCT DATA SYSTEMS.</li> <li>2. IDENTIFY APPLICABLE EXISTING TOOLS.</li> <li>3. GENERATE REQUIREMENTS FOR NEW TOOLS.</li> <li>4. BUILD NEW TOOLS IDENTIFIED IN 3.</li> <li>5. INTEGRATED TOOL SET SUPPORTING METHOD.</li> </ol>	<p><b>DEVELOPMENT PLAN</b></p> <table border="1"> <thead> <tr> <th>Year</th> <th>Task 1</th> <th>Task 2</th> <th>Task 3</th> <th>Task 4</th> <th>Task 5</th> <th>Total</th> </tr> </thead> <tbody> <tr> <td>1989</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td>0.45</td> </tr> <tr> <td>1990</td> <td>0.3M</td> <td></td> <td></td> <td></td> <td></td> <td>0.45</td> </tr> <tr> <td>1991</td> <td></td> <td>0.15M</td> <td></td> <td></td> <td></td> <td>0.6</td> </tr> <tr> <td>1992</td> <td></td> <td></td> <td>0.1M</td> <td></td> <td></td> <td>0.95</td> </tr> <tr> <td>1993</td> <td></td> <td></td> <td></td> <td>0.15M</td> <td></td> <td>0.2</td> </tr> <tr> <td>1994</td> <td></td> <td></td> <td></td> <td></td> <td>0.4M</td> <td>0.4M</td> </tr> <tr> <td>1995</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td>0.2M</td> </tr> <tr> <td>2007</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td>2.85</td> </tr> </tbody> </table>	Year	Task 1	Task 2	Task 3	Task 4	Task 5	Total	1989						0.45	1990	0.3M					0.45	1991		0.15M				0.6	1992			0.1M			0.95	1993				0.15M		0.2	1994					0.4M	0.4M	1995						0.2M	2007						2.85
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## GLOBAL DISTRIBUTED COMPUTING ARCHITECTURES

N. MURRAY

<p><b>SCOPE</b> RESEARCH AND DEVELOP THE ARCHITECTURAL CONCEPT FOR ONBOARD PROCESSING ACROSS MULTIPLE OBSERVATION SPACECRAFT.</p> <p><b>OBJECTIVES</b></p> <ul style="list-style-type: none"> <li>• ASSESS GLOBAL SATELLITE SCIENCE REQUIREMENTS AND ALGORITHMS FOR ONBOARD PROCESSING.</li> <li>• CREATE SIMULATION CAPABILITY TO EVALUATE ALGORITHMS AND ARCHITECTURES.</li> <li>• EVALUATE ARCHITECTURES / ALGORITHMS - RECOMMEND ARCHITECTURE CONCEPT.</li> </ul> <p><b>RATIONALE</b> ENABLE SCIENCE USERS DIRECT ACCESS TO SENSOR DATA AND GLOBAL INFORMATION.</p>	<p><b>APPROACH</b> USE EXISTING SIMULATIVE PROGRAMS AND AUGMENT WHERE NECESSARY; CREATE AND EVALUATE NEW, INNOVATIVE, AND ORIGINAL ARCHITECTURAL CONCEPTS TO MEET UNIQUE NASA REQUIREMENTS.</p> <p><b>DELIVERABLES</b></p> <ol style="list-style-type: none"> <li>1. ASSESS SCIENCE REQUIREMENTS AND ALGORITHMS.</li> <li>2. CREATE EMULATIVE / SIMULATIVE ABILITY.</li> <li>3. ARCHITECTURAL CONCEPT EVALUATIONS.</li> </ol>	<p><b>DEVELOPMENT PLAN</b></p> <table border="1"> <thead> <tr> <th>Week</th> <th>Task</th> <th>Cost (\$M)</th> </tr> </thead> <tbody> <tr> <td>90</td> <td>1</td> <td>0.3M</td> </tr> <tr> <td>91</td> <td>1, 2</td> <td>0.5M</td> </tr> <tr> <td>92</td> <td>2, 3</td> <td>0.5M</td> </tr> <tr> <td>93</td> <td>3</td> <td>0.5M</td> </tr> <tr> <td>94</td> <td></td> <td></td> </tr> <tr> <td>95</td> <td></td> <td></td> </tr> <tr> <td>96</td> <td></td> <td></td> </tr> <tr> <td>97</td> <td></td> <td></td> </tr> <tr> <td>98</td> <td></td> <td></td> </tr> <tr> <td>99</td> <td></td> <td></td> </tr> <tr> <td>2000</td> <td></td> <td></td> </tr> <tr> <td>2001</td> <td></td> <td></td> </tr> <tr> <td>2002</td> <td></td> <td></td> </tr> <tr> <td>2003</td> <td></td> <td></td> </tr> <tr> <td>2004</td> <td></td> <td></td> </tr> <tr> <td>2005</td> <td></td> <td></td> </tr> <tr> <td>2006</td> <td></td> <td></td> </tr> <tr> <td>2007</td> <td></td> <td></td> </tr> </tbody> </table> <p><b>TECHNOLOGY ASSESSMENT</b></p> <table border="1"> <thead> <tr> <th>Year</th> <th>Present Program Readiness Level</th> <th>Mission Technology Needs Readiness Level</th> <th>With Augmentation Readiness Level</th> </tr> </thead> <tbody> <tr> <td>1989</td> <td>1</td> <td>1</td> <td>1</td> </tr> <tr> <td>1995</td> <td>4</td> <td>4</td> <td>4</td> </tr> <tr> <td>2001</td> <td>7</td> <td>7</td> <td>6</td> </tr> <tr> <td>2007</td> <td>8</td> <td>8</td> <td>7</td> </tr> </tbody> </table> <p><b>TOTAL \$M/YR</b></p> <table border="1"> <thead> <tr> <th>Year</th> <th>Total Cost (\$M/YR)</th> </tr> </thead> <tbody> <tr> <td>1989</td> <td>0.8</td> </tr> <tr> <td>1995</td> <td>1.5</td> </tr> <tr> <td>2001</td> <td>1.0</td> </tr> <tr> <td>2007</td> <td>0.5</td> </tr> <tr> <td><b>TOTAL</b></td> <td><b>3.8</b></td> </tr> </tbody> </table>	Week	Task	Cost (\$M)	90	1	0.3M	91	1, 2	0.5M	92	2, 3	0.5M	93	3	0.5M	94			95			96			97			98			99			2000			2001			2002			2003			2004			2005			2006			2007			Year	Present Program Readiness Level	Mission Technology Needs Readiness Level	With Augmentation Readiness Level	1989	1	1	1	1995	4	4	4	2001	7	7	6	2007	8	8	7	Year	Total Cost (\$M/YR)	1989	0.8	1995	1.5	2001	1.0	2007	0.5	<b>TOTAL</b>	<b>3.8</b>
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## SOFTWARE ENGINEERING ENVIRONMENT FOR GCTI

<b>SCOPE</b>	<p>PROVIDE AN INTEGRATED SET OF TOOLS FOR THE DEVELOPMENT OF GLOBAL CHANGE APPLICATION SOFTWARE THROUGHOUT THE LIFE CYCLE.</p>	<b>APPROACH</b>	<p>DEVELOP EMERGING TECHNOLOGIES SUCH AS REUSABILITY AND AUTOMATED PROGRAMMING. COMBINE WITH AUTOMATED SPECIFICATION AND ANALYSIS TECHNIQUES AND PROVIDE PROJECT MANAGEMENT CAPABILITIES TO PRODUCE AN INTEGRATED SOFTWARE ENVIRONMENT.</p>																								
<b>OBJECTIVES</b>	<ul style="list-style-type: none"> <li>• INTEGRATION OF AUTOMATED DEVELOPMENT TECHNIQUES AND REUSABLE LIBRARY.</li> <li>• AUTOMATED PROJECT AND CONFIGURATION MANAGEMENT.</li> <li>• EFFICIENT AND TRACEABLE MAINTENANCE.</li> </ul>	<b>DELIVERABLES</b>	<ol style="list-style-type: none"> <li>1. NEEDED TOOLS / CAPABILITIES IDENTIFIED.</li> <li>2. SPECIFICATION AND ANALYSIS TOOLS.</li> <li>3. AUTOMATED SPECIFICATION AND PROGRAMMING SUBSYSTEM.</li> <li>4. INTEGRATED LIBRARY / PROGRAMMING SYSTEM.</li> </ol>																								
<b>RATIONALE</b>	<p>REDUCED LIFE-CYCLE COSTS AND INCREASED SOFTWARE QUALITY THROUGH AUTOMATED DEVELOPMENT AND MAINTENANCE.</p>	<b>TECHNOLOGY ASSESSMENT</b>																									
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DEPENDABLE SOFTWARE																																																																													
<p><b>SCOPE</b> DEVELOP AND INTEGRATE TECHNOLOGIES NEEDED TO PRODUCE SOFTWARE THAT IS CORRECT, ROBUST, SAFE, AND FAULT TOLERANT.</p> <p><b>OBJECTIVES</b></p> <ul style="list-style-type: none"> <li>• IDENTIFY EFFECTIVE FAULT AVOIDANCE METHODS FOR SOFTWARE DEVELOPMENT.</li> <li>• DEVELOP AND VALIDATE RELIABILITY AND SAFETY ANALYSIS TECHNIQUES.</li> <li>• DEVELOP AUTOMATED TESTING METHODS.</li> </ul> <p><b>RATIONALE</b> INCREASED SOFTWARE DEPENDABILITY THROUGH QUALITY DESIGN, ANALYSIS, AND AUTOMATED TESTING.</p>	<p><b>APPROACH</b> DEVELOP AND ASSESS TECHNOLOGY IN THE AREAS OF FAULT AVOIDANCE, FAULT ELIMINATION, FAULT TOLERANCE, RELIABILITY ANALYSIS, SAFETY TECHNIQUES, AND AUTOMATED TESTING METHODS FOR USE IN DEVELOPMENT OF GLOBAL CHANGE APPLICATION SOFTWARE.</p> <p><b>DELIVERABLES</b></p> <ol style="list-style-type: none"> <li>1. DEPENDABLE SOFTWARE DEVELOPMENT GUIDELINES.</li> <li>2. AUTOMATED TESTING METHODOLOGY.</li> <li>3. RELIABILITY AND SAFETY ANALYSIS TOOL.</li> <li>4. SUITE OF TESTING TOOLS.</li> </ol>																																																																												
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## SOFTWARE LIBRARY AND REUSE

**SCOPE**  
ROBUST REUSABLE SOFTWARE ELEMENTS AND SUITABLE LIBRARY SUPPORT MECHANISMS FOR GLOBAL CHANGE APPLICATIONS.

**OBJECTIVES**

- DEVELOP METHODOLOGY FOR CREATING AND USING PLUG-COMPATIBLE SOFTWARE PARTS.
- CREATE LIBRARY MECHANISM TO SUPPORT REUSABLE PARTS SUITABLE FOR GLOBAL CHANGE APPLICATIONS.
- DEVELOP GUIDELINES FOR SOFTWARE REUSE THROUGHOUT THE SOFTWARE LIFE CYCLE.

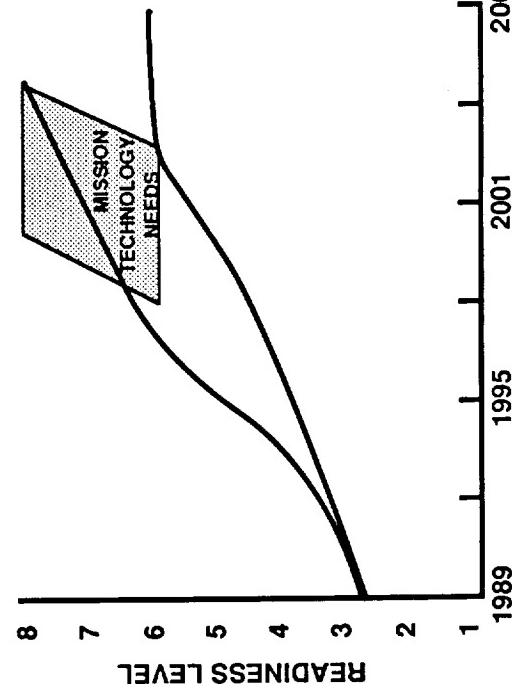
**RATIONALE**  
GREATER PRODUCTIVITY AND QUALITY THROUGH REUSE OF ROBUST SOFTWARE ELEMENTS.

**APPROACH**  
EVALUATE / IMPROVE REUSABLE SOFTWARE SYNTHESIS SYSTEM.  
EXPLORE OBJECT-ORIENTED DESIGN AS A METHOD TO SUPPORT SOFTWARE REUSE.  
PERFORM GLOBAL CHANGE DOMAIN ANALYSIS.  
IDENTIFY AND ADAPT EXISTING SOFTWARE FOR GLOBAL CHANGE REUSE LIBRARY.

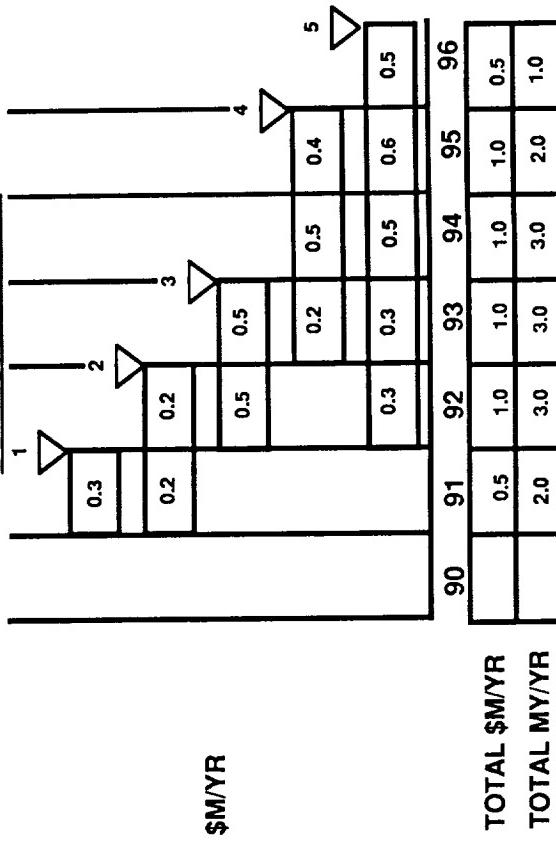
**DELIVERABLES**

1. INITIAL LIBRARY SYSTEM.
2. DOMAIN ANALYSIS OF GLOBAL CHANGE APPLICATIONS.
3. GUIDELINES FOR SOFTWARE REUSE.
4. REUSABLE GLOBAL CHANGE APPLICATION LIBRARY COMPONENTS.
5. EXPANDED LIBRARY SYSTEM FOR GLOBAL CHANGE APPLICATIONS.

### TECHNOLOGY ASSESSMENT

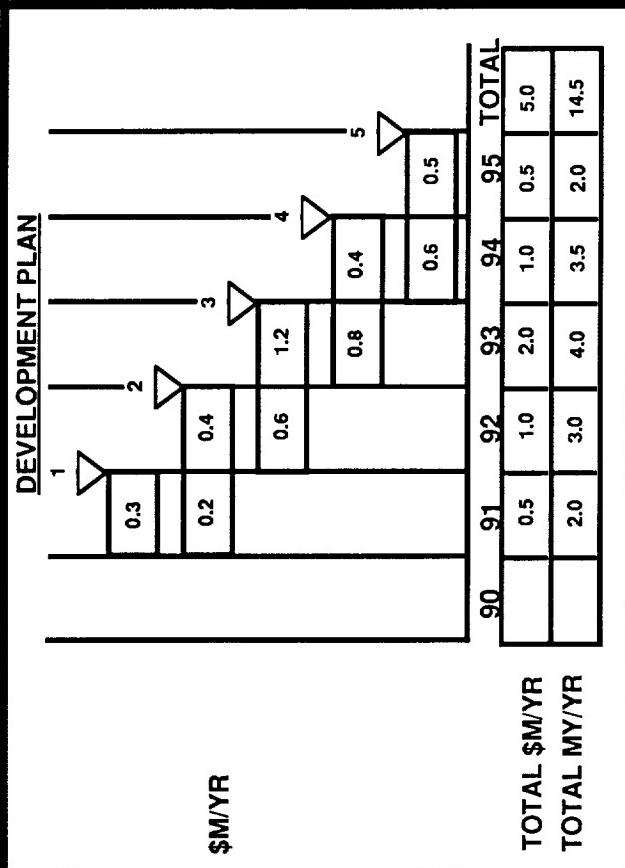


### DEVELOPMENT PLAN



## AUTOMATED PARALLEL SOFTWARE

<p><b>SCOPE</b> DEVELOP THE CAPABILITY TO PRODUCE FROM A GRAPHICAL REPRESENTATION, ADA SOURCE CODE FOR PARALLEL EXECUTION.</p> <p><b>OBJECTIVES</b></p> <ul style="list-style-type: none"> <li>• DEFINE SOFTWARE SPECIFICATIONS CLEARLY AND UNAMBIGUOUSLY.</li> <li>• TRANSLATE SPECIFICATIONS TO PARALLEL CODE EASILY AND CORRECTLY.</li> <li>• TEST AND MAINTAIN CODE EFFECTIVELY.</li> </ul> <p><b>RATIONALE</b> ENABLE EFFECTIVE USE OF ADVANCED PARALLEL ARCHITECTURES NEEDED FOR COMPLEX ON-BOARD PROCESSING.</p>	<p><b>APPROACH</b> EXTEND CURRENT AND DEVELOPING AUTOMATED PROGRAMMING CAPABILITIES TO PROVIDE AUTOMATIC DISTRIBUTION OF ALGORITHMS AMONG MULTIPROCESSORS VIA SEQUENTIAL, GRAPHICAL SPECIFICATION OF SOFTWARE.</p>
	<p><b>DELIVERABLES</b></p> <ol style="list-style-type: none"> <li>1. AUTOMATED SEQUENTIAL PROGRAMMING TOOL.</li> <li>2. AUTOMATIC TESTING / MANAGEMENT FACILITY.</li> <li>3. PROTOTYPE PARALLEL CODE SYSTEM.</li> <li>4. TESTING / MANAGEMENT FOR PARALLEL SOFTWARE.</li> <li>5. AUTOMATIC PARALLEL SOFTWARE SYSTEM.</li> </ol>
	<p><b>TECHNOLOGY ASSESSMENT</b></p> <p>READYNESS LEVEL</p> <p>MISSION TECHNOLOGY NEEDS</p> <p>1989 1995 2001 2007</p>



## LaRC GCTI Information Technologies

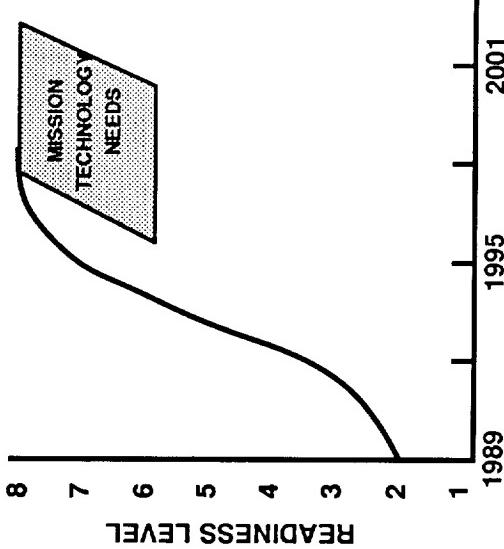
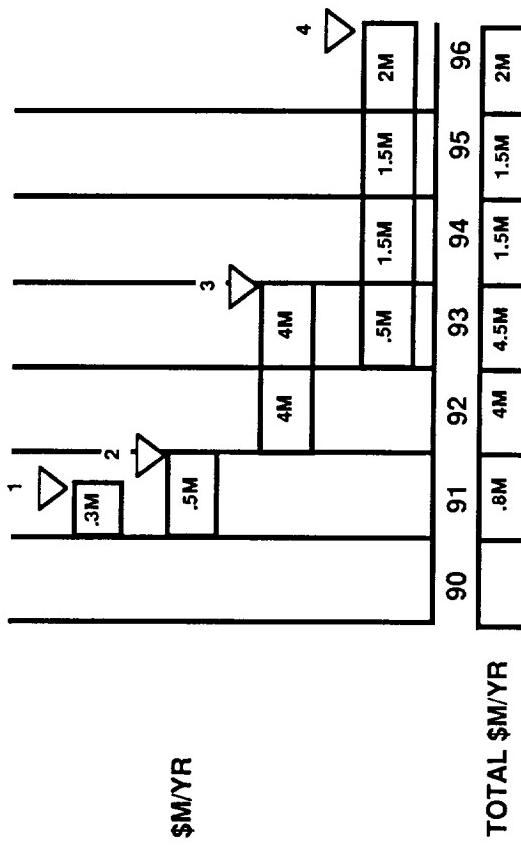
### 3.2 Flight Element

Technology	NASA GCTI WBS	Proposal funding requirements, millions of dollars					
		FY90	FY91	FY92	FY93	FY94	FY95
Digital signal processor	3.21-2		1.5	2.0	4.0	4.0	
Application-specific integrated circuits			0.8	4.0	4.5	1.5	1.5
Chip-level integration	3.21-1		2.0	3.0	3.0	3.0	3.0
Low power GaAs preprocessors			0.4	0.6	1.0	1.0	0.5
Multiprocessors for sensor fusion	3.22-5		1.0	1.0	1.5	1.5	1.0
Spaceborne 32-bit RISC			7.0	7.0	7.0	7.0	7.0
16-bit VHSIC 1750A			1.5	1.0	0.8		
32-bit VHSIC 1750A			2.0	1.0	0.8		
High performance laser for optical recording	3.22-1	0.2	0.5	0.5	0.5	0.5	0.5
Photonic network	3.22-2		0.6	1.0	1.0	1.0	0.5
Spaceflight optical disk recorder	3.22-1		3.3	4.0	5.0	4.0	3.0
Integrated data processor		0.2	0.7	0.7	0.8	1.0	0.1
Sensor specific preprocessing			6.0	8.0	16.0	16.0	6.0
Totals		0.4	27.3	33.8	45.9	40.5	23.1

## DIGITAL SIGNAL PROCESSOR

<b>SCOPE</b> DEVELOP DIGITAL SIGNAL PROCESSING TECHNOLOGY FOR ONBOARD ADVANCED DATA PROCESSING FOR REMOTE SENSING INSTRUMENTS.	<b>APPROACH</b> <ul style="list-style-type: none"> <li>ANALYZE GCTI INSTRUMENTS AND IDENTIFY TARGET FOR APPLICATION.</li> <li>ANALYZE TARGET AND DEVELOP ALGORITHM TO ACHIEVE REQUIRED PERFORMANCE.</li> <li>DEVELOP AND IMPLEMENT ALGORITHM USING COMMERCIALLY AVAILABLE DSP PROCESSORS.</li> <li>INCORPORATE IN TARGET APPLICATION BREADBOARD.</li> <li>SPACE-FLIGHT QUALIFY DSP PROCESSOR.</li> </ul>																								
<b>OBJECTIVES</b> <ul style="list-style-type: none"> <li>DEVELOP SPECIAL PURPOSE DIGITAL PREPROCESSING ALGORITHMS.</li> <li>FLIGHT QUALIFY SPECIAL PURPOSE DSP PROCESSORS.</li> <li>DEVELOP AND DEMONSTRATE DSP SYSTEM ARCHITECTURES.</li> </ul>	<b>DELIVERABLES</b> <ol style="list-style-type: none"> <li>SELECTED APPLICATION</li> <li>ALGORITHMS AND DESIGN</li> <li>BREADBOARD SYSTEM DEMONSTRATION</li> <li>FLIGHT SYSTEM</li> </ol>																								
<b>RATIONALE</b> ENABLE DEVELOPMENT OF REAL-TIME HIGH RATE ADAPTIVE SENSORS THAT PERFORM ONBOARD PROCESSING AND CONTROL.	<b>DEVELOPMENT PLAN</b> <table border="1"> <thead> <tr> <th>Year</th> <th>Task</th> <th>Cost (\$M/YR)</th> </tr> </thead> <tbody> <tr> <td>90</td> <td>1</td> <td>0.5M</td> </tr> <tr> <td>91</td> <td>2</td> <td>1M</td> </tr> <tr> <td>92</td> <td>3</td> <td>1M</td> </tr> <tr> <td>93</td> <td>4</td> <td>1M</td> </tr> <tr> <td>94</td> <td>5</td> <td>3M</td> </tr> <tr> <td>95</td> <td>6</td> <td>3M</td> </tr> <tr> <td>96</td> <td></td> <td></td> </tr> </tbody> </table>	Year	Task	Cost (\$M/YR)	90	1	0.5M	91	2	1M	92	3	1M	93	4	1M	94	5	3M	95	6	3M	96		
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<b>TECHNOLOGY ASSESSMENT</b>																									

**APPLICATION-SPECIFIC INTEGRATED CIRCUITS**

<b>SCOPE</b> DEVELOP AGENCY-WIDE CAPABILITY TO DESIGN, SIMULATE, AND TEST ASIC'S FOR HIGH-RATE SPACEFLIGHT DATA PROCESSING APPLICATIONS.	<b>APPROACH</b> <ul style="list-style-type: none"> <li>DETERMINE CURRENT CAPABILITY AND FUTURE NEEDS.</li> <li>DEVELOP PLAN TO ESTABLISH INTEGRATED CAPABILITY.</li> <li>IMPLEMENT PLAN AND TARGET POTENTIAL APPLICATION.</li> <li>DESIGN, DEVELOP, AND DEMONSTRATE SPACEFLIGHT QUALIFIED ASIC.</li> </ul>																																								
<b>OBJECTIVES</b> <ul style="list-style-type: none"> <li>INCORPORATE ASIC'S INTO SPACEFLIGHT SYSTEMS.</li> <li>DEVELOP NASA-WIDE SYSTEM TO PERFORM DESIGN AND SIMULATION.</li> <li>ESTABLISH SPACEFLIGHT-QUALIFIED PROCESSES AND SOURCES.</li> </ul>	<b>DELIVERABLES</b> <ol style="list-style-type: none"> <li>CURRENT CAPABILITY AND NEED SURVEY</li> <li>INTEGRATED CAPABILITY PLAN</li> <li>SYSTEM TO DESIGN, SIMULATE, AND TEST ASIC'S</li> <li>SPACEFLIGHT-QUALIFIED ASIC FUNCTIONING IN SYSTEM</li> </ol>																																								
<b>RATIONALE</b> MAKE ASIC TECHNOLOGY READILY AVAILABLE FOR INCORPORATION INTO FUTURE SPACEFLIGHT SYSTEMS. ASIC'S WILL IMPROVE SYSTEM PERFORMANCE AND RELIABILITY USING LESS WEIGHT AND POWER.	<b>TECHNOLOGY ASSESSMENT</b>  <p>The graph plots 'MISSION TECHNOLOGY NEEDS' against 'READINESS LEVEL' (Y-axis, 1 to 8) and time (X-axis, 1989 to 2007). The curve starts at a high readiness level (around 7.5) in 1989 and decreases steadily, crossing the 'MISSION TECHNOLOGY NEEDS' line at approximately 1995. After 1995, the readiness level continues to decline more rapidly, reaching a low level by 2007.</p>																																								
	<b>DEVELOPMENT PLAN</b>  <table border="1"> <thead> <tr> <th>Year</th> <th>Task 1</th> <th>Task 2</th> <th>Task 3</th> <th>Task 4</th> </tr> </thead> <tbody> <tr> <td>90</td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>91</td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>92</td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>93</td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>94</td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>95</td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>96</td> <td></td> <td></td> <td></td> <td></td> </tr> </tbody> </table> <p>The chart shows four tasks (1, 2, 3, 4) plotted against years 90 to 96. Task 1 starts in year 90 and ends in year 94. Task 2 starts in year 91 and ends in year 95. Task 3 starts in year 92 and ends in year 96. Task 4 starts in year 93 and ends in year 96.</p>	Year	Task 1	Task 2	Task 3	Task 4	90					91					92					93					94					95					96				
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## CHIP-LEVEL INTEGRATION

<p><b>SCOPE</b> DEVELOP ENHANCED DETECTOR MODULES WITH INTEGRATED (ON-CHIP) PREPROCESSING ELEMENTS FOR ONBOARD IMAGE AND SPECTRAL DATA EXTRACTION.</p> <p><b>OBJECTIVES</b></p> <ul style="list-style-type: none"> <li>• IMPROVE SYSTEM PERFORMANCE.</li> <li>• IMPROVE RELIABILITY FOR LONG-LIFE SENSING.</li> <li>• DECREASE SYSTEM POWER CONSUMPTION.</li> </ul> <p><b>RATIONALE</b> MAXIMIZE PERFORMANCE OF EXISTING AND EMERGING DETECTOR TECHNOLOGIES FOR SPACEFLIGHT REMOTE SENSING SYSTEMS. ENHANCED DETECTOR MODULES WILL BE REQUIRED TO MEET POWER, WEIGHT, AND VOLUME CONSTRAINTS.</p>	<p><b>APPROACH</b></p> <ul style="list-style-type: none"> <li>• ANALYZE GCT INSTRUMENTS AND IDENTIFY TARGET FOR APPLICATION.</li> <li>• ANALYZE TARGET, AND DEVELOP ENHANCED SENSORS TO ACHIEVE IMPROVED PERFORMANCE.</li> <li>• DESIGN AND BUILD ENHANCED DETECTORS USING COMMERCIALLY AVAILABLE HARDWARE.</li> <li>• INTEGRATE DETECTOR IN TARGET BREADBOARD.</li> <li>• BUILD AND QUALIFY SPACEFLIGHT-ENHANCED DETECTORS.</li> </ul> <p><b>DELIVERABLES</b></p> <ol style="list-style-type: none"> <li>1. REPORT ON SELECTED APPLICATION</li> <li>2. DETECTOR MODULE DESIGN</li> <li>3. BREADBOARD SYSTEM</li> <li>4. FLIGHT SYSTEM</li> </ol>	<p><b>TECHNOLOGY ASSESSMENT</b></p> <table border="1"> <thead> <tr> <th>Year</th> <th>TRL</th> </tr> </thead> <tbody> <tr><td>1990</td><td>8</td></tr> <tr><td>1991</td><td>7</td></tr> <tr><td>1992</td><td>6</td></tr> <tr><td>1993</td><td>5</td></tr> <tr><td>1994</td><td>4</td></tr> <tr><td>1995</td><td>3</td></tr> </tbody> </table> <p><b>DEVELOPMENT PLAN</b></p> <table border="1"> <thead> <tr> <th>Year</th> <th>Task</th> <th>Budget (\$M/YR)</th> </tr> </thead> <tbody> <tr><td>1990</td><td>1</td><td>1M</td></tr> <tr><td>1991</td><td>2</td><td>1.5M</td></tr> <tr><td>1992</td><td>3</td><td>1M</td></tr> <tr><td>1993</td><td>4</td><td>.5M</td></tr> <tr><td>1994</td><td>5</td><td>2M</td></tr> <tr><td>1995</td><td>6</td><td>2.5M</td></tr> <tr><td>1996</td><td>7</td><td>3M</td></tr> <tr><td>1997</td><td></td><td></td></tr> </tbody> </table> <p><b>TOTAL \$M/YR</b></p>	Year	TRL	1990	8	1991	7	1992	6	1993	5	1994	4	1995	3	Year	Task	Budget (\$M/YR)	1990	1	1M	1991	2	1.5M	1992	3	1M	1993	4	.5M	1994	5	2M	1995	6	2.5M	1996	7	3M	1997		
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## LOW POWER GaAs PREPROCESSORS TECHNOLOGY

**SCOPE** TO IMPROVE ON CURRENT STATE OF ART GaAs DIGITAL AND MMIC TECHNOLOGY TO REDUCE POWER WHILE MAINTAINING RADIATION TOLERANCE AND PERFORMANCE.  **OBJECTIVES**   - STUDY CANDIDATE FABRICATION TECHNOLOGIES. - DEVELOP TEST AND LOGIC CELLS. - DEVELOP INTEGRATED DEVICES.   **RATIONALE**   - RECENT IMPROVEMENTS IN SMALL CHIP YIELDS IN GaAs INDICATE THAT IT IS BECOMING SUFFICIENTLY MATURE TO BRING TO REAL SYSTEM USE. - BRING 2 1/2 TIMES SPEED IMPROVEMENT AT SAME OR LOWER POWER AS SILICON CMOS. - TECHNOLOGY DEVELOPMENT IN CONCERT WITH DARPA/SDIO.   **APPROACH**   - STUDY POTENTIAL GaAs LOW POWER ALTERNATIVE LOGIC TO THE CURRENT MESFET, MODFET, HBT TECHNOLOGIES. - USE VHDL AND GaAs COMPILERS TO DESIGN FUNCTIONAL CELLS. - FABRICATE AND TEST CELLS IN CHIPS. - USE OF U. OF IDAHO WHERE APPLICABLE.   **DELIVERABLES**   1. REPORT OF RADIATION HARDENED LOW-POWER TECHNOLOGY 2. SPEED, POWER, MANUFACTURABILITY TESTS 3. PREPROCESSOR CHIP TEST 4. INTEGRATE INTO SYSTEM AND TEST	**DEVELOPMENT PLAN**	Task	Start Date	End Date	Resource (\$M/YR)		------	------------	----------	-------------------		1	90	91	0.3M		2	91	92	0.1M		3	92	93	0.3M		4	93	94	0.1M			94	95	0.5M			95	96	0.5M			96	97	0.5M			97	98	0.5M			98	99	0.5M			99	2000	0.5M			2000	2001	0.5M			2001	2002	0.5M			2002	2003	0.5M			2003	2004	0.5M			2004	2005	0.5M			2005	2006	0.5M			2006	2007	0.5M			2007	2008	0.5M			2008	2009	0.5M			2009	2010	0.5M			2010	2011	0.5M			2011	2012	0.5M			2012	2013	0.5M			2013	2014	0.5M			2014	2015	0.5M			2015	2016	0.5M			2016	2017	0.5M			2017	2018	0.5M			2018	2019	0.5M			2019	2020	0.5M			2020	2021	0.5M			2021	2022	0.5M			2022	2023	0.5M			2023	2024	0.5M			2024	2025	0.5M			2025	2026	0.5M			2026	2027	0.5M			2027	2028	0.5M			2028	2029	0.5M			2029	2030	0.5M			2030	2031	0.5M			2031	2032	0.5M			2032	2033	0.5M			2033	2034	0.5M			2034	2035	0.5M			2035	2036	0.5M			2036	2037	0.5M			2037	2038	0.5M			2038	2039	0.5M			2039	2040	0.5M			2040	2041	0.5M			2041	2042	0.5M			2042	2043	0.5M			2043	2044	0.5M			2044	2045	0.5M			2045	2046	0.5M			2046	2047	0.5M			2047	2048	0.5M			2048	2049	0.5M			2049	2050	0.5M			2050	2051	0.5M			2051	2052	0.5M			2052	2053	0.5M			2053	2054	0.5M			2054	2055	0.5M			2055	2056	0.5M			2056	2057	0.5M			2057	2058	0.5M			2058	2059	0.5M			2059	2060	0.5M			2060	2061	0.5M			2061	2062	0.5M			2062	2063	0.5M			2063	2064	0.5M			2064	2065	0.5M			2065	2066	0.5M			2066	2067	0.5M			2067	2068	0.5M			2068	2069	0.5M			2069	2070	0.5M			2070	2071	0.5M			2071	2072	0.5M			2072	2073	0.5M			2073	2074	0.5M			2074	2075	0.5M			2075	2076	0.5M			2076	2077	0.5M			2077	2078	0.5M			2078	2079	0.5M			2079	2080	0.5M			2080	2081	0.5M			2081	2082	0.5M			2082	2083	0.5M			2083	2084	0.5M			2084	2085	0.5M			2085	2086	0.5M			2086	2087	0.5M			2087	2088	0.5M			2088	2089	0.5M			2089	2090	0.5M			2090	2091	0.5M			2091	2092	0.5M			2092	2093	0.5M			2093	2094	0.5M			2094	2095	0.5M			2095	2096	0.5M			2096	2097	0.5M			2097	2098	0.5M			2098	2099	0.5M			2099	20100	0.5M			20100	20101	0.5M			20101	20102	0.5M			20102	20103	0.5M			20103	20104	0.5M			20104	20105	0.5M			20105	20106	0.5M			20106	20107	0.5M			20107	20108	0.5M			20108	20109	0.5M			20109	20110	0.5M			20110	20111	0.5M			20111	20112	0.5M			20112	20113	0.5M			20113	20114	0.5M			20114	20115	0.5M			20115	20116	0.5M			20116	20117	0.5M			20117	20118	0.5M			20118	20119	0.5M			20119	20120	0.5M			20120	20121	0.5M			20121	20122	0.5M			20122	20123	0.5M			20123	20124	0.5M			20124	20125	0.5M			20125	20126	0.5M			20126	20127	0.5M			20127	20128	0.5M			20128	20129	0.5M			20129	20130	0.5M			20130	20131	0.5M			20131	20132	0.5M			20132	20133	0.5M			20133	20134	0.5M			20134	20135	0.5M			20135	20136	0.5M			20136	20137	0.5M			20137	20138	0.5M			20138	20139	0.5M			20139	20140	0.5M			20140	20141	0.5M			20141	20142	0.5M			20142	20143	0.5M			20143	20144	0.5M			20144	20145	0.5M			20145	20146	0.5M			20146	20147	0.5M			20147	20148	0.5M			20148	20149	0.5M			20149	20150	0.5M			20150	20151	0.5M			20151	20152	0.5M			20152	20153	0.5M			20153	20154	0.5M			20154	20155	0.5M			20155	20156	0.5M			20156	20157	0.5M			20157	20158	0.5M			20158	20159	0.5M			20159	20160	0.5M			20160	20161	0.5M			20161	20162	0.5M			20162	20163	0.5M			20163	20164	0.5M			20164	20165	0.5M			20165	20166	0.5M			20166	20167	0.5M			20167	20168	0.5M			20168	20169	0.5M			20169	20170	0.5M			20170	20171	0.5M			20171	20172	0.5M			20172	20173	0.5M			20173	20174	0.5M			20174	20175	0.5M			20175	20176	0.5M			20176	20177	0.5M			20177	20178	0.5M			20178	20179	0.5M			20179	20180	0.5M			20180	20181	0.5M			20181	20182	0.5M			20182	20183	0.5M			20183	20184	0.5M			20184	20185	0.5M			20185	20186	0.5M			20186	20187	0.5M			20187	20188	0.5M			20188	20189	0.5M			20189	20190	0.5M			20190	20191	0.5M			20191	20192	0.5M			20192	20193	0.5M			20193	20194	0.5M			20194	20195	0.5M			20195	20196	0.5M			20196	20197	0.5M			20197	20198	0.5M			20198	20199	0.5M			20199	20200	0.5M			20200	20201	0.5M			20201	20202	0.5M			20202	20203	0.5M			20203	20204	0.5M			20204	20205	0.5M			20205	20206	0.5M			20206	20207	0.5M			20207	20208	0.5M			20208	20209	0.5M			20209	20210	0.5M			20210	20211	0.5M			20211	20212	0.5M			20212	20213	0.5M			20213	20214	0.5M			20214	20215	0.5M			20215	20216	0.5M			20216	20217	0.5M			20217	20218	0.5M			20218	20219	0.5M			20219	20220	0.5M			20220	20221	0.5M			20221	20222	0.5M			20222	20223	0.5M			20223	20224	0.5M			20224	20225	0.5M			20225	20226	0.5M			20226	20227	0.5M			20227	20228	0.5M			20228	20229	0.5M			20229	20230	0.5M			20230	20231	0.5M			20231	20232	0.5M			20232	20233	0.5M			20233	20234	0.5M			20234	20235	0.5M			20235	20236	0.5M			20236	20237	0.5M			20237	20238	0.5M			20238	20239	0.5M			20239	20240	0.5M			20240	20241	0.5M			20241	20242	0.5M			20242	20243	0.5M			20243	20244	0.5M			20244	20245	0.5M			20245	20246	0.5M			20246	20247	0.5M			20247	20248	0.5M			20248	20249	0.5M			20249	20250	0.5M			20250	20251	0.5M			20251	20252	0.5M			20252	20253	0.5M			20253	20254	0.5M			20254	20255	0.5M			20255	20256	0.5M			20256	20257	0.5M			20257	20258	0.5M			20258	20259	0.5M			20259	20260	0.5M			20260	20261	0.5M			20261	20262	0.5M			20262	20263	0.5M			20263	20264	0.5M			20264	20265	0.5M			20265	20266	0.5M			20266	20267	0.5M			20267	20268	0.5M			20268	20269	0.5M			20269	20270	0.5M			20270	20271	0.5M			20271	20272	0.5M			20272	20273	0.5M			20273	20274	0.5M			20274	20275	0.5M			20275	20276	0.5M			20276	20277	0.5M			20277	20278	0.5M			20278			

# MULTIPROCESSORS FOR SENSOR EMISSION

H. BENZ

<b>SCOPE</b> RADIATION HARDENED MULTIPROCESSORS FOR SENSOR FUSION AND CONTROL.	<b>OBJECTIVES</b> • DEVELOP CURRENT GENERATION PROCESSOR CHIP TECHNOLOGY INTO NEXT GENERATION SYSTEMS APPLICATIONS. • SUPPORT POLAR AND GEOSTATIONARY RADIATION REQUIREMENTS FOR LIMITED AMOUNTS OF ONBOARD SENSOR FUSION BETWEEN VARIOUS SENSING SYSTEMS WITH LOW POWER, MODEST COMPLEXITY SYSTEMS.	<b>RATIONALE</b> • OPERATION AT GEO MUST MIX LASER COMM-LINKED GROUND PROCESSORS WITH RADIATION HARDENED ON-ORBIT COMPUTATIONAL HARDWARE.	<b>APPROACH</b> <ul style="list-style-type: none"><li>• USE CURRENT GENERATION 16-BIT AND LIMITED AMOUNT OF 32-BIT VON NEUMANN ARCHITECTED CHIP SETS TO DEVELOP CONCEPTS.</li><li>• BUILD ON CURRENT CSTI JOINT PROCESSOR DEVELOPMENT PROGRAM BETWEEN LANGLEY AND JPL BY AUGMENTATION OF MISSION APPLICATION STUDIES. DEVELOP TEST SIMULATIONS, DEMONSTRATE IN HARDWARE.</li></ul>																																		
<b>DELIVERABLES</b> <ol style="list-style-type: none"><li>1. MIXED-PROCESSOR GRAPHICAL THEORY</li><li>2. MULTIPROCESSOR OS SIMULATOR</li><li>3. DEVELOP ADA APPLICATION TEST PROGRAM</li><li>4. DEVELOP SYSTEM ARCHITECTURE</li><li>5. TEST/DEMO MULTIPROCESSOR SYSTEM</li></ol>			<b>DEVELOPMENT PLAN</b> <table border="1"><thead><tr><th>Task</th><th>Duration</th><th>Start Date</th><th>End Date</th></tr></thead><tbody><tr><td>1</td><td>0.1M</td><td>90-01</td><td>90-02</td></tr><tr><td>2</td><td>0.1M</td><td>90-02</td><td>90-03</td></tr><tr><td>3</td><td>0.1M</td><td>90-03</td><td>90-04</td></tr><tr><td>4</td><td>0.1M</td><td>90-04</td><td>90-05</td></tr><tr><td>5</td><td>0.1M</td><td>90-05</td><td>90-06</td></tr></tbody></table> <b>TECHNOLOGY ASSESSMENT</b> <table border="1"><thead><tr><th>Year</th><th>Readiness Level</th></tr></thead><tbody><tr><td>1989</td><td>8</td></tr><tr><td>1995</td><td>6</td></tr><tr><td>2001</td><td>4</td></tr><tr><td>2007</td><td>2</td></tr></tbody></table>	Task	Duration	Start Date	End Date	1	0.1M	90-01	90-02	2	0.1M	90-02	90-03	3	0.1M	90-03	90-04	4	0.1M	90-04	90-05	5	0.1M	90-05	90-06	Year	Readiness Level	1989	8	1995	6	2001	4	2007	2
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## SPACEBORNE 32-BIT RISC PROCESSOR CHIP SET

**SCOPE**  
TO WORK JOINT PROGRAM WITH AF-RADC  
TO CODEVELOP RH-32 CHIP SETS FOR GCTI  
ONBOARD PROCESSING AND CONTROL APPLICATIONS.

**OBJECTIVES**

- PROVIDE NEXT GENERATION ONBOARD PROCESSING CAPABILITY FOR CONTROL AND DATA HANDLING.

- SIMULTANEOUSLY MEET RAD-HARD, LOW POWER, HIGH PERFORMANCE GOALS WITH LIMITED FAULT TOLERANCE AND DATA INTEGRITY FOR NEXT-GENERATION EMBEDDED COMPUTER.
- LEVERAGE FROM BSTS, SSTS SYSTEM TECHNOLOGY DEVELOPMENTS.

### RATIONALE

NEEDED HIGH PERFORMANCE PROCESSORS.  
GEO POWER AND HEAT REJECTION EXPENSIVE.

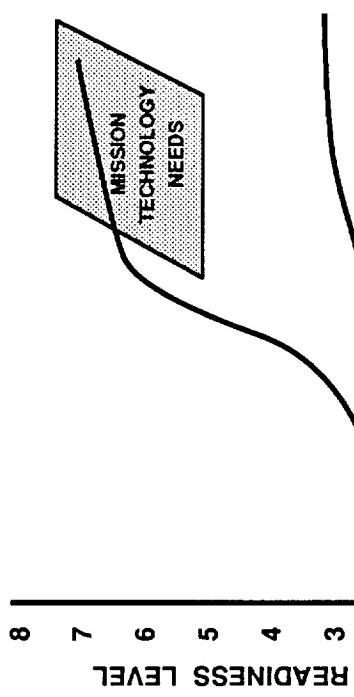
### APPROACH

CODEVELOP WITH JOINT AF-RADC AND AF-STC AND SDIO PARTICIPATION, BOOTSTRAPPING ONTO THE DARPA CORE MIPS, AND AF-RADC RH-32 HARD AND MM AND FEASIBILITY PROGRAMS, AND USE EARLY LANGLEY PARTICIPATION IN THESE PROGRAMS.

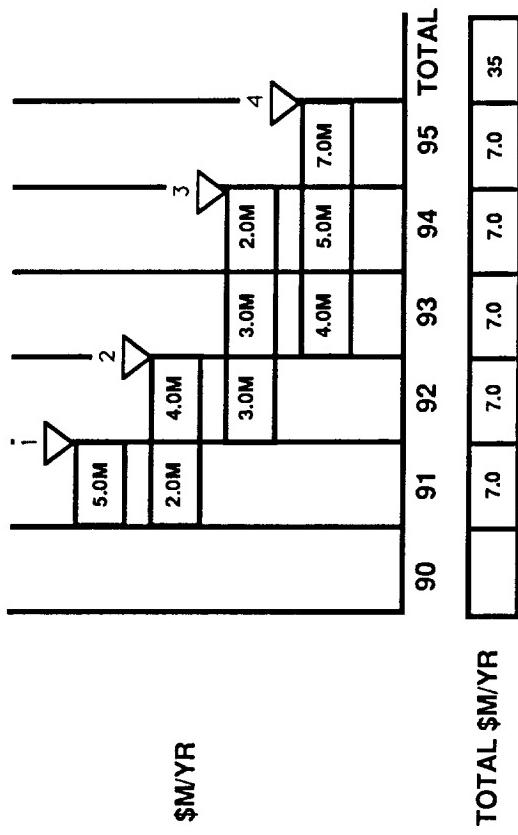
### DELIVERABLES

1. DESIGN OF CHIP SET
2. FIRST FAB AND TEST
3. DESIGN INTEGRATION
4. FINAL TEST IN COMPUTING ENVIRONMENT

### TECHNOLOGY ASSESSMENT



### DEVELOPMENT PLAN



## 16-BIT VHSIC 1750A SPACEFLIGHT COMPUTER UPGRADE

<p><b>SCOPE</b> DEVELOP AND QUALIFY A HIGH-PERFORMANCE VHSIC UPGRADE TO THE EXISTING 16-BIT 1750A MAST COMPUTER.</p> <p><b>OBJECTIVES</b></p> <ul style="list-style-type: none"> <li>• 3 MIPS PROCESSOR PERFORMANCE.</li> <li>• 20 MIPS ARRAY PROCESSOR PERFORMANCE.</li> <li>• 50 MBPS EXTERNAL DATA BUS RATE WITH FIBER OPTICS.</li> <li>• 200% INCREASE IN MEMORY DENSITY, RAD-HARDEDENED.</li> </ul>	<p><b>APPROACH</b></p> <ul style="list-style-type: none"> <li>• MODIFY THE DESIGN OF THE CURRENT NASA MAST 1750A VLSI-BASED SPACE-QUALIFIED COMPUTER TO A GENERAL-PURPOSE SPACE-QUALIFIED VHSIC COMPUTER.</li> <li>• BUILD UPON THE SOFTWARE DEVELOPMENT EFFORT SUPPORTING THE CURRENT MAST COMPUTER.</li> </ul>	<p><b>DELIVERABLES</b></p> <ol style="list-style-type: none"> <li>1. GROUND SUPPORT EQUIPMENT AND SOFTWARE DEVELOPMENT ENVIRONMENT.</li> <li>2. PROTOTYPE COMPUTER.</li> <li>3. SPACE-QUALIFIED COMPUTER AND SPARE CARD SET.</li> <li>4. SUSTAINED ENGINEERING.</li> </ol>	<p><b>TECHNOLOGY ASSESSMENT</b></p> <p>The graph plots 'MISSION TECHNOLOGY NEEDS' against 'READYNESS LEVEL'. The Y-axis ranges from 1 to 8, and the X-axis shows years from 1989 to 1996. A diagonal line starts at (1989, 8) and ends at (1996, 3). A shaded triangular area is bounded by the line, the Y-axis, and a vertical line at X=1996.</p> <table border="1"> <thead> <tr> <th>Year</th> <th>Readiness Level</th> </tr> </thead> <tbody> <tr><td>1989</td><td>8</td></tr> <tr><td>1990</td><td>7</td></tr> <tr><td>1991</td><td>6</td></tr> <tr><td>1992</td><td>5</td></tr> <tr><td>1993</td><td>4</td></tr> <tr><td>1994</td><td>3</td></tr> <tr><td>1995</td><td>3</td></tr> <tr><td>1996</td><td>3</td></tr> </tbody> </table>	Year	Readiness Level	1989	8	1990	7	1991	6	1992	5	1993	4	1994	3	1995	3	1996	3	<p><b>DEVELOPMENT PLAN</b></p> <p>The timeline shows milestones 1 through 4 and funding levels in millions of dollars per year.</p> <table border="1"> <thead> <tr> <th>Year</th> <th>Total \$M/YR</th> </tr> </thead> <tbody> <tr><td>90</td><td></td></tr> <tr><td>91</td><td></td></tr> <tr><td>92</td><td>1.5M</td></tr> <tr><td>93</td><td>1M</td></tr> <tr><td>94</td><td>.8M</td></tr> <tr><td>95</td><td>.6M</td></tr> <tr><td>96</td><td></td></tr> </tbody> </table>	Year	Total \$M/YR	90		91		92	1.5M	93	1M	94	.8M	95	.6M	96	
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C.2

## 32-BIT VHSIC 1750A SPACEFLIGHT COMPUTER UPGRADE

<p><b>SCOPE</b> DEVELOP AND QUALIFY A 32-BIT PROCESSOR UPGRADE TO THE EXISTING MAST COMPUTER; MAINTAIN ADA LANGUAGE SUPPORT CAPABILITY, WITH INTERNAL ARCHITECTURE CHANGES TO 32-BIT DATA PATHS AND EXPANDED ADDRESSING CAPABILITY.</p> <p><b>OBJECTIVES</b></p> <ul style="list-style-type: none"> <li>HIGHER DATA PROCESSING/REDUCTION THROUGHPUT.</li> <li>LONG-TERM GROWTH CAPABILITY FOR ONBOARD PROCESSING.</li> <li>NEAR-TERM AVAILABILITY FOR FLIGHT APPLICATIONS.</li> </ul> <p><b>RATIONALE</b></p> <ul style="list-style-type: none"> <li>HIGH PERFORMANCE ON-ORBIT SENSOR DATA PROCESSING.</li> <li>FAULT TOLERANT PROCESSING FOR AUTONOMOUS SYSTEMS.</li> <li>IMPROVED REAL-TIME RESPONSE FOR DYNAMIC SYSTEMS.</li> <li>TECHNOLOGY LEVERAGED BY DOD PROGRAMS (USAF RH-32).</li> </ul>	<p><b>APPROACH</b></p> <ul style="list-style-type: none"> <li>MODIFY THE DESIGN OF THE CURRENT NASA MAST 1750A VLSI-BASED SPACE-QUALIFIED COMPUTER TO A GENERAL-PURPOSE SPACE-QUALIFIED VHSIC COMPUTER.</li> <li>BUILD UPON THE SOFTWARE DEVELOPMENT EFFORT SUPPORTING THE CURRENT MAST COMPUTER.</li> </ul> <p><b>DELIVERABLES</b></p> <ol style="list-style-type: none"> <li>GROUND SUPPORT EQUIPMENT AND SOFTWARE DEVELOPMENT ENVIRONMENT.</li> <li>PROTOTYPE COMPUTER.</li> <li>SPACE QUALIFIED COMPUTER AND SPARE CARD SET.</li> <li>SUSTAINED ENGINEERING.</li> </ol>																								
<p><b>TECHNOLOGY ASSESSMENT</b></p> <p>The graph plots 'MISSION TECHNOLOGY NEEDS' against 'READINESS LEVEL' (Y-axis, 2 to 8) and 'YEAR' (X-axis, 1989 to 2007). A shaded triangular area represents the mission needs, which starts at level 8 in 1989 and decreases to level 2 by 2007. A solid line represents the current technology status, which starts at level 8 in 1989 and decreases to level 2 by 2007, tracking the mission needs.</p>	<p><b>DEVELOPMENT PLAN</b></p> <p>The chart shows a timeline from 1990 to 1996. Task 1 (1M) starts in 90 and ends in 91. Task 2 (1M) starts in 91 and ends in 92. Task 3 (.5M) starts in 92 and ends in 93. Task 4 (.8M) starts in 93 and ends in 94. A dashed line extends the timeline to 1996. The total cost in millions of dollars is shown at the bottom.</p> <table border="1"> <thead> <tr> <th>Year</th> <th>Task</th> <th>Cost (\$M)</th> </tr> </thead> <tbody> <tr> <td>90</td> <td>1</td> <td>1M</td> </tr> <tr> <td>91</td> <td>2</td> <td>1M</td> </tr> <tr> <td>92</td> <td>3</td> <td>.5M</td> </tr> <tr> <td>93</td> <td>4</td> <td>.8M</td> </tr> <tr> <td>94</td> <td></td> <td></td> </tr> <tr> <td>95</td> <td></td> <td></td> </tr> <tr> <td>96</td> <td></td> <td></td> </tr> </tbody> </table> <p>TOTAL \$/YR</p>	Year	Task	Cost (\$M)	90	1	1M	91	2	1M	92	3	.5M	93	4	.8M	94			95			96		
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## HIGH-PERFORMANCE LASER FOR OPTICAL RECORDING

<u>SCOPE</u>	<u>APPROACH</u>	<u>DEVELOPMENT PLAN</u>																								
<p><b>SCOPE</b></p> <p>DEVELOP AND DEMONSTRATE HIGH-PERFORMANCE LASER FOR OPTICAL RECORDING.</p> <p><b>OBJECTIVE</b></p> <ul style="list-style-type: none"> <li>REDUCE LASER WAVELENGTH.</li> <li>IMPROVE LASER STABILITY AND MODULATION RATE.</li> <li>INCREASE LASER POWER EFFICIENCY.</li> </ul> <p><b>RATIONALE</b></p> <p>SHORTER WAVELENGTH LASERS WILL PROVIDE INCREASED OPTICAL RECORDING CAPACITY.</p>	<p><b>SCOPE</b></p> <p>DEVELOP SHORTER WAVELENGTH SEMICONDUCTOR (SC) LASER MATERIAL AND DEVICE DESIGN. FABRICATE, DESIGN, AND CHARACTERIZE LASER, AND DEVELOP STABLE AND LONG LIFE SC LASER.</p> <p><b>DELIVERABLES</b></p> <ul style="list-style-type: none"> <li>MATERIAL SYSTEM AND INITIAL DESIGN.</li> <li>Demonstration of initial SC LASER.</li> <li>Engineering design model laser.</li> <li>Long life and stable laser.</li> <li>Space-qualified SC LASER.</li> </ul>	<table border="1"> <thead> <tr> <th>Task</th> <th>90</th> <th>91</th> <th>92</th> <th>93</th> <th>94</th> <th>95</th> <th>TOTAL</th> </tr> </thead> <tbody> <tr> <td>R&amp;T BS</td> <td>0.2</td> <td>0.5</td> <td>0.5</td> <td>0.5</td> <td>0.5</td> <td>0.5</td> <td>2.7M</td> </tr> <tr> <td>TOTAL \$M/YR</td> <td>1.0</td> <td>1.0</td> <td>2.0</td> <td>2.0</td> <td>2.0</td> <td>2.0</td> <td>8.0</td> </tr> </tbody> </table>	Task	90	91	92	93	94	95	TOTAL	R&T BS	0.2	0.5	0.5	0.5	0.5	0.5	2.7M	TOTAL \$M/YR	1.0	1.0	2.0	2.0	2.0	2.0	8.0
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<b>TECHNOLOGY ASSESSMENT</b>	<p>The graph plots the Mission Needs Window against the Readiness Level (RL) from 1 to 7. The window is shaded and shows a peak around RL 5, which corresponds to the year 2005.</p>	<p>The graph plots the Mission Needs Window against the Readiness Level (RL) from 1 to 7. The window is shaded and shows a peak around RL 5, which corresponds to the year 2005.</p>																								

# HIGH-PERFORMANCE PHOTONIC NETWORK DEVELOPMENT

N. MURRAY

**SCOPE**  
RESEARCH AND DEMONSTRATE A HIGH-PERFORMANCE ALL PHOTONIC NETWORK FOR ONBOARD EARTH-OBSERVING SATELLITES.

## OBJECTIVES

- RESEARCH AND DEFINE THE ARCHITECTURAL ISSUES FOR AN ALL PHOTONIC NETWORK.
- RESEARCH AND DEVELOP AN ADAPTABLE OPTIC NODE FOR SELECTED ARCHITECTURES.
- INTEGRATE THE OPTIC NODE INTO PHOTONIC NETWORK TEST BED DEMONSTRATION.

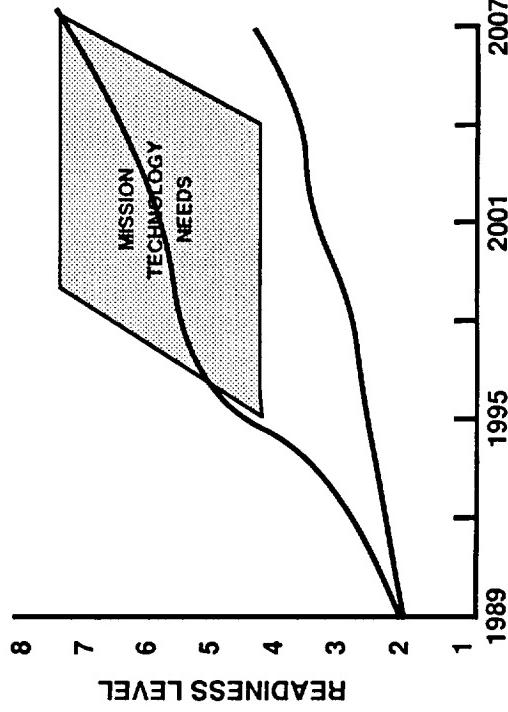
**RATIONALE**  
ENABLE SCIENCE USERS DIRECT ACCESS TO SENSOR DATA AND GLOBAL INFORMATION.

**APPROACH**  
USE ONGOING RESEARCH PRODUCTS FROM NASA, UNIVERSITIES, AND INDUSTRY; NASA UNDERTAKE NEW AND INNOVATIVE RESEARCH TO MEET UNIQUE REQUIREMENTS.

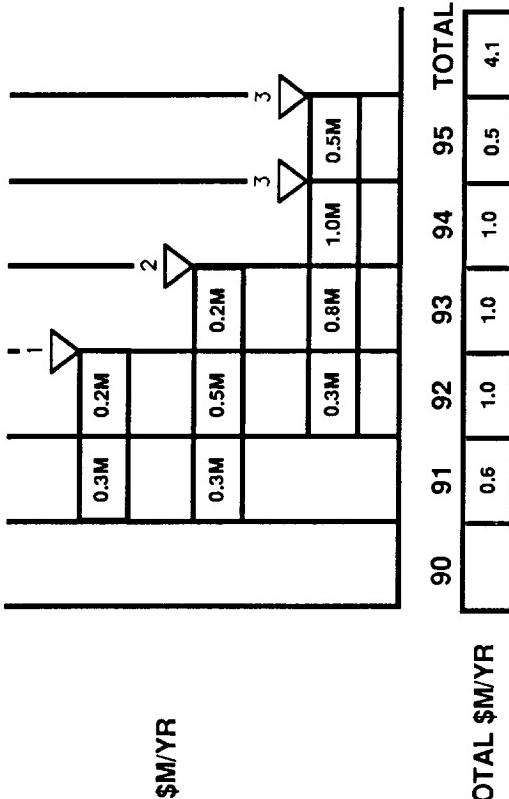
## DELIVERABLES

1. ARCHITECTURE DEFINITION AND MODELING.
2. OPTIC NODE DEVELOPMENT.
3. PHOTONIC NETWORK BUILD - MINIDEMO.

## TECHNOLOGY ASSESSMENT



## DEVELOPMENT PLAN



TOTAL \$M/YR

Year	90	91	92	93	94	95	TOTAL
	0.3M	0.2M	0.3M	0.5M	0.2M	0.3M	4.1M

## SPACEFLIGHT OPTICAL DISK RECORDER

<p><b>SCOPE</b> DEVELOP HIGH-PERFORMANCE REWRITABLE OPTICAL DISK MASS STORAGE SYSTEM FOR SPACEFLIGHT APPLICATIONS.</p> <p><b>OBJECTIVES</b></p> <ul style="list-style-type: none"> <li>• UP TO 1.8 GIGABIT/SEC I/O RATE.</li> <li>• CAPACITY TO TERABIT (120 GIGABYTE).</li> <li>• RANDOM FILE ACCESS (100 MSEC).</li> <li>• SIMULTANEOUS INPUT AND OUTPUT.</li> </ul> <p><b>RATIONALE</b> HIGH-SPEED/HIGH-CAPACITY MASS STORAGE NEEDED FOR FUTURE MISSIONS. ALLOWS PRIORITY DOWNLINK AND ONBOARD PROCESSING.</p>	<p><b>APPROACH</b></p> <ul style="list-style-type: none"> <li>• LEVERAGE EXISTING CSTI AND DOD PROGRAMS.</li> <li>• USE VERSATILE EXPANDABLE SYSTEM ARCHITECTURE BASED ON SINGLE DISK DRIVES AND MODULAR CONTROLLER.</li> <li>• DEVELOP AND QUALIFY MODULES.</li> <li>• DEMONSTRATE SYSTEM CONCEPT.</li> </ul> <p><b>DELIVERABLES</b></p> <ol style="list-style-type: none"> <li>1. ADVANCED DEVELOPMENT UNIT FROM CSTI.</li> <li>2. SYSTEM MODELS.</li> <li>3. ENGINEERING DEMONSTRATION UNIT.</li> <li>4. TEST BED SYSTEM DEMONSTRATION.</li> <li>5. FLIGHT PROTOTYPE DRIVE AND CONTROLLER.</li> <li>6. FLIGHT TEST MINIMUM SYSTEM.</li> </ol>	<p><b>TECHNOLOGY ASSESSMENT</b></p> <p>READYNESS LEVEL</p> <p>MISSION TECHNOLOGY NEEDS</p> <p>CSTI</p> <p>WITH TECHNOLOGY</p> <p>2007</p>	<p><b>DEVELOPMENT PLAN</b></p> <table border="1"> <thead> <tr> <th>Year</th> <th>Milestone</th> <th>Capacity (\$M)</th> </tr> </thead> <tbody> <tr> <td>1990</td> <td>1</td> <td>3M</td> </tr> <tr> <td>1991</td> <td>2</td> <td>3.3M</td> </tr> <tr> <td>1992</td> <td>3</td> <td>4M</td> </tr> <tr> <td>1993</td> <td>4</td> <td>5M</td> </tr> <tr> <td>1994</td> <td>5</td> <td>4M</td> </tr> <tr> <td>1995</td> <td>6</td> <td>2M</td> </tr> <tr> <td>1996</td> <td></td> <td></td> </tr> </tbody> </table> <p>TOTAL \$/YR</p> <p>90 91 92 93 94 95 96</p>	Year	Milestone	Capacity (\$M)	1990	1	3M	1991	2	3.3M	1992	3	4M	1993	4	5M	1994	5	4M	1995	6	2M	1996		
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## INTEGRATED DATA PROCESSOR/SMART SENSOR CONCEPTS

<p><b>SCOPE</b></p> <p>DEVELOP AND DEMONSTRATE ONBOARD DATA PROCESSOR EMBEDDED IN MICROWAVE AND OPTICAL SENSOR SYSTEMS.</p> <p><b>OBJECTIVE</b></p> <ul style="list-style-type: none"> <li>INTEGRATED SENSOR ANALOG SIGNAL PROCESSING WITH DIGITAL PROCESSOR.</li> <li>DEMONSTRATE AUTOMATED SIGNAL PROCESSING.</li> <li>DEMONSTRATE SENSOR CALIBRATION AND SYSTEM CONTROLLER PROCESSOR.</li> </ul> <p><b>RATIONALE</b></p> <p>REMOTE ONBOARD SENSOR SYSTEM REQUIRES AUTOMATED AND INTEGRATED PROCESSOR.</p>	<p><b>APPROACH</b></p> <p>UTILIZE ANALOG AND DIGITAL INTEGRATED CIRCUIT DESIGN TO IMPLEMENT SMART SENSOR PROCESSOR. DEVELOP INTEGRATED SENSOR/PROCESSOR FOR MICROWAVE AND OPTICAL SENSORS.</p> <p><b>DELIVERABLES</b></p> <ul style="list-style-type: none"> <li>RADIATION-HARDENED PROCESSOR DESIGN.</li> <li>SENSOR/PROCESSOR INTEGRATION DESIGN.</li> <li>INITIAL SENSOR/PROCESSOR.</li> <li>FULL SENSOR/PROCESSOR WITH CALIBRATION.</li> <li>SPACE-QUALIFIED INTEGRATED PROCESSOR.</li> </ul>	<p><b>TECHNOLOGY ASSESSMENT</b></p> <p>The graph plots 'READINESS LEVEL' on the Y-axis (1 to 7) against time on the X-axis. Two curves represent the evolution of technology: one rising from level 1 to 7 by 2010, and another falling from level 7 to 2 by 2010. A shaded rectangular area between these curves is labeled 'MISSION NEEDS WINDOW'.</p>	<p><b>DEVELOPMENT PLAN</b></p> <table border="1"> <thead> <tr> <th rowspan="2">R&amp;T BS</th> <th colspan="5">TOTAL \$M/YR</th> <th rowspan="2">TOTAL</th> </tr> <tr> <th>90</th> <th>91</th> <th>92</th> <th>93</th> <th>94</th> </tr> </thead> <tbody> <tr> <td>90</td> <td>0.2</td> <td>0.7</td> <td>0.7</td> <td>0.8</td> <td>1.0</td> <td>2.6M</td> </tr> <tr> <td>TOTAL \$M/YR</td> <td>2.0</td> <td>2.0</td> <td>3.0</td> <td>4.0</td> <td>4.0</td> <td>15.0</td> </tr> </tbody> </table>	R&T BS	TOTAL \$M/YR					TOTAL	90	91	92	93	94	90	0.2	0.7	0.7	0.8	1.0	2.6M	TOTAL \$M/YR	2.0	2.0	3.0	4.0	4.0	15.0
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TOTAL \$M/YR	2.0	2.0	3.0	4.0	4.0	15.0																							

## SENSOR SPECIFIC PREPROCESSING

<p><b>SCOPE</b> DEVELOP HIGH-PERFORMANCE DETECTOR SPECIFIC PREPROCESSING COMPONENTS FOR SPACEBORNE REMOTE SENSING INSTRUMENTS.</p> <p><b>OBJECTIVES</b></p> <ul style="list-style-type: none"> <li>• FLIGHT QUALIFY SPECIAL PURPOSE PREPROCESSING ELEMENTS.</li> <li>• DEVELOP AND DEMONSTRATE SYSTEM PERFORMANCE.</li> <li>• DEVELOP AGENCY-WIDE CAPABILITIES TO APPLY ADVANCED TECHNOLOGIES TO FUTURE MISSIONS.</li> </ul>	<p><b>APPROACH</b></p> <ul style="list-style-type: none"> <li>• ASSESS NASA REQUIREMENTS VERSUS AVAILABLE TECHNOLOGIES.</li> <li>• ESTABLISH AGENCY-WIDE FACILITIES TO PROVIDE TOOLS FOR COMPONENT DEVELOPMENT.</li> <li>• IDENTIFY LONG-TERM SOURCES FOR FLIGHT QUALIFIED PARTS.</li> <li>• DESIGN, FABRICATE, AND TEST PREPROCESSING SYSTEM IN TARGET INSTRUMENTS.</li> </ul>	<p><b>DELIVERABLES</b></p> <ol style="list-style-type: none"> <li>1. SELECTED INSTRUMENT FOR ADVANCE PREPROCESSING COMPONENTS.</li> <li>2. SYSTEMS TO DEVELOP ALGORITHM AND DESIGN COMPONENTS.</li> <li>3. PREPROCESSING ALGORITHMS AND DESIGNS.</li> <li>4. FLIGHT-QUALIFIED SYSTEMS.</li> </ol>	<p><b>RATIONALE</b></p> <p>MEASUREMENTS OF GLOBAL CHANGE PHENOMENA WILL REQUIRE UNPRECEDENTED DYNAMIC RANGE AND SIGNAL-TO-NOISE RATIO. MISSION LENGTH REQUIRES THE RELIABILITY AND INHERENT STABILITY OF DIGITAL PREPROCESSING. INCREASED SYSTEM BANDWIDTH IS REQUIRED TO PROCESS AND TRANSMIT DATA IN REAL-TIME.</p>	<p><b>TECHNOLOGY ASSESSMENT</b></p> <p>The graph plots 'MISSION TECHNOLOGY NEEDS' (Y-axis, 1 to 8) against 'READINESS LEVEL' (X-axis, 1989 to 2007). A shaded triangular area represents the technology needs, which start at level 8 in 1989 and decrease to level 2 by 2007. A solid line represents the readiness level, which starts at 1 in 1989 and increases steadily to 8 by 2007, crossing the mission needs line around 2001.</p>	<p><b>DEVELOPMENT PLAN</b></p> <p>The Gantt chart shows the timeline for the development plan. The Y-axis represents '\$M/YR' (millions of dollars per year) and the X-axis represents years from 1990 to 1996. The chart includes four tasks labeled 1 through 4:</p> <table border="1"> <thead> <tr> <th>Task</th> <th>Start Year</th> <th>End Year</th> <th>Budget (\$M/YR)</th> </tr> </thead> <tbody> <tr> <td>1</td> <td>1990</td> <td>1991</td> <td>2M</td> </tr> <tr> <td>2</td> <td>1991</td> <td>1992</td> <td>4M</td> </tr> <tr> <td>3</td> <td>1992</td> <td>1994</td> <td>4M</td> </tr> <tr> <td>4</td> <td>1994</td> <td>1996</td> <td>6M</td> </tr> </tbody> </table>	Task	Start Year	End Year	Budget (\$M/YR)	1	1990	1991	2M	2	1991	1992	4M	3	1992	1994	4M	4	1994	1996	6M
Task	Start Year	End Year	Budget (\$M/YR)																						
1	1990	1991	2M																						
2	1991	1992	4M																						
3	1992	1994	4M																						
4	1994	1996	6M																						

## LaRC GCTI Information Technologies

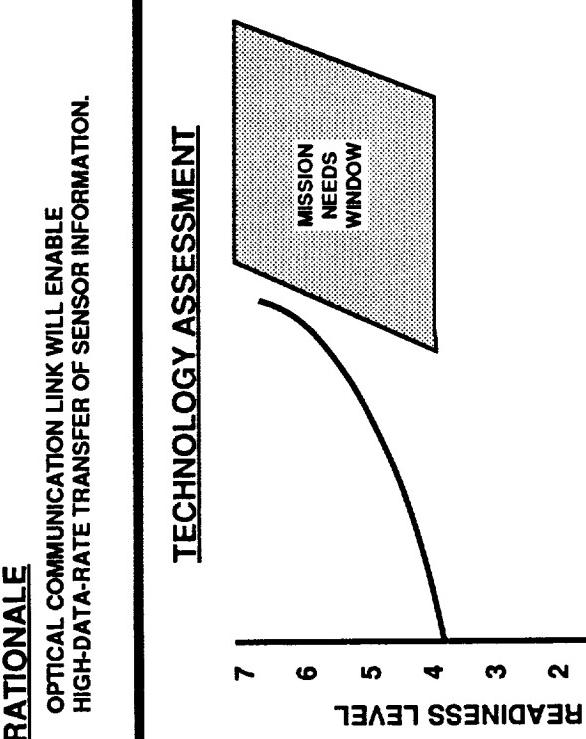
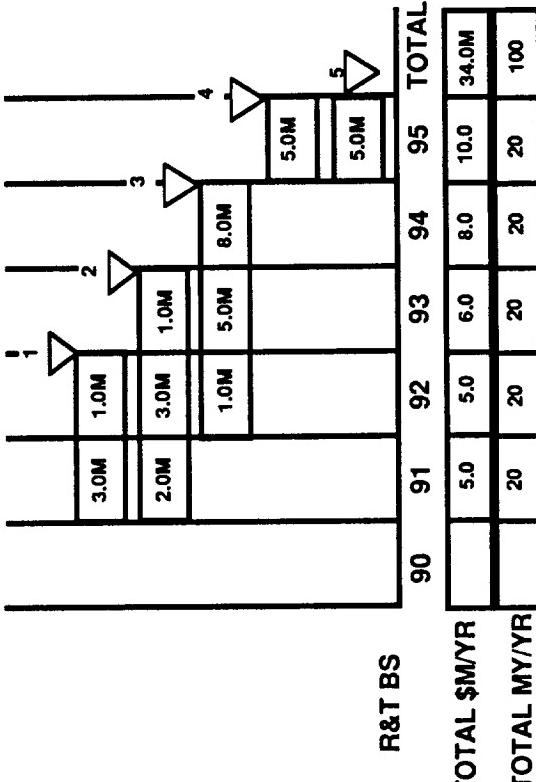
### 3.3 Information Transfer

Technology	NASA GCTI WBS	Proposal funding requirements, millions of dollars					
		FY90	FY91	FY92	FY93	FY94	FY95
High performance semiconductor lasers	3.31-1	0.5	0.5	0.5	0.8	0.8	0.8
Optical crosslink communications	3.31-2		5.0	5.0	6.0	8.0	10.0
Optical backplane interconnect			0.5	0.5	0.5	0.5	0.5
High speed fiber optic transceiver	3.32-1	0.5	0.3	0.4	0.5	1.0	
Totals		— 1.0	— 6.3	— 6.4	— 7.8	— 10.3	— 11.3

## HIGH-PERFORMANCE SEMICONDUCTOR LASERS

		<u>SCOPE</u>		<u>OBJECTIVE</u>		<u>APPROACH</u>		<u>DELIVERABLES</u>		<u>TECHNOLOGY ASSESSMENT</u>		<u>DEVELOPMENT PLAN</u>						
		DEVELOP AND DEMONSTRATE HIGH-POWER AND HIGH-DATA-RATE SEMICONDUCTOR (SC) LASER FOR OPTICAL COMMUNICATION.		DEMONSTRATE HIGH-POWER SC LASER. • DEMONSTRATE HIGH-DATA-RATE LASER. • DEMONSTRATE STABLE AND LONG LIFE SPACE QUALIFIED SC LASER.		UTILIZE AlGaAs QUANTUM WELL (QW) DESIGN WITH GRATING; FABRICATE AND TEST DESIGN; ITERATE LASER DESIGN FOR LONG LIFE, STABLE, AND SPACE-QUALIFIED SC LASER.		INITIAL QW AND DFB LASER DESIGN. • INITIAL LASER DEMONSTRATION. • HIGH-SPEED/POWER SC LASER. • STABLE AND LONG LIFE LASER. • SPACE-QUALIFIED LASER.		MISSION NEEDS WINDOW	Present Program	R&T BS	TOTAL \$M/YR	TOTAL MY/YR	TOTAL			
		<u>RATIONALE</u>		HIGH-PERFORMANCE SC LASER WILL ENABLE HIGH-DATA-RATE OPTICAL COMMUNICATION SYSTEM.						READINESS LEVEL	LAUNCH	90	91	92	93	94	95	TOTAL
										7	2010							
										6	1995	2000	2.0	2.0	2.0	2.0	2.0	10.0
										5								
										4								
										3								
										2								
										1								

**HIGH-PERFORMANCE OPTICAL CROSSLINK COMMUNICATIONS**

<b>SCOPE</b> DEVELOP AND DEMONSTRATE HIGH-PERFORMANCE OPTICAL CROSSLINK FOR HIGH-CAPACITY SENSOR DATA TRANSFER.	<b>APPROACH</b> DEMONSTRATE OPTICAL AND ELECTRONIC SYSTEM COMPONENTS, VALIDATE TRACKING SYSTEM, DEMONSTRATE OPTICAL LINK CAPABILITY, AND SPACE QUALIFY OPTICAL CROSSLINK SYSTEM.	<b>DELIVERABLES</b> <ul style="list-style-type: none"> <li>DEMONSTRATION OF SYSTEM COMPONENTS.</li> <li>VALIDATION OF SYSTEM DESIGN.</li> <li>OPERATIONAL DEMONSTRATION OF LINK.</li> <li>SPACE QUALIFICATION OF SYSTEM.</li> <li>DELIVERY OF CROSSLINK SYSTEM.</li> </ul>																																
<b>OBJECTIVE</b> <ul style="list-style-type: none"> <li>Demonstrate high-data-rate optical communication links.</li> <li>Demonstrate tracking, pointing, and acquisition system.</li> <li>Space qualification of optical communication system.</li> </ul>	<b>RATIONALE</b> OPTICAL COMMUNICATION LINK WILL ENABLE HIGH-DATA-RATE TRANSFER OF SENSOR INFORMATION.																																	
<b>TECHNOLOGY ASSESSMENT</b> 	<b>DEVELOPMENT PLAN</b> 	<table border="1"> <thead> <tr> <th></th> <th>90</th> <th>91</th> <th>92</th> <th>93</th> <th>94</th> <th>95</th> <th>TOTAL</th> </tr> </thead> <tbody> <tr> <td>R&amp;T BS</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>TOTAL \$M/YR</td> <td>5.0</td> <td>5.0</td> <td>6.0</td> <td>8.0</td> <td>10.0</td> <td>34.0M</td> <td></td> </tr> <tr> <td>TOTAL MY/YR</td> <td>20</td> <td>20</td> <td>20</td> <td>20</td> <td>20</td> <td>100</td> <td></td> </tr> </tbody> </table>		90	91	92	93	94	95	TOTAL	R&T BS								TOTAL \$M/YR	5.0	5.0	6.0	8.0	10.0	34.0M		TOTAL MY/YR	20	20	20	20	20	100	
	90	91	92	93	94	95	TOTAL																											
R&T BS																																		
TOTAL \$M/YR	5.0	5.0	6.0	8.0	10.0	34.0M																												
TOTAL MY/YR	20	20	20	20	20	100																												

## OPTICAL BACKPLANE INTERCONNECT SWITCH (OBIS)

<p><b>SCOPE</b> DEVELOP HIGH-PERFORMANCE OBIS FOR DATA PROCESSOR AND COMPUTER COMMUNICATIONS.</p> <p><b>OBJECTIVE</b></p> <ul style="list-style-type: none"> <li>• VALIDATE OBIS INTEGRATED OPTICS DESIGN.</li> <li>• DEMONSTRATE INITIAL 4 x 4 OBIS.</li> <li>• DEMONSTRATE 32 x 32 OBIS.</li> </ul> <p><b>RATIONALE</b></p> <p>OPTICAL SWITCHING REDUCES DIGITAL DELAYS AND BOTTLENECKS IN DATA SYSTEM.</p>	<p><b>APPROACH</b> BUILD UPON DEMONSTRATED OPTICAL SWITCHING, FABRICATE INTEGRATED OPTICS DESIGN, DEMONSTRATE DESIGN PERFORMANCE, AND EXTEND DESIGN TO LARGER OBIS ARRAYS.</p> <p><b>DELIVERABLES</b></p> <ul style="list-style-type: none"> <li>• VALIDATE OBIS DESIGN.</li> <li>• DEMONSTRATE INITIAL OBIS PERFORMANCE.</li> <li>• DEMONSTRATE 4 x 4 OBIS.</li> </ul>	<p><b>DEVELOPMENT PLAN</b></p> <table border="1" style="margin-top: 10px; border-collapse: collapse; width: 100%;"> <thead> <tr> <th></th> <th>90</th> <th>91</th> <th>92</th> <th>93</th> <th>94</th> <th>95</th> <th>TOTAL</th> </tr> </thead> <tbody> <tr> <td>R&amp;T BS</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>TOTAL \$M/YR</td> <td></td> <td>0.5</td> <td>0.5</td> <td>0.5</td> <td>0.5</td> <td>0.5</td> <td>2.5M</td> </tr> <tr> <td>TOTAL MY/YR</td> <td></td> <td>0.5</td> <td>0.5</td> <td>0.5</td> <td>0.5</td> <td>0.5</td> <td>2.5</td> </tr> </tbody> </table>		90	91	92	93	94	95	TOTAL	R&T BS								TOTAL \$M/YR		0.5	0.5	0.5	0.5	0.5	2.5M	TOTAL MY/YR		0.5	0.5	0.5	0.5	0.5	2.5	<p><b>TECHNOLOGY ASSESSMENT</b></p> <p>MISSION NEEDS WINDOW</p> <p>Present Program</p> <p>LAUNCH</p> <p>READYNESS LEVEL</p> <p>1989 1995 2000 2005 2010</p>
	90	91	92	93	94	95	TOTAL																												
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TOTAL \$M/YR		0.5	0.5	0.5	0.5	0.5	2.5M																												
TOTAL MY/YR		0.5	0.5	0.5	0.5	0.5	2.5																												

# HIGH SPEED FIBER OPTIC TRANSCEIVER

H. HENDRICKS

<p><b>SCOPE</b></p> <p>DEVELOP, DEMONSTRATE, AND SPACE QUALIFY HIGH SPEED FIBER OPTICS (FO) TRANSCEIVER.</p> <p><b>OBJECTIVE</b></p> <ul style="list-style-type: none"> <li>• DESIGN AND FABRICATE INTEGRATED CIRCUIT FIBER OPTIC TRANSCEIVER.</li> <li>• DEMONSTRATE 0.05 - 4 GBITS/SEC FO TRANSCEIVER (TX/RX)</li> <li>• SPACE QUALIFY TRANSCEIVER.</li> </ul> <p><b>RATIONALE</b></p> <p>SPACE DATA SYSTEMS NEED NONEXISTENT HIGH-SPEED AND SPACE-QUALIFIED FO TX/RX.</p>	<p><b>APPROACH</b></p> <p>JOINT AF/NASA PROGRAM. PERFORM CAD DESIGN AND VALIDATE, FABRICATE DESIGN, AND MIL/SPACE QUALIFY FIBER-OPTIC TRANSCEIVER FOR LEO AND GEO ENVIRONMENT.</p> <p><b>DELIVERABLES</b></p> <ul style="list-style-type: none"> <li>• VALIDATED CAD TRANSCEIVER DESIGN.</li> <li>• ENGINEERING DESIGN MODEL TRANSCEIVER.</li> <li>• 0.05 - 4 GBITS/SEC TRANSCEIVER.</li> <li>• SPACE-QUALIFIED FO TRANSCEIVER.</li> <li>• FINAL DESIGN SPECIFICATIONS AND REPORT.</li> </ul>																																								
	<p><b>TECHNOLOGY ASSESSMENT</b></p> <p>READINESS LEVEL</p> <p>MISSION NEEDS WINDOW</p> <p>LAUNCH</p> <p>1989 1995 2000 2005 2010</p> <table border="1"> <thead> <tr> <th>YEAR</th> <th>R&amp;T BS</th> <th>TOTAL \$M/YR</th> <th>TOTAL MY/YR</th> <th>TOTAL</th> </tr> </thead> <tbody> <tr> <td>90</td> <td>0.2M</td> <td>0.5</td> <td>1.0</td> <td>2.7M</td> </tr> <tr> <td>91</td> <td>0.3M</td> <td>0.3</td> <td>1.0</td> <td>4.0</td> </tr> <tr> <td>92</td> <td>0.3M</td> <td>0.4</td> <td>1.0</td> <td></td> </tr> <tr> <td>93</td> <td>0.4M</td> <td>0.5</td> <td>1.0</td> <td></td> </tr> <tr> <td>94</td> <td>0.5M</td> <td>0.9M</td> <td>1.0</td> <td></td> </tr> <tr> <td>95</td> <td>0.9M</td> <td></td> <td>1.0</td> <td></td> </tr> <tr> <td>TOTAL</td> <td>0.1M</td> <td></td> <td></td> <td></td> </tr> </tbody> </table>	YEAR	R&T BS	TOTAL \$M/YR	TOTAL MY/YR	TOTAL	90	0.2M	0.5	1.0	2.7M	91	0.3M	0.3	1.0	4.0	92	0.3M	0.4	1.0		93	0.4M	0.5	1.0		94	0.5M	0.9M	1.0		95	0.9M		1.0		TOTAL	0.1M			
YEAR	R&T BS	TOTAL \$M/YR	TOTAL MY/YR	TOTAL																																					
90	0.2M	0.5	1.0	2.7M																																					
91	0.3M	0.3	1.0	4.0																																					
92	0.3M	0.4	1.0																																						
93	0.4M	0.5	1.0																																						
94	0.5M	0.9M	1.0																																						
95	0.9M		1.0																																						
TOTAL	0.1M																																								

LaRC GCTI Information Technologies

**3.4 Ground Element**

Technology	NASA GCTI WBS	Proposal funding requirements, millions of dollars					
		FY90	FY91	FY92	FY93	FY94	FY95
Ground-based optical disk	3.41-6		0.5	1.0	1.5	1.5	2.0
Totals			0.5	1.0	1.5	1.5	2.0

## GROUND-BASED OPTICAL DISK MASS STORAGE SYSTEM

### SCOPE

DEVELOP A HIGH-PERFORMANCE REWRITABLE OPTICAL DISK MASS STORAGE SYSTEM TO SUPPORT ON-LINE MISSION OPERATIONS.

- REAL-TIME DATA RECORDING
- MULTIPLE USER NEAR REAL-TIME ACCESS TO SCIENCE & ENGINEERING DATA

### OBJECTIVES

- CAPACITY TO A TERABYTE
- RAPID FILE ACCESS (100 MILLISECONDS)
- 300 MEGABIT/SECOND INPUT/OUTPUT RATE

### RATIONALE

- SUPPORT EOS TERABIT/DAY AT 300 MBITS/SEC
- RAPID DATA ACCESS FOR SCIENTIFIC AND ENGINEERING ANALYSIS
- BROAD SUPERCOMPUTER APPLICATION

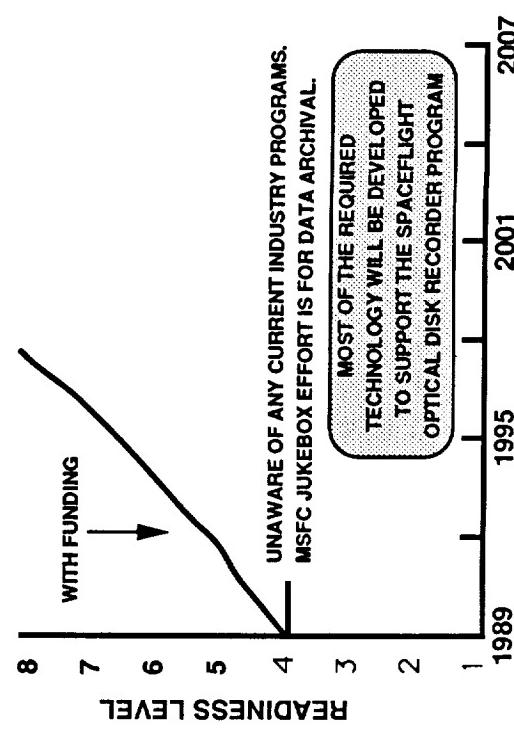
### APPROACH

- LEVERAGE TECHNOLOGY FROM EXISTING NASA AND DOD OPTICAL DISK PROGRAMS
- SEEK INDUSTRY PARTICIPATION/LEVERAGING IN SUPPORT OF FUTURE COMMERCIAL APPLICATIONS/MARKET-SHARE
- COMBINED NASA, DOD, AND INDUSTRY CONCEPT & REQUIREMENTS TO SUPPORT MULTIPLE APPLICATIONS

### DELIVERABLES

1. SYSTEM CONCEPTUAL DESIGN
2. PROTOTYPE/DEMONSTRATION SYSTEM
3. TEST BED SYSTEM DEMONSTRATION
4. OPERATIONAL SYSTEM

### TECHNOLOGY ASSESSMENT



### DEVELOPMENT PLAN

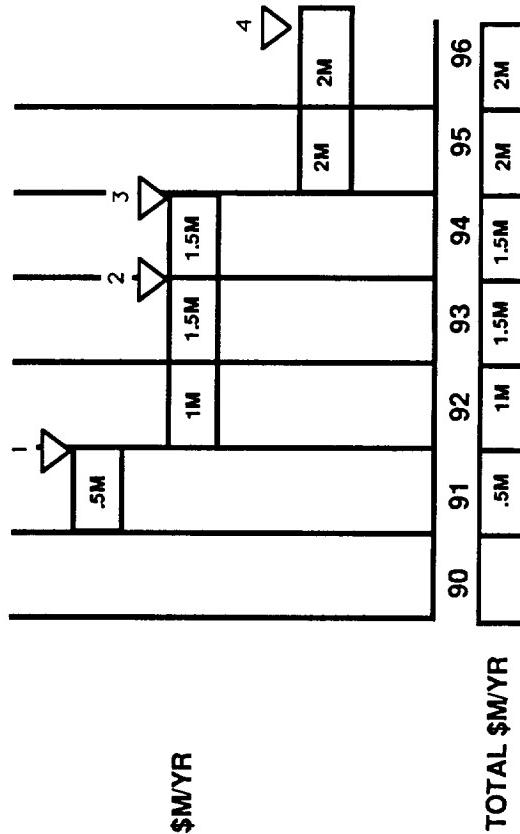


Table I. Global Change Science Measurement Requirements

Measurement	Location	Temporal resolution	Spatial resolution	Accuracy required	Comments	Measurement method (a)	Source (b)
Solar irradiance	Sun disk	1 day <sup>c</sup> (1 sec)		0.10%	Total	Radiometer	1, 4
UV	Sun disk	7 day <sup>c</sup> (1 min)		0.10%	Ongoing	UV spectroscopy	1, 4
Index of volcanic emissions (see aerosols, gases, atmospheric temperature, ocean surface temperature)	Site specific				Irregular observation, in situ measurements		1
CO <sub>2</sub>	Troposphere	1-3 hr	10 × 10 × 1 km 100 × 100 × 1 km	1%	In situ	Lidar IR spectrometry	1
N <sub>2</sub> O	Troposphere	1-3 hr	100 × 100 × 1 km	1%		IR: interferometry, emission, occultation	1
CH <sub>4</sub>	Troposphere	1-3 hr	100 × 100 × 1 km	1%		IR: interferometry, emission, occultation	1, 4
CFM's	Troposphere	1-3 hr	100 × 100 × 1 km	1%		IR: interferometry, IR spectrometry (2–20 $\mu$ m), lidar	1
Troposphere O <sub>3</sub>	Troposphere	1-3 hr	10 × 10 × 1 km 1-3 hr	1%		Lidar IR: interferometry, emission, occultation	1, 4
Troposphere CO	Troposphere	1-3 hr	10 × 10 × 1 km	1%		IR: spectrometry, emission	1, 4
Troposphere COS	Troposphere	2 week	200 × 200 × 3 km	1%		IR: spectrometry, lidar	2, 3
Troposphere H <sub>2</sub> O	Troposphere	<sup>c</sup> 1-12 hr	100 × 100 × 1 km	1%		IR: spectrometry	2, 3, 4
Troposphere H <sub>2</sub> O <sub>2</sub>	Troposphere	<sup>c</sup> 1-12 hr	10 × 10 × 1 km	1%		Lidar	
		1-3 hr	10 × 10 × 1 km	1%		IR: spectrometry, lidar	2, 3

Footnotes are at end of table, page 116.

Table I. Continued

Measurement	Location	Temporal resolution	Spatial resolution	Accuracy required	Comments	Measurement method (a)	Source (b)
Troposphere NO	Troposphere	1–3 hr	10 × 10 × 1 km	1%		IR: spectrometry, lidar	2, 3
Troposphere NO <sub>2</sub>	Troposphere	1–3 hr	10 × 10 × 1 km	1%		IR: spectrometry, lidar	2, 3
Troposphere HNO <sub>3</sub>	Troposphere	1–3 hr	10 × 10 × 1 km	1%		IR: spectrometry, lidar	2, 3
Troposphere NH <sub>3</sub>	Troposphere	1–3 hr	10 × 10 × 1 km	1%		IR: spectrometry, lidar	2, 3
Troposphere C <sub>2</sub> H <sub>6</sub>	Troposphere	1–3 hr	10 × 10 × 1 km	1%		IR: spectrometry, lidar	2
Troposphere C <sub>2</sub> H <sub>2</sub>	Troposphere	1–3 hr	10 × 10 × 1 km	1%		IR: spectrometry, lidar	2
Troposphere SO <sub>2</sub>	Troposphere	1–3 hr	10 × 10 × 1 km	1%		IR: spectrometry, lidar	2, 3
Troposphere OH	Troposphere	1–3 hr	10 × 10 × 1 km	1%	Low concentration, difficult, need technology development	Lidar, UV	2, 3
Stratosphere O <sub>3</sub>	Stratosphere	c 1–12 hr	10 × 10 × 1 km	1%	Day and night	UV, sondes, microwave, lidar IR: emission, interferometry, occultation	1, 4
Stratosphere H <sub>2</sub> O	Stratosphere	3–12 hr	500 × 500 × 3.5 km	5%		IR: emission, interferometry, occultation Microwave, submillimeter	1
Stratosphere NO <sub>2</sub>	Stratosphere	3–12 hr	500 × 500 × 3.5 km	5%		Occultation, visible spectrometry, submillimeter IR: emission, interferometry	1
Stratosphere HNO <sub>3</sub>	Stratosphere	3–12 hr	500 × 500 × 3.5 km	5%	Various methods	IR: limb scan Submillimeter	1
Stratosphere HCl	Stratosphere	3–12 hr	500 × 500 × 3.5 km	5%		IR: interferometry, emission, occultation Microwave, submillimeter	1

Footnotes are at end of table, page 116.

Table I. Continued

Measurement	Location	Temporal resolution	Spatial resolution	Accuracy required	Comments	Measurement method (a)	Source (b)
Stratosphere aerosols	Stratosphere	c-12 hr	200 × 500 × 1 km	25%		Occultation, lidar	1, 4
Stratosphere O	Stratosphere	3-12 hr	500 × 500 × 3.5 km	5%	FIR bands, valuable for stratospheric species, day and night	Submillimeter	2
Stratosphere O <sub>2</sub>	Stratosphere	3-12 hr	500 × 500 × 3.5 km	5%		Visible/IR/FIR spectrometry Lidar, microwave	3
Stratosphere CO	Stratosphere	3-12 hr	500 × 500 × 3.5 km	5%		IR spectrometry, microwave	2, 3
Stratosphere HOCl	Stratosphere	3-12 hr	500 × 500 × 3.5 km	5%		IR spectrometry, microwave, submillimeter	2, 3
Stratosphere OCIO	Stratosphere	3-12 hr	500 × 500 × 3.5 km	5%		IR spectrometry, submillimeter	2, 3
Stratosphere OH	Stratosphere	3-12 hr	500 × 500 × 3.5 km	5%	Difficult	FIR spectrometry, microwave, submillimeter	2, 3
Stratosphere HO <sub>2</sub>	Stratosphere	3-12 hr	500 × 500 × 3.5 km	5%		IR spectrometry, microwave, submillimeter	2, 3
Stratosphere H <sub>2</sub> O <sub>2</sub>	Stratosphere	3-12 hr	500 × 500 × 3.5 km	5%		IR spectrometry, microwave, submillimeter	2, 3
Stratosphere NO	Stratosphere	3-12 hr	500 × 500 × 3.5 km	5%		IR spectrometry, submillimeter	2, 3
Stratosphere N <sub>2</sub> O	Stratosphere	3-12 hr	500 × 500 × 3.5 km	5%		IR spectrometry, microwave, submillimeter	2, 3
Stratosphere N <sub>2</sub> O <sub>5</sub>	Stratosphere	3-12 hr	500 × 500 × 3.5 km	5%		Visible/IR/FIR spectrometry, lidar, microwave	3
Stratosphere ClO	Stratosphere	3-12 hr	500 × 500 × 3.5 km	5%		IR spectrometry, microwave, submillimeter	2, 3

Footnotes are at end of table, page 116.

Table I. Continued

Measurement	Location	Temporal resolution	Spatial resolution	Accuracy required	Comments	Measurement method (a)	Source (b)
Stratosphere ClONO <sub>2</sub>	Stratosphere	3–12 hr	500 × 500 × 3.5 km	5%		IR spectrometry	2, 3
Stratosphere BrO	Stratosphere	3–12 hr	500 × 500 × 3.5 km	5%		IR spectrometry, submillimeter	2, 3
Stratosphere HBr	Stratosphere	3–12 hr	500 × 500 × 3.5 km	5%		IR/FIR spectrometry	3
Stratosphere CH <sub>4</sub>	Stratosphere	3–12 hr	500 × 500 × 3.5 km	5%		IR: interferometry, emission, occultation	1
Stratosphere CFM's	Stratosphere	3–12 hr	500 × 500 × 3.5 km	5%	Lidar	IR: interferometry, spectrometry (2–20 $\mu$ m)	1
Troposphere temperature	Troposphere	c15 min–3 hr	100 × 100 × 5 km	0.5 K		Sondes, IR, microwave	1, 4
Stratosphere temperature	Stratosphere	1–3 hr	500 × 500 × 3.5 km	1 K		Sondes, IR, microwave, IR limb scan	1
Surface pressure	Earth surface	c0.5–3 hr	100 × 100 km	1 mbar	In situ	Microwave	1, 4
Tropical winds	Troposphere	c0.5–3 hr	100 × 100 km	2 m/sec		Sondes, motion detection, submillimeter	1, 4
		c0.5–3 hr	100 × 100 × 3.5 km	0.5 m/sec		Lidar	
		c0.5–3 hr	10 × 10 km	2 m/sec		Lidar	
Extratropical winds	Troposphere	c0.5–3 hr	100 × 100 km	2 m/sec		Sondes, submillimeter	1, 4
		c0.5–3 hr	100 × 100 × 3.5 km	0.5 m/sec		Lidar	
		c0.5–3 hr	10 × 10 km	2 m/sec		Lidar	
Tropospheric water vapor	Troposphere	1–3 hr	100 × 100 km × 100 mbar	0.001 ppm		Sondes, microwave (22 and 183 GHz), IR, lidar	1, 4
Precipitation	Earth surface	c0.5–3 hr	1 km	5%	In situ	IR, microwave, radar (37 GHz)	1, 4

Footnotes are at end of table, page 116.

Table I. Continued

Measurement	Location	Temporal resolution	Spatial resolution	Accuracy required	Comments	Measurement method (a)	Source (b)
Earth radiation budget: long (1–15 $\mu\text{m}$ ) short (0.3–1 $\mu\text{m}$ )	Earth disk	c1–3 hr	10–30 km	2%			1, 4
Clouds: extent, type, height emission temperature albedo	Earth disk	c1–3 hr 6 hr 6 hr 6 hr c1–3 hr	1 $\times$ 1 km 1 $\times$ 1 km 50 $\times$ 50 km 50 $\times$ 50 km 1 $\times$ 1 km	2% 0.5°C 0.01 .05 kgm/m <sup>2</sup>	In situ	IR Visible	IR: spectrometry, emission, submillimeter
H <sub>2</sub> O content pH of rain and clouds							1, 4
Cloud motion	Troposphere	3–5 min	0.5 km			Visible	2, 3, 4
Lightning	Troposphere	3–5 min	0.5 km			0.774 nm	4
Convective stability	Troposphere	15 min	40 km			Microwave	4, 5
Convective storms	Troposphere	1–15 min	0.5 km			Visible, IR	4, 5
Hurricanes	Troposphere	15 min	1–30 km			Visible, mid IR, microwave	4, 5
Fog	Troposphere/ Surface	30 min	0.5 km			Visible, mid IR	4
Dust storms	Troposphere/ Surface	15–60 min	1–10 km			IR	4
Tropospheric aerosols	Troposphere	c1–12 hr	10 $\times$ 10 $\times$ 1 km	5%	In situ	Visible, IR spectrometry, lidar	1, 4
Surface radiating temperature: land inland waters ice	Surface Surface Surface	1–3 hr 1–3 hr 1–3 hr	1 km 30 m 1 km	0.5°C 0.1°C 0.5°C		Thermal IR, microwave radiometers Thermal IR, microwave radiometers IR	1

Footnotes are at end of table, page 116.

Table I. Continued

Measurement	Location	Temporal resolution	Spatial resolution	Accuracy required	Comments	Measurement method (a)	Source (b)
Incident solar flux	Surface	1 day	100 × 100 km		In situ possible	Visible	
Snow cover	Continent	1–7 days	30 m 10 km	5%	In situ possible	Visible and IR imaging spectrometers and radiometers, microwave radiometers, SAR ( $L_r$ , C-, X-, K-bands)	1
Snow water equivalent	Watersheds	0.5–7 days	30 m–1 km	5%	In situ possible	Microwave radiometer (6 91 GHz)	
Ice sheet volume	Continent	1–50 years	1 km to 100 × 100 km	1%		Laser altimeter, aircraft SAR	1
River runoff (volume)	100s km	1 day	1 km	10%	In situ possible	Visible and IR imaging spectrometers and radiometers, microwave radiometers	1
River flooding	Surface	60 min	0.1–0.5 km			Visible, mid-IR	
River runoff (sediment loading)	100s km	c.1–24 hr	0.2–1 km	10%	In situ possible	Visible and IR imaging spectrometers and radiometers, microwave radiometers	1, 4
River runoff (chemical constituents)	100s km	1 day	500 m	10%	In situ possible	Visible and IR imaging spectrometers and radiometers, microwave radiometers	1
Surface characteristics: surface roughness albedo	100s km to continent	1 year 1 day	30 m–1 km 100 × 100 km	10% 1%	In situ possible	Visible, IR, microwave, radar SAR ( $P_r$ , $L_r$ , C-, X-bands) UV to 50 $\mu$ m	1

Footnotes are at end of table, page 116.

Table I. Continued

Measurement	Location	Temporal resolution	Spatial resolution	Accuracy required	Comments	Measurement method (a)	Source (b)
Index of land use changes	kms to continent	1 day	30 m–1 km	1%	In situ possible, high resolution	Visible and IR imaging spectrometers, SAR	1, 4
Index of vegetation cover (identification and extent)	kms to continent	3–30 days	30 m–1 km	1%	In situ resolution	Visible and IR imaging spectrometers (0.4–2.45 $\mu$ m), SAR (P-, L-, C-, X-bands)	1, 4
Index of surface wetness (wetlands/irrigation)	kms to continent	2 days	1–10 km	5%	In situ possible	Microwave radiometers (1.4 and 6 GHz), SAR (P-, L-, C-bands)	1, 4
Vegetation stress	kms to continent	1 day	5 km	10%		Imaging spectrometer	2, 3
Soil moisture	kms to continent	12 hrs–3 days	30 m–10 km	5%	In situ	Microwave radiometers	1
Soil type/illumination	Earth surface	30 min	0.1–0.3 km			Visible	4
Biome extent, productivity, and nutrient cycling	kms to continent	3–7 days	30 m–1 km	10%	In situ possible	Visible and IR imaging spectrometers (0.4–2.45 $\mu$ m), SAR (L-, C-, X-bands)	1
Biomass burning	Troposphere/Surface		0.5 km			Visible	2, 4
Evapotranspiration	Surface	1 day	1 km	5%		IR, visible	2, 4
Land surface elevation	Continent	10 years	300 × 300 m	1 m		Laser altimeter, radar altimeter	1
Sea surface temperature	Ocean basins	6 hours	1–4 km	0.1°C	In situ possible	Visible and IR imaging spectrometers and radiometers, microwave radiometers	1
Sea ice extent	Polar oceans	1 week	5–20 km	10 km		Microwave radiometers (18–91 GHz), SAR (L-, C-, X-bands)	1
Sea ice type	Polar oceans	2 weeks	1 km	1%	In situ possible	Microwave radiometers (18–91 GHz), SAR (P-, L-, C-, X-, Ku-bands)	1

Footnotes are at end of table, page 116.

Table I. Continued

Measurement	Location	Temporal resolution	Spatial resolution	Accuracy required	Comments	Measurement method (a)	Source (b)
Sea ice motion	Polar oceans	1 day	100 m	10 m		Surface drifters, radar altimeter, SAR	1
Ocean wind stress	Ocean basins	1 day	50 × 50 km	0.5 m/s	In situ possible	Microwave: scatterometer, altimeter, SAR	1
Ocean wave height	Ocean basins	3 days	50 km	10%		Altimetry	1
Ocean wave spectrum	Ocean basins	3 days	50 km	±10°		SAR	1
Sea level (coastal flooding and shoreline changes)	Ocean basins Shoreline Shoreline	2 days 60 min hrs-weeks	10 km 0.1 km 50–100 m	1 cm	Tide gage	Altimetry Visible, mid IR Visible	1 4 4
Incident solar flux	Global	1 day	100 × 100 km			Visible	1
Subsurface circulation	kms to ocean basins	hrs-days	30 m–100 km	2–20 cm/s	In situ possible	Buoys, altimetry	1
Ocean chlorophyll	kms to ocean basins	2 days	30 m–4 km	10%	In situ possible, 5–10 nm spectral resolution up to 0.7 μm	Imaging spectrometers: (0.435–0.565 μm)	1
Phytoplankton spectra	kms to ocean basins	2 days	30 m–4 km	10%		Visible, IR	2
Biogeochemical fluxes	Global	2 days	30 m–4 km	10%	In situ possible	Visible and IR spectrometers, SAR	1
Ecosystem stress	Global	hrs-days	30–100 m			Visible, IR	4
Ocean CO <sub>2</sub>	Ocean basins	2 days	500 m		In situ possible	IR (3 μm)	1
Ocean productivity	Ocean basins	15–60 min	0.2–1 km			400–900 nm	4
Geoid	Global	10 years	1 km	1 cm		Altimetry, tracking systems	1

Footnotes are at end of table, page 116.

Table I. Concluded

Measurement	Location	Temporal resolution	Spatial resolution	Accuracy required	Comments	Measurement method (a)	Source (b)
Plate motions	Global	2 months	1–10000 km	0.5 cm		Very long baseline interferometry, laser ranging	1
Plate deformations	kms to continent	2 months	1–10000 km	0.5 cm	In situ possible	Laser ranging and altimetry, GPS, seismic networks linked to spacecraft, visible and SAR imagery	1
Polar motion and Earth rotation	Global	2 months	10–10000 km			Very long baseline interferometry, lunar ranging	1
Time-dependent magnetic field	Global	years	30 × 30 km	0.5 nT	In situ possible	Magnetometer	1
Changes in gravity	Global	years	30 × 30 km	0.5 mgal		Satellite tracking	1

<sup>a</sup> Abbreviations:

- FIR far infrared
- GPS global positioning satellite
- IR infrared
- SAR synthetic aperture radar
- UV ultraviolet

<sup>b</sup> Source of the global change science measurement requirements:

1. The Bretherton Report
2. Additions from the JPL in-house survey
3. Additions from the LARC in-house survey
4. GPESSC
5. Additions from the GSFC in-house survey

<sup>c</sup> Additional temporal resolution requirements of the Geostationary Platform Earth Sciences Steering Committee (GPESSC)

Table II. Measurement History for the Science Requirements

Measurement	Location	Operational spacecraft	Name	In situ	Planned spacecraft	Name	No measurement (a)	Priority (b)
Solar irradiance	Sun disk	X	ERB					3
UV	Sun disk	X	SBUV					2
Index of volcanic emissions (see aerosols, gases, atmospheric temperature, ocean surface temperature)	Site specific	X	SAGE 2	X	X	SAGE 3		1
CO <sub>2</sub>	Troposphere			X	X	TRACER		
N <sub>2</sub> O	Troposphere						X	3
CH <sub>4</sub>	Troposphere						X	2
CFM's	Troposphere						X	2
Troposphere O <sub>3</sub>	Troposphere			X				2
Troposphere CO	Troposphere	X			X	MAPS		
Troposphere COS	Troposphere						X	2
Troposphere H <sub>2</sub> O	Troposphere			X	X		LASA	2
Troposphere H <sub>2</sub> O <sub>2</sub>	Troposphere						X	3
Troposphere NO	Troposphere						X	3
Troposphere NO <sub>2</sub>	Troposphere						X	3
Troposphere HNO <sub>3</sub>	Troposphere						X	3

Footnotes are at end of table, page 125.

Table II. Continued

Measurement	Location	Operational spacecraft	Name	In situ	Planned spacecraft	Name	No measurement (a)	Priority (b)
Troposphere NH <sub>3</sub>	Troposphere						X	3
Troposphere C <sub>2</sub> H <sub>6</sub>	Troposphere						X	3
Troposphere C <sub>2</sub> H <sub>2</sub>	Troposphere						X	3
Troposphere SO <sub>2</sub>	Troposphere	X	SBUV	X				3
Troposphere OH	Troposphere						X	3
Stratosphere O <sub>3</sub>	Stratosphere	X	SBUV/TOMS, LIMS, SAGE 2, SME	X	X	GOMR, MLS, ISAMS, CLAES, SAFIRE, HALOE, SAGE 3, LASA		3
Stratosphere H <sub>2</sub> O	Stratosphere	X	LIMS, SAGE 2	X		ISAMS, CLAES, SAFIRE, HALOE, SAGE 3		2
Stratosphere NO <sub>2</sub>	Stratosphere	X	SAGE 2 SME LIMS	X		SAGE 3, HALOE, ISAMS, CLAES, ATMOS, SAFIRE		1
Stratosphere HNO <sub>3</sub>	Stratosphere	X	LIMS	X		ISAMS, CLAES, SAFIRE		1
Stratosphere HCl	Stratosphere	X	ATMOS	X		ATMOS, HALOE, CLAES, SAFIRE		1
Stratosphere aerosols	Stratosphere	X	SAM 2, SAGE 2	X		SAGE 3, LITE		2
Stratosphere O	Stratosphere					X	SAFIRE	3

Footnotes are at end of table, page 125.

Table II. Continued

Measurement	Location	Operational spacecraft	Name	In situ	Planned spacecraft	Name	No measurement (a)	Priority (b)
Stratosphere O <sub>2</sub>	Stratosphere	X	MAPS, SAMS		X	TRACER, ISAMS	X	2
Stratosphere CO	Stratosphere	X			X	SAFIRE		2
Stratosphere HOCl	Stratosphere				X		X	3
Stratosphere OCIO	Stratosphere				X	SAFIRE		3
Stratosphere OH	Stratosphere				X	SAFIRE		3
Stratosphere HO <sub>2</sub>	Stratosphere				X	SAFIRE		3
Stratosphere H <sub>2</sub> O <sub>2</sub>	Stratosphere				X	SAFIRE, MLS		3
Stratosphere NO	Stratosphere				X	HALOE, ISAMS		3
Stratosphere N <sub>2</sub> O	Stratosphere	X	SAMS		X	HALOE, CLAES, ISAMS		3
Stratosphere N <sub>2</sub> O <sub>5</sub>	Stratosphere				X	SAFIRE, CLAES		3
Stratosphere ClO	Stratosphere				X	MLS		3
Stratosphere ClONO <sub>2</sub>	Stratosphere				X	CLAES		3
Stratosphere BrO	Stratosphere				X		X	3
Stratosphere HBr	Stratosphere				X	SAFIRE		3
Stratosphere CH <sub>4</sub>	Stratosphere	X	SAMS		X	ISAMS, CLAES, HALOE, SAFIRE		2
Stratosphere CFM's	Stratosphere				X	CLAES		2

Footnotes are at end of table, page 125.

Table II. Continued

Measurement	Location	Operational spacecraft	Name	In situ	Planned spacecraft	Name	No measurement (a)	Priority (b)
Troposphere temperature	Troposphere	X	GOES, TOVS	X	X	AMSU		3
Stratosphere temperature	Stratosphere	X	MSU, ATMOS, LIMS	X	X	AMSU, CLAES, ISAMS, GOMR, SAFIRE		2
Surface pressure	Earth surface						X	3
Tropical winds	Troposphere	X	GOES	X	X	LAWS		2
Extratropical winds	Troposphere			X	X	LAWS		1
Tropospheric water vapor	Troposphere	X	SSM, VAS	X	X	AMSU, LASA		2
Precipitation	Earth surface	X	GOES, SSM	X	X	AMSR, TRMM		3
Earth radiation budget: long (1–15 $\mu\text{m}$ ) short (0.3–1 $\mu\text{m}$ )	Earth disk	X	ERBE	X	X	CERES		2
Clouds:					X			
extent, type, height emission temperature albedo	Earth disk	X	GOES AVHRR GOES				X	2
H <sub>2</sub> O content pH of rain and clouds		X					X	2
Cloud motion	Troposphere	X	GOES					2
Lightning	Troposphere	X	LANDSAT					1

Footnotes are at end of table, page 125.

Table II. Continued

Measurement	Location	Operational spacecraft	Name	In situ	Planned spacecraft	Name	No measurement (a)	Priority (b)
Convective stability	Troposphere	X	GOES	X				1
Convective storms	Troposphere	X	GOES	X				1
Hurricanes	Troposphere	X	GOES	X				1
Fog	Troposphere/ Surface			X				1
Dust storms	Troposphere/ Surface	X	GOES	X				1
Tropospheric aerosols	Troposphere	X	AVHRR	X			MODIS, LASA	1
Surface radiating temperature:								
land	Surface	X	AVHRR, VAS					1
inland waters	Surface	X	AVHRR, VAS					1
ice	Surface	X	AVHRR					1
Incident solar flux	Surface	X	GOES					1
Snow cover	Continent	X	AVHRR, SSM				AMIRR, AMSR, SAR	1
Snow water equivalent	Watersheds	X	SSM				AMSR	1

Footnotes are at end of table, page 125.

Table II. Continued

Measurement	Location	Operational spacecraft	Name	In situ	Planned spacecraft	Name	No measurement (a)	Priority (b)
Ice sheet volume	Continent			X	X	GLRS		1
River runoff (volume)	100s km			X				1
River flooding	Surface			X				1
River runoff (sediment loading)	100s km			X				1
River runoff (chemical constituents)	100s km			X				1
Surface characteristics: surface roughness albedo	100s km to continent		AVHRR, SSM, SAR		X	MODIS, SAR		1
Index of land use changes	kms to continent	X	AVHRR, SPOT		X	SAR		2
Index of vegetation cover (identification and extent)	kms to continent	X	AVHRR		X	SAR		3
Index of surface wetness (wetlands/irrigation)	kms to continent	X	SSM		X	SAR		1
Vegetation stress	kms to continent							1
Soil moisture	kms to continent	X	AVHRR, GOES, SSM		X	SAR		3
Soil type/illumination	Earth surface	X	SPOT					1

Footnotes are at end of table, page 125.

Table II. Continued

Measurement	Location	Operational spacecraft	Name	In situ	Planned spacecraft	Name	No measurement (a)	Priority (b)
Biome extent, productivity, and nutrient cycling	kms to continent			X	X	SAR		3
Biomass burning	Troposphere/ Surface	X	SPOT					3
Evapotranspiration	Surface				X			3
Land surface elevation	Continent				X	GLRS		2
Sea surface temperature	Ocean basins	X	AVHRR, SSM		X	AMRIR		3
Sea ice extent	Polar oceans	X	SSM		X	SAR		2
Sea ice type	Polar oceans				X	AMSU, SAR		1
Sea ice motion	Polar oceans			X	X	SAR		1
Ocean wind stress	Ocean basins	X	SSM		X	SAR		3
Ocean wave height	Ocean basins				X	GLRS		3
Ocean wave spectrum	Ocean basins				X	SAR		3

Footnotes are at end of table, page 125.

Table II. Continued

Measurement	Location	Operational spacecraft	Name	In situ	Planned spacecraft	Name	No measurement (a)	Priority (b)
Sea level (coastal flooding and shoreline changes)	Ocean basins Shoreline Shoreline		X					2
Incident solar flux	Global	X	GOES					1
Subsurface circulation	kms to ocean basins		X					3
Ocean chlorophyll	kms to ocean basins	X	CZCS	X	X	MERIS	X	3
Phytoplankton spectra	kms to ocean basins		X					2
Biogeochemical fluxes	Global			X		SAR	X	2
Ecosystem stress	Global						X	1
Ocean CO <sub>2</sub>	Ocean basins						X	2
Ocean productivity	Ocean basins						X	2
Geoid	Global						GLRS	3
Plate motions	Global						GLRS	2
Plate deformations	kms to continent	X	SPOT	X	X	GLRS	X	3

Footnotes are at end of table. page 125.

Table II. Concluded

Measurement	Location	Operational spacecraft	Name	In situ	Planned spacecraft	Name	No measurement (a)	No measurement (b)	Priority (b)
Polar motion and Earth rotation	Global			X					1
Time-dependent magnetic field	Global				X	GREM			1
Changes in gravity	Global	X	LAGEOS						1

<sup>a</sup>X denotes no existing routine operational measurement<sup>b</sup>Priority of measurement:

- 3. Essential
- 2. Highly important
- 1. Substantially important

Table III. Technology Readiness Levels

Readiness Level	Definition
1	Basic principles observed and reported
2	Conceptual design formulated
3	Conceptual design tested analytically or experimentally
4	Critical functions/characteristics demonstrated
5	Component/breadboard tested in relevant environment
6	Prototype engineering model tested in relevant environment
7	Engineering model tested in space
8	Full operational capability (incorporated in production design)

Table IV. Work Breakdown Structure (WBS) Proposed for the Global Change Technology Initiative (GCTI)

1.0 Observation thrust

- 1.1 Coolers
- 1.2 Detectors
- 1.3 Submillimeter
- 1.4 Microwave sensing
- 1.5 Optics
- 1.6 Pointing and control
- 1.7 Lasers
- 1.8 Calibration

2.0 Spacecraft and operations thrust

- 2.1 Materials
- 2.2 Structures and control
- 2.3 Systems analysis
- 2.4 Power
- 2.5 Propulsion
- 2.6 Thermal control

3.0 Data and information systems thrust

- 3.1 Systems
- 3.2 Flight element
- 3.3 Information transfer
- 3.4 Ground element

Table V. Summary of LaRC Proposals Submitted to the GCTI

Thrust	No. of quad charts	Proposal funding requirements, millions of dollars					
		FY90	FY91	FY92	FY93	FY94	FY95
1.0 Observation:							
1.1 Coolers	1		0.10	0.10	0.10	0.20	0.20
1.2 Detectors	8	1.53	6.03	8.73	8.73	8.05	4.65
1.3 Submillimeter	0						
1.4 Microwave sensing	8	.90	8.60	12.55	11.70	9.55	5.75
1.5 Optics	9	.98	2.68	4.20	6.50	4.70	1.10
1.6 Pointing and control	3		.90	1.10	2.70	1.50	.70
1.7 Lasers	10	.10	5.95	8.50	11.60	13.20	8.50
1.8 Calibration	1		<u>1.50</u>	<u>1.10</u>	<u>.20</u>	<u>0</u>	<u>0</u>
Subtotal	40	3.51	25.76	36.28	41.53	37.20	20.90
2.0 Spacecraft and operations:							
2.1 Materials	5		4.25	7.90	10.60	11.70	11.15
2.2 Structures and control	2		8.00	10.00	15.50	21.00	15.00
2.3 Systems analysis	6	1.50	10.25	16.20	20.05	46.90	50.90
2.4 Power	1		.20	.25	.20	.25	.25
2.5 Propulsion	2		.35	.30	.35	.45	.20
2.6 Thermal control	2		<u>.35</u>	<u>.35</u>	<u>.50</u>	<u>.60</u>	<u>.40</u>
Subtotal	18	1.50	23.40	35.00	47.20	80.90	77.90
3.0 Data and information systems:							
3.1 Systems	6		3.95	6.55	8.15	5.70	3.50
3.2 Flight element	13	.40	27.30	33.80	45.90	40.50	23.10
3.3 Information transfer	4	1.00	6.30	6.40	7.80	10.30	11.30
3.4 Ground element	1		<u>.50</u>	<u>1.00</u>	<u>1.50</u>	<u>1.50</u>	<u>2.00</u>
Subtotal	24	1.40	38.05	47.75	63.35	58.00	39.90
Grand total	82	6.41	87.21	119.03	152.08	176.10	138.70

Table VI. Traceability of Technologies to Measurement Techniques and Science Requirements

	Technique										LaRC survey		
	Lidar	Gas correlation	UV radiometry	Visible	IR	Far IR	Sub mm	Microwave	Active cavity	In-situ	Horizontal resolution, km	Vertical resolution, km	Accuracy
	Observables												
Tropospheric constituents													
Trace gases	✓	✓			✓	✓	✓		✓		500	3.5	10%
Ozone	✓				✓	✓	✓		✓		200	2	10%
Aerosols	✓				✓	✓			✓		100	.2	20%
Clouds	✓				✓	✓		✓	✓		1	.1	5%
Middle atmospheric constituents													
Trace gases	✓	✓	✓		✓	✓	✓	✓	✓		500	3.5	5%
Ozone	✓				✓	✓	✓		✓		200	1	5%
Aerosols	✓				✓	✓			✓		200	1	20%
Atmospheric response variables													
Temperature	✓					✓	✓		✓		300	2	1 K
Pressure	✓					✓	✓		✓				
Wind*	✓					✓	✓		✓		✓	25	3
Precipitation											✓	1	2 m/s
Radiation components*						✓	✓		✓		✓	100	10% 1%
Solar irradiance*				✓						✓			
Surface characteristics													
Soil moisture						✓	✓		✓		✓	10	5%
Vegetation index*						✓	✓		✓		✓	1	1%
Biomass burning						✓	✓		✓			.5	
Volcanoes						✓	✓		✓			1	
Albedo						✓	✓		✓			100	1%
Ocean variables													
Temperature						✓	✓				✓	1-4	.1°C
Sea ice extent												5	10 m
Sea level												20	1 cm
CO <sub>2</sub> content												.5	
Plate motions	✓										1	1000	
Technology needs													
Observation													
Cryogenic cooler technology	✓	✓				✓	✓	✓	✓	✓	✓		
Detector technology	✓	✓				✓	✓	✓	✓	✓	✓		
Submillimeter technology			✓			✓	✓	✓	✓	✓	✓		
Microwave technology										✓	✓		
Optical systems technology	✓	✓		✓		✓	✓	✓	✓	✓	✓		
Pointing & control technology	✓	✓		✓		✓	✓	✓	✓	✓	✓		
Laser system technology	✓	✓		✓		✓	✓	✓	✓	✓	✓		
Calibration technology	✓	✓		✓		✓	✓	✓	✓	✓	✓		
Spacecraft/Operations													
Materials technology	✓	✓		✓		✓	✓	✓	✓	✓	✓		
Structures & control technology	✓	✓		✓		✓	✓	✓	✓	✓	✓		
Systems technology	✓	✓		✓		✓	✓	✓	✓	✓	✓		
Power technology	✓	✓		✓		✓	✓	✓	✓	✓	✓		
Propulsion technology	✓	✓		✓		✓	✓	✓	✓	✓	✓		
Thermal systems technology	✓	✓		✓		✓	✓	✓	✓	✓	✓		
Data/Information													
Systems technology	✓	✓		✓		✓	✓	✓	✓	✓	✓		
Flight processing technology	✓	✓		✓		✓	✓	✓	✓	✓	✓		
Information transfer technology	✓	✓		✓		✓	✓	✓	✓	✓	✓		
Ground processing technology	✓	✓		✓		✓	✓	✓	✓	✓	✓		

\* High temporal requirements.

Table VII. Three Phases Proposed in Implementing the GCTI Program

Phase I EOS technology:

- Cryogenic coolers
- Infrared arrays
- Active microwave
- Submillimeter
- Laser sensing
- Multiinstrument pointing
- Optical communications
- Data visualization
- Access and retrieval
- Information archives
- NDE/NDI
- EOS systems analysis

Phase 2 LEO/GEO technology:

- Microwave sensing
- Power systems
- Propulsion
- Chip level integration
- Optics
- Large array CCD
- Software engineering
- Space environment effects
- Deployable structures
- LEO/GEO system studies

Phase 3 Mission to Planet Earth:

To be determined



National Aeronautics and  
Space Administration

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